

Generative Networks for Fast Simulation

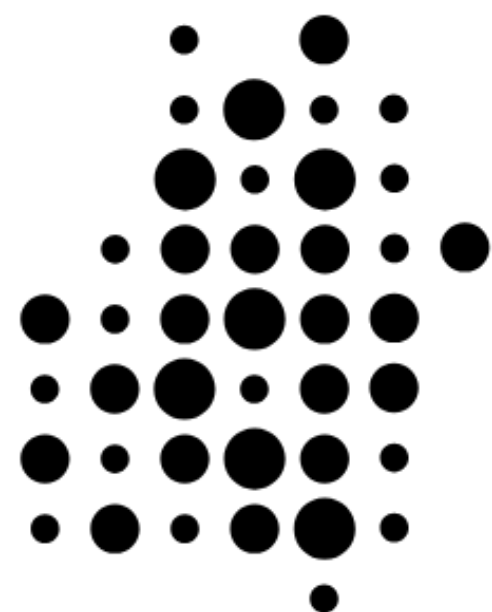
Statistics for Generative Networks

Sascha Cassandra Diefenbacher, Heidelberg University

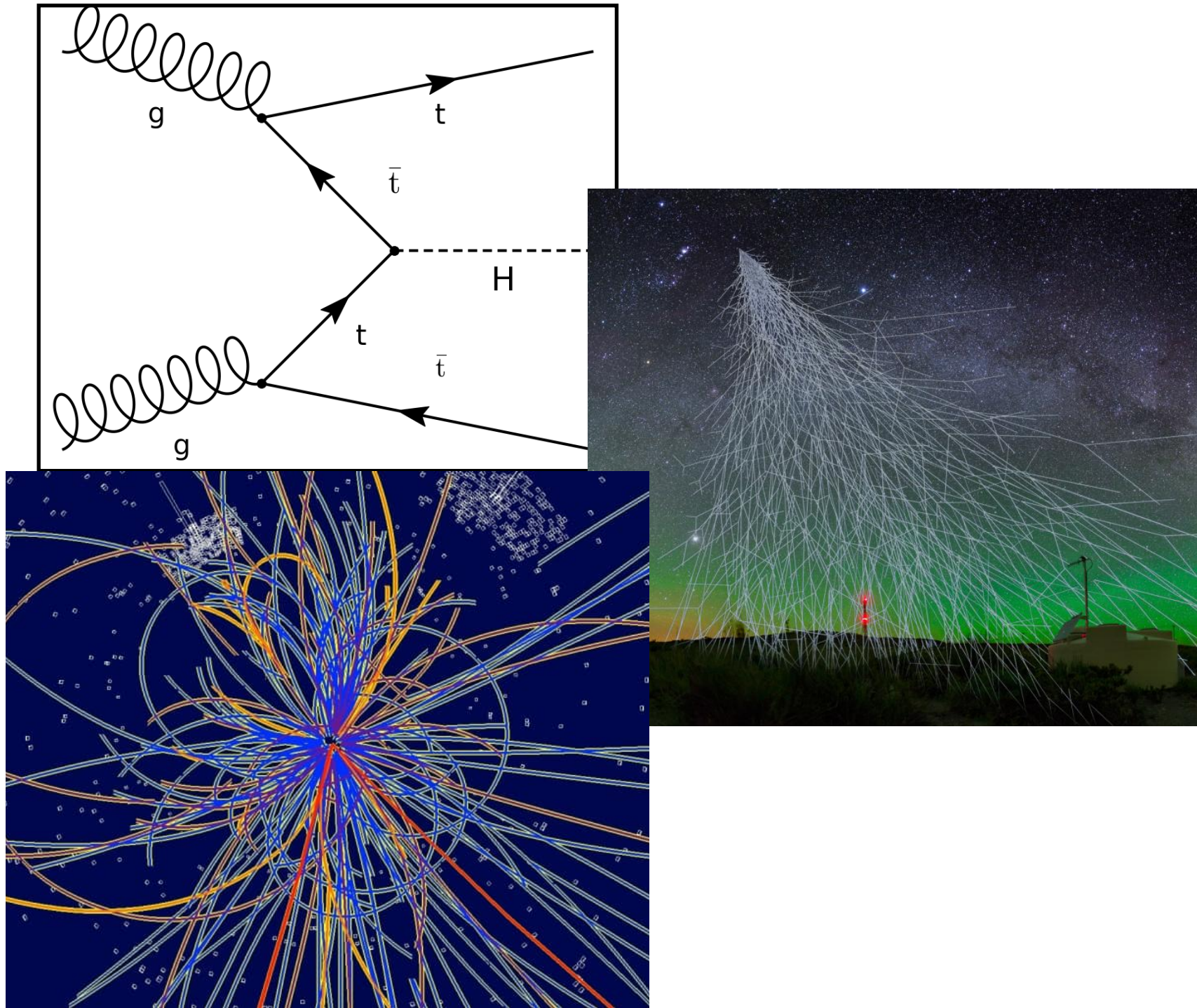
WMLQ 2026, Warsaw

September 7th, 2026

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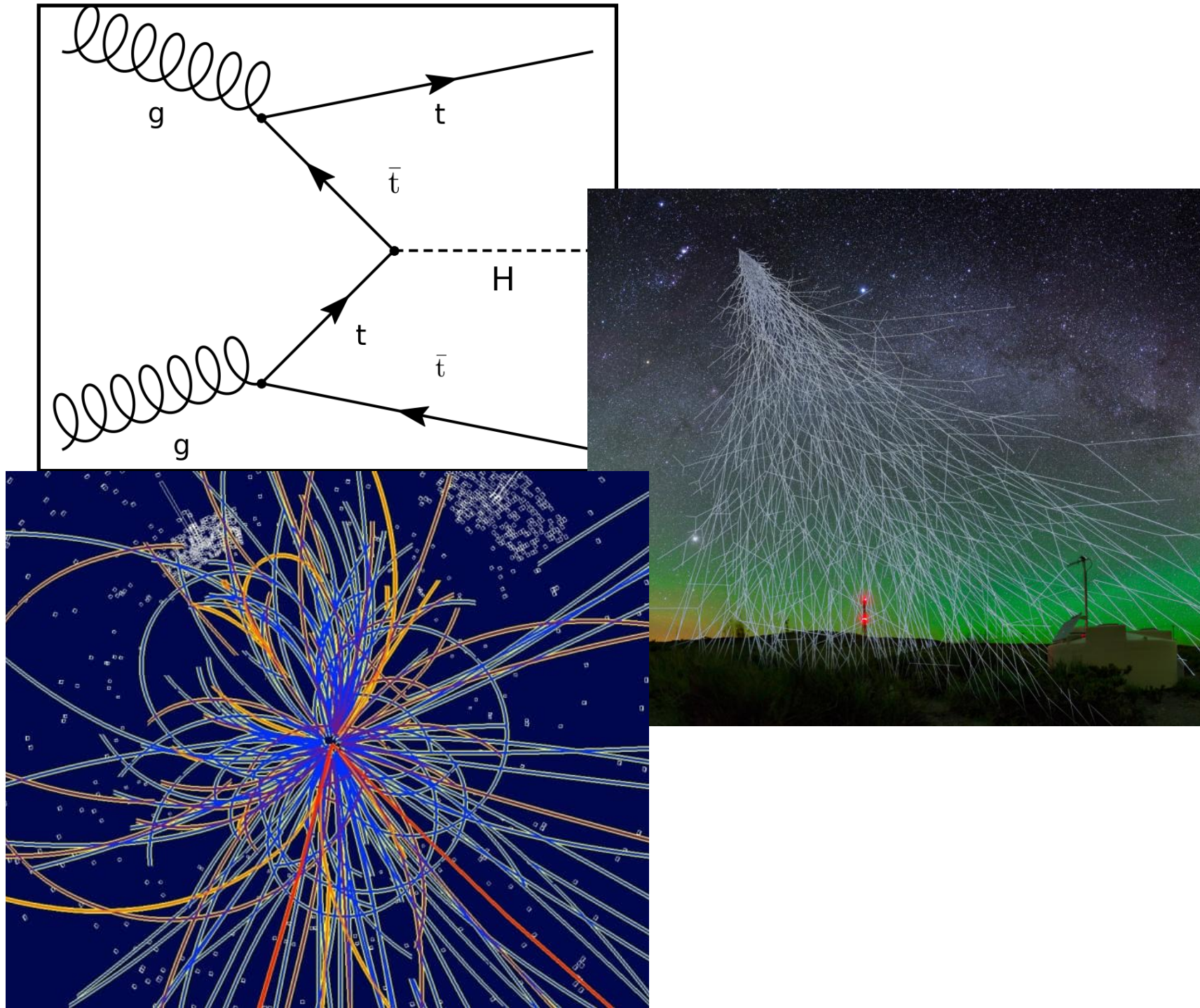
Challenge I: Complexity

- ▶ $t\bar{t}H$ events in terms of hadrons
 - ▶ Air showers from ground observation
 - ▶ Radio waves transformed to images
-
- ▶ Extremely high-dimensional
 - ▶ Highly correlated
 - ▶ Infer fundamental-theory parameters
e.g. $t\bar{t}H$: masses, couplings, CP phase...

- ▶ LHC & SKA: O(PB) per second
- ▶ Challenging to select
- ▶ Expensive to analyze
- ▶ Needs even more simulated data



Challenge II: Large Datasets

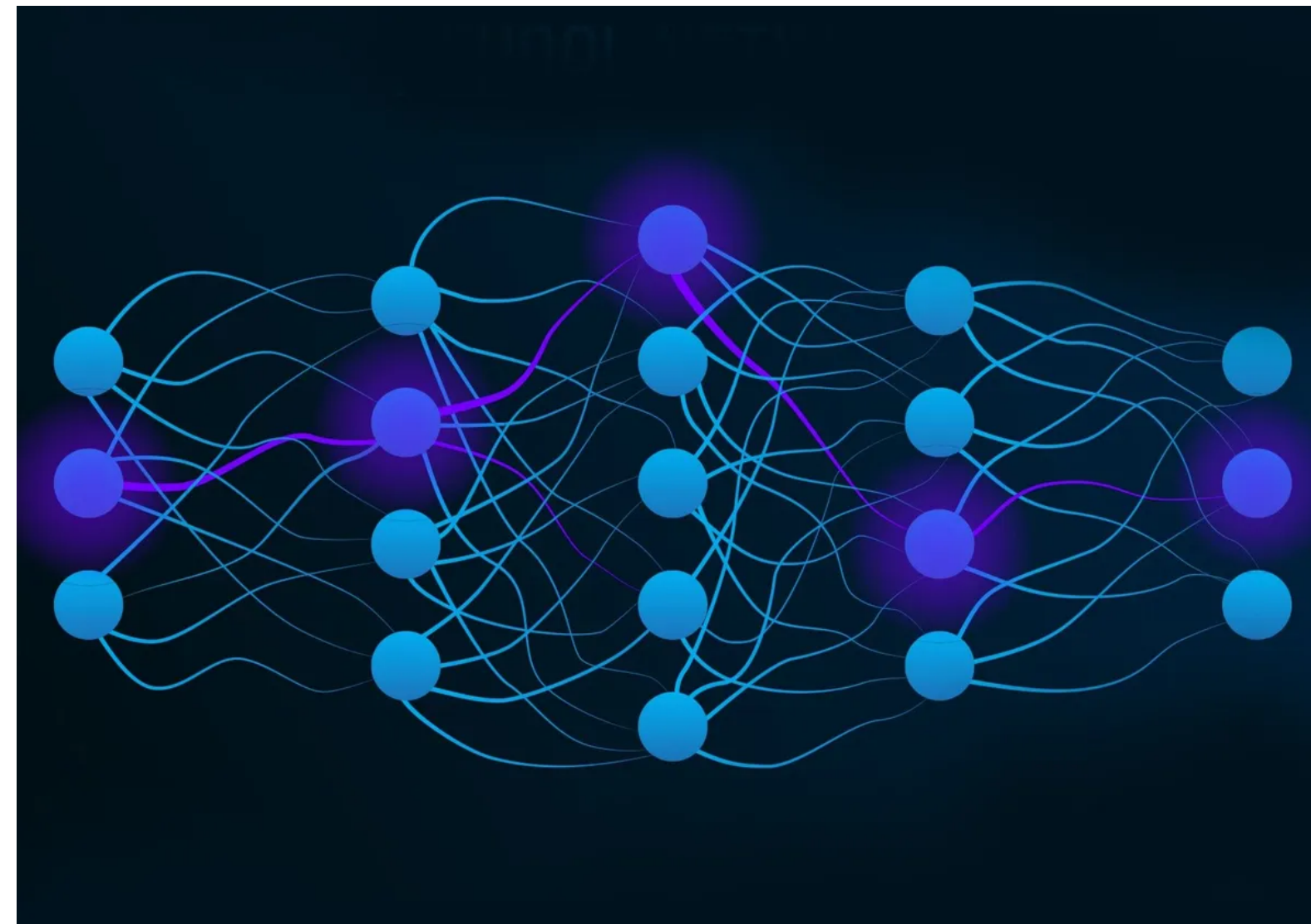


Challenge I: Complexity

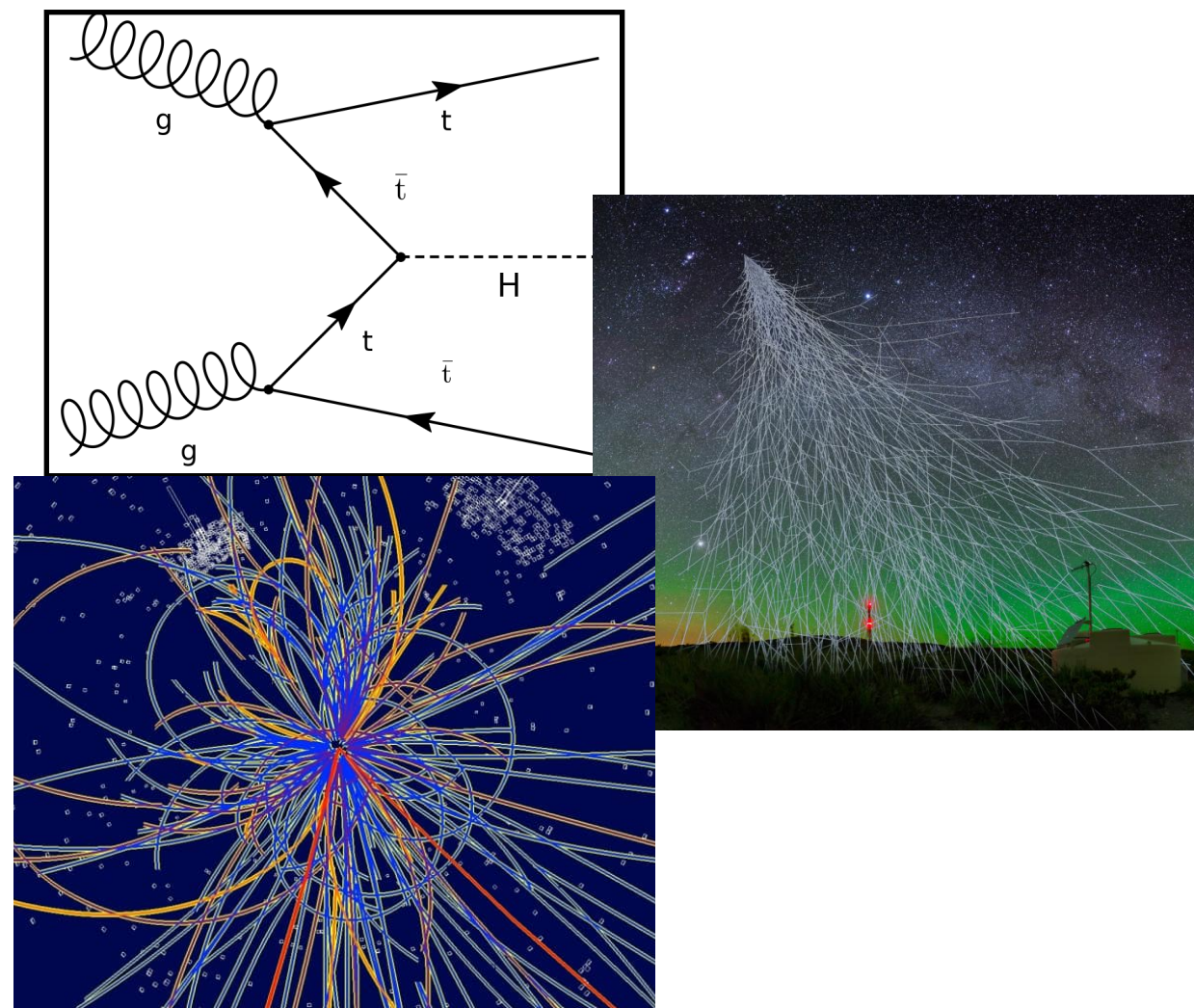


Challenge II: Large Datasets

Solution: Machine Learning

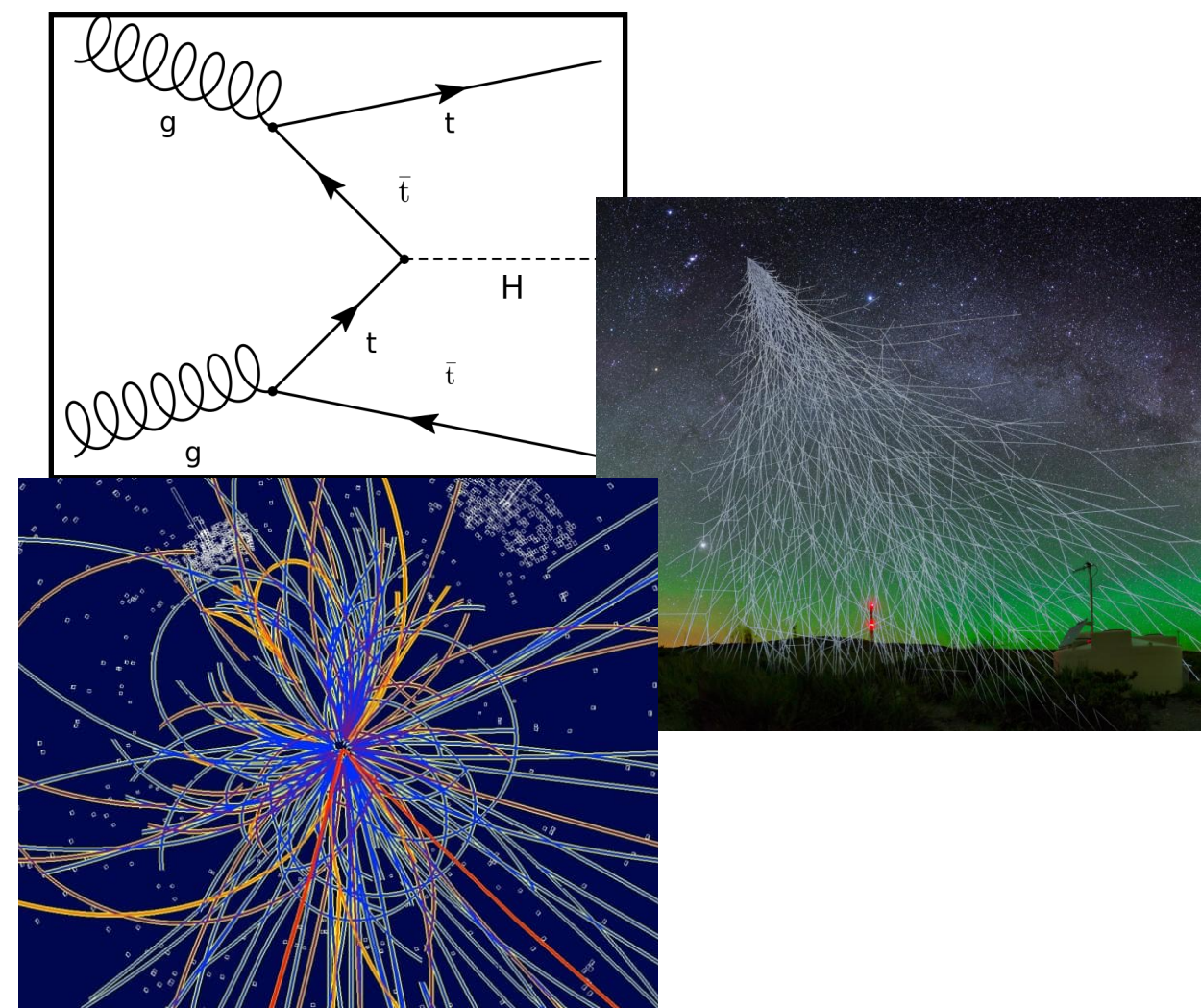
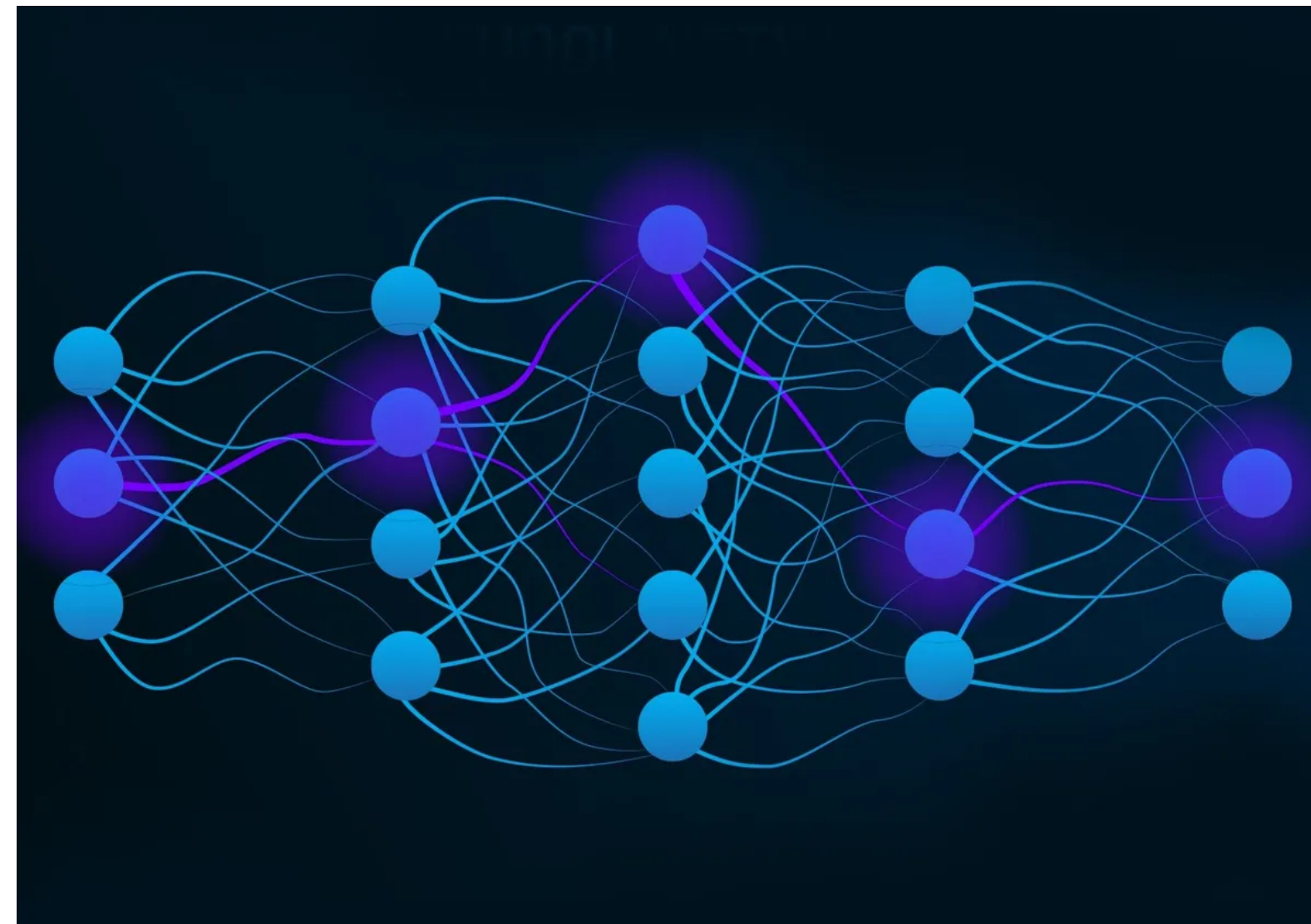


Challenge II: Large Datasets



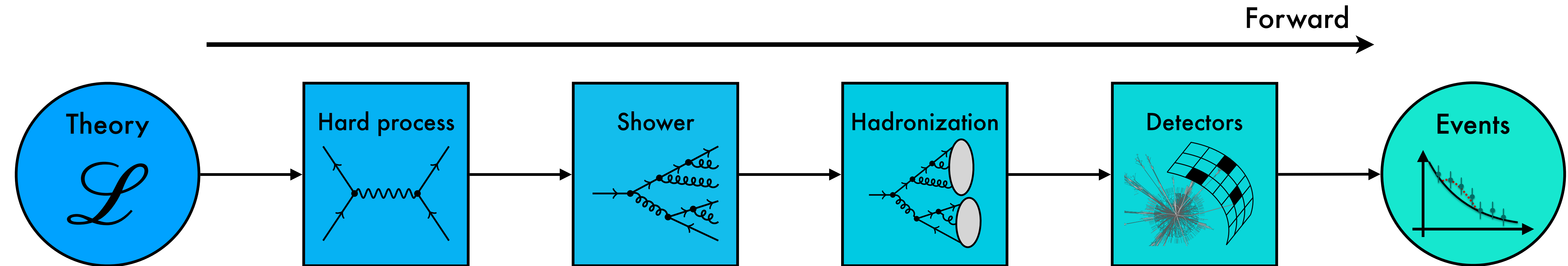
Challenge I: Complexity

Solution: Machine Learning



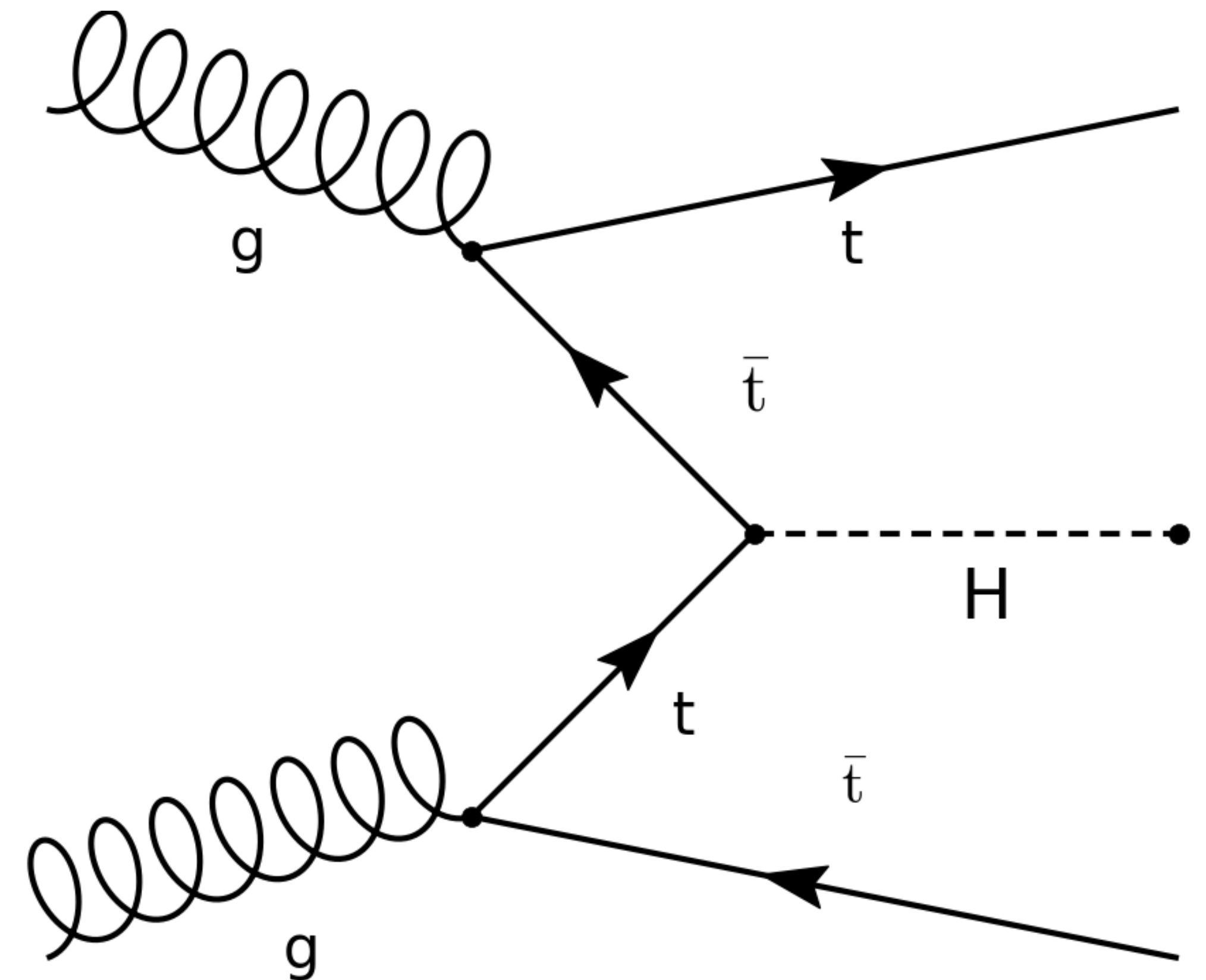
Understand Complexity

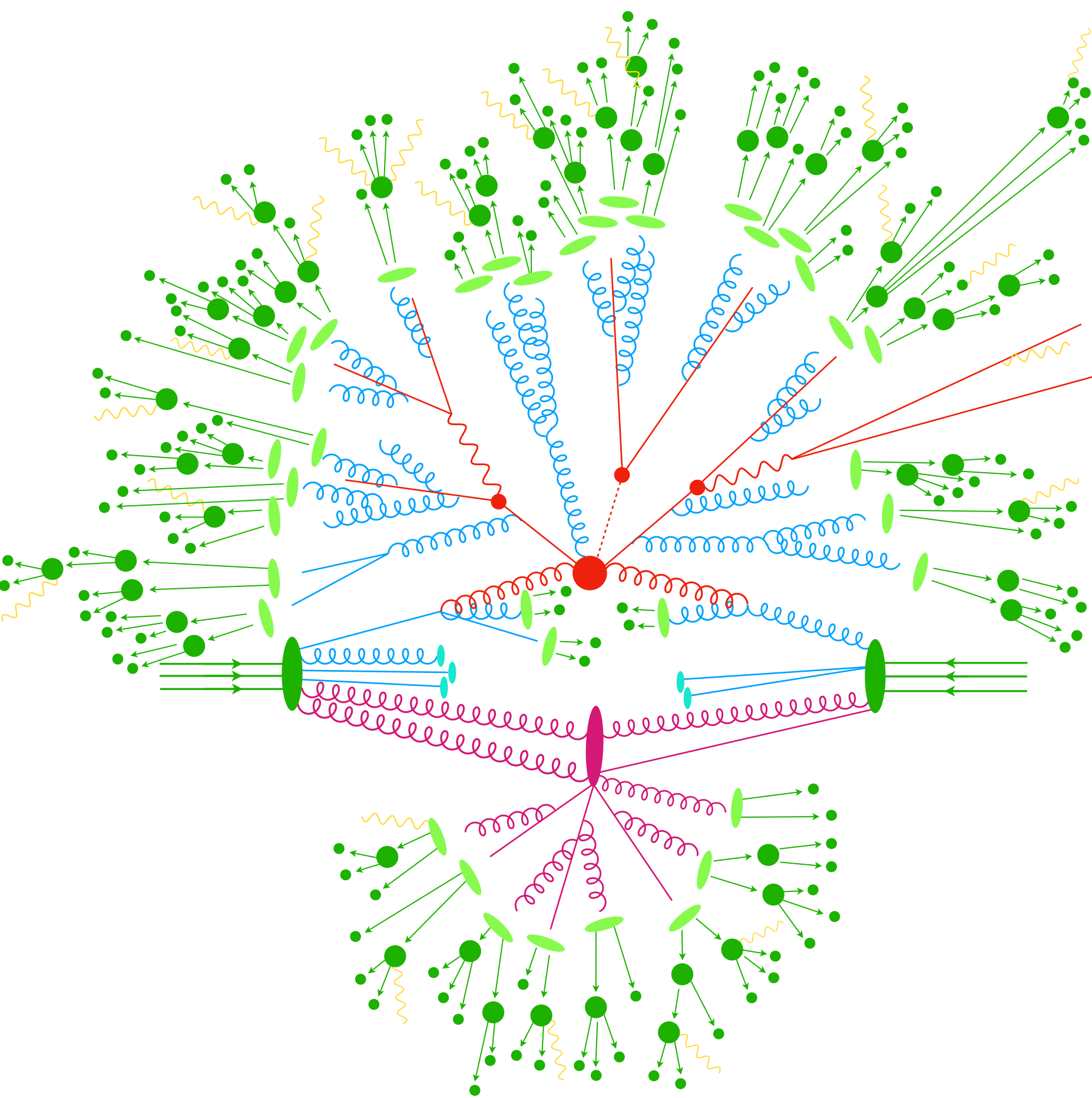
Using Large Datasets



Hard Process

- Models initial particle collision
- Many processes with cross-sections
- Calculate cross-sections from theory model/Lagrangian
- Use Monte Carlo sampling
- Complex processes → expensive



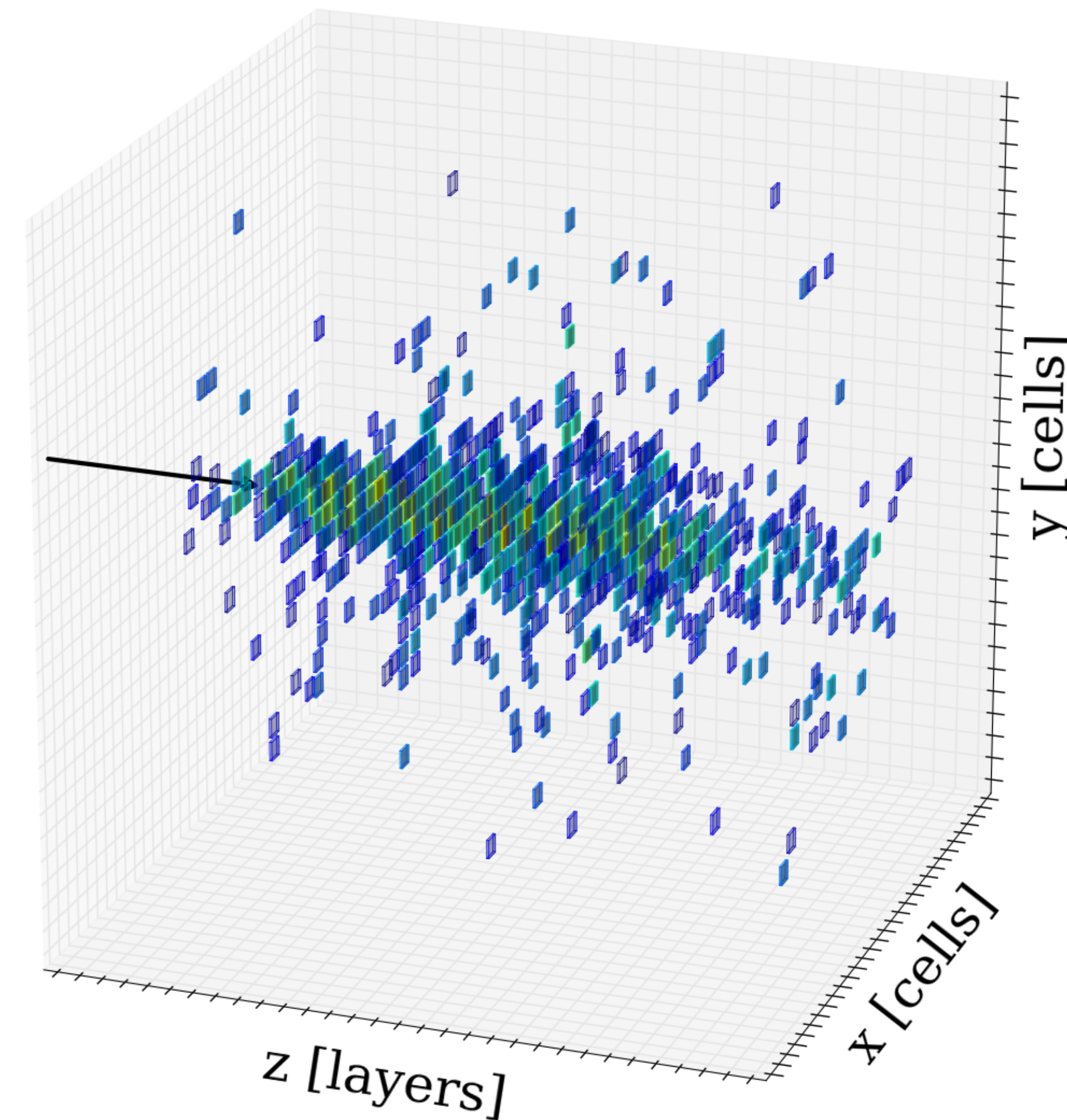


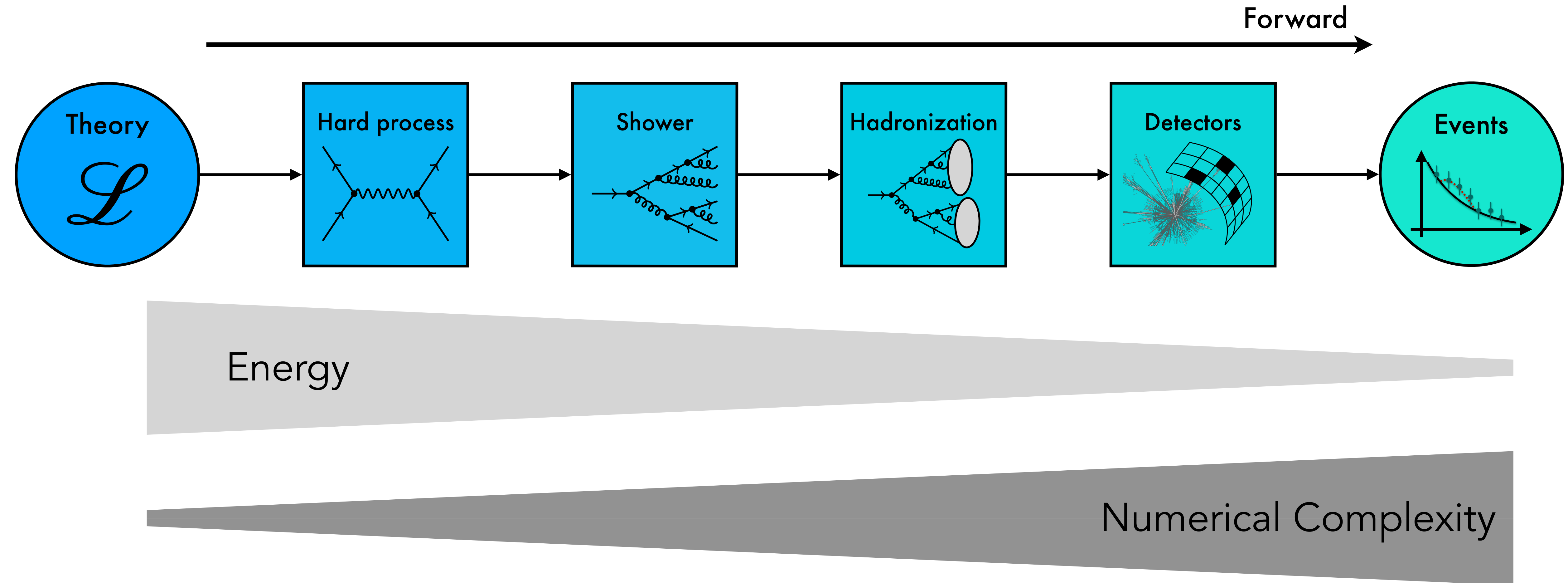
Showering/Hadronization

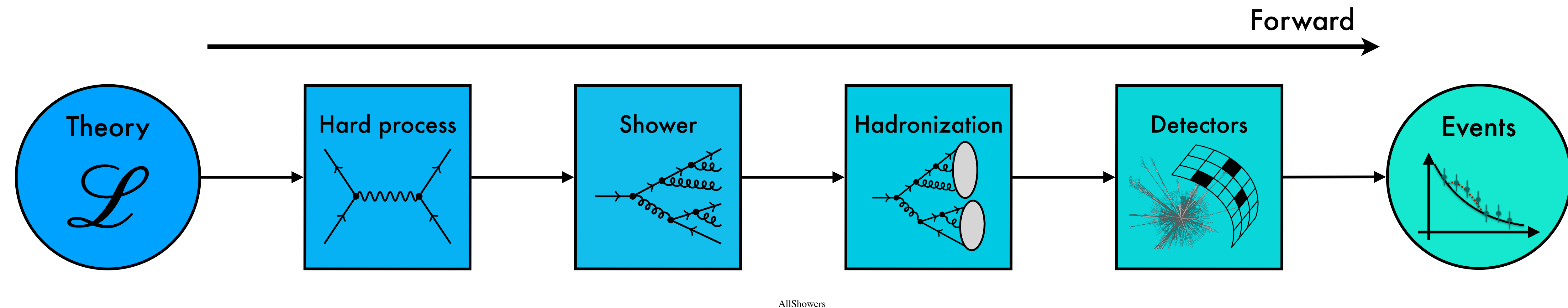
- ▶ Quarks only exist in bound states
- ▶ Any quark produced forms Hadron
- ▶ Propagating Hadrons emit more particles
- ▶ Collimated sprays of particles called jets
- ▶ Current models imperfect, difficult to simulate

Detector Simulation

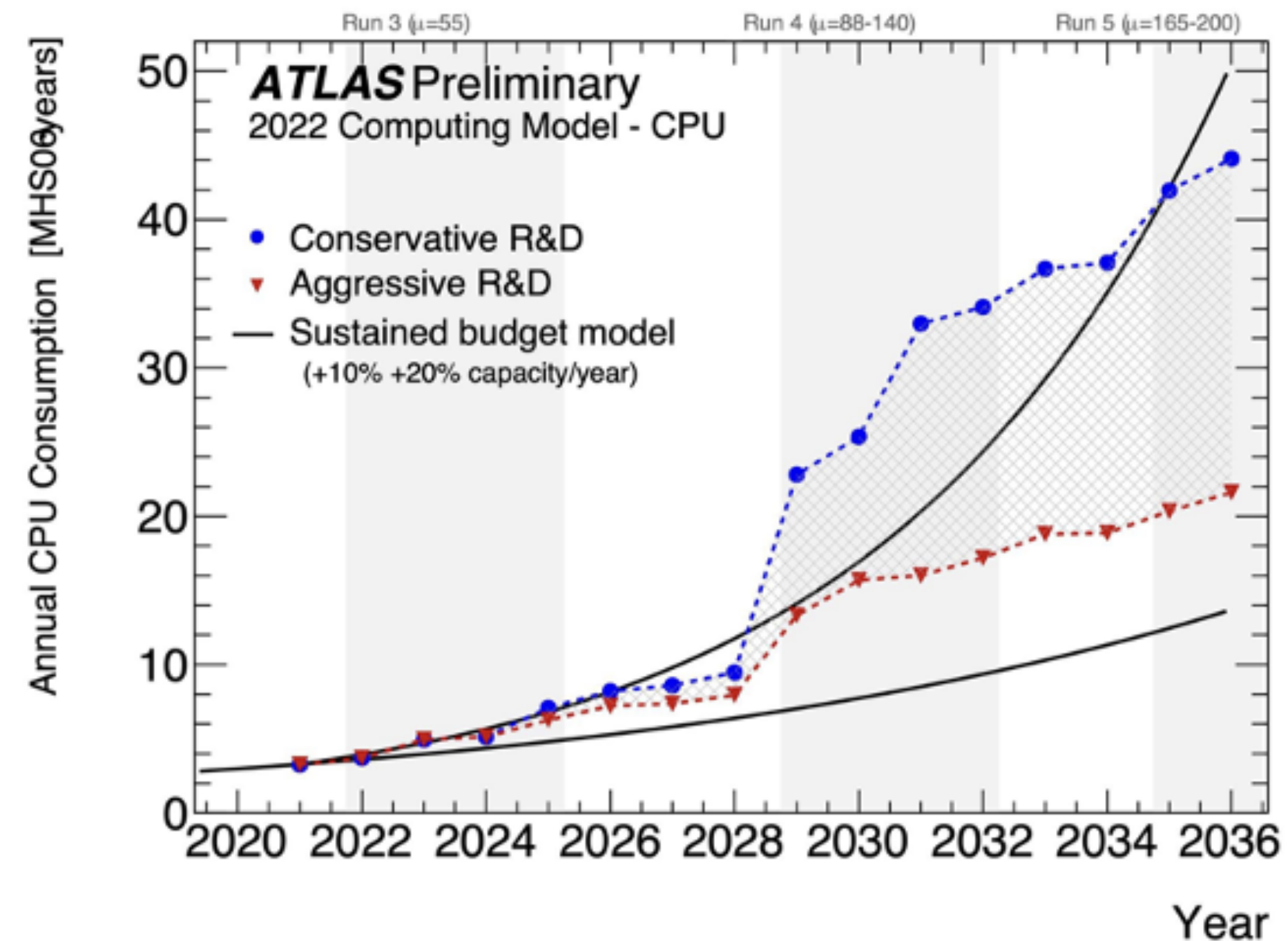
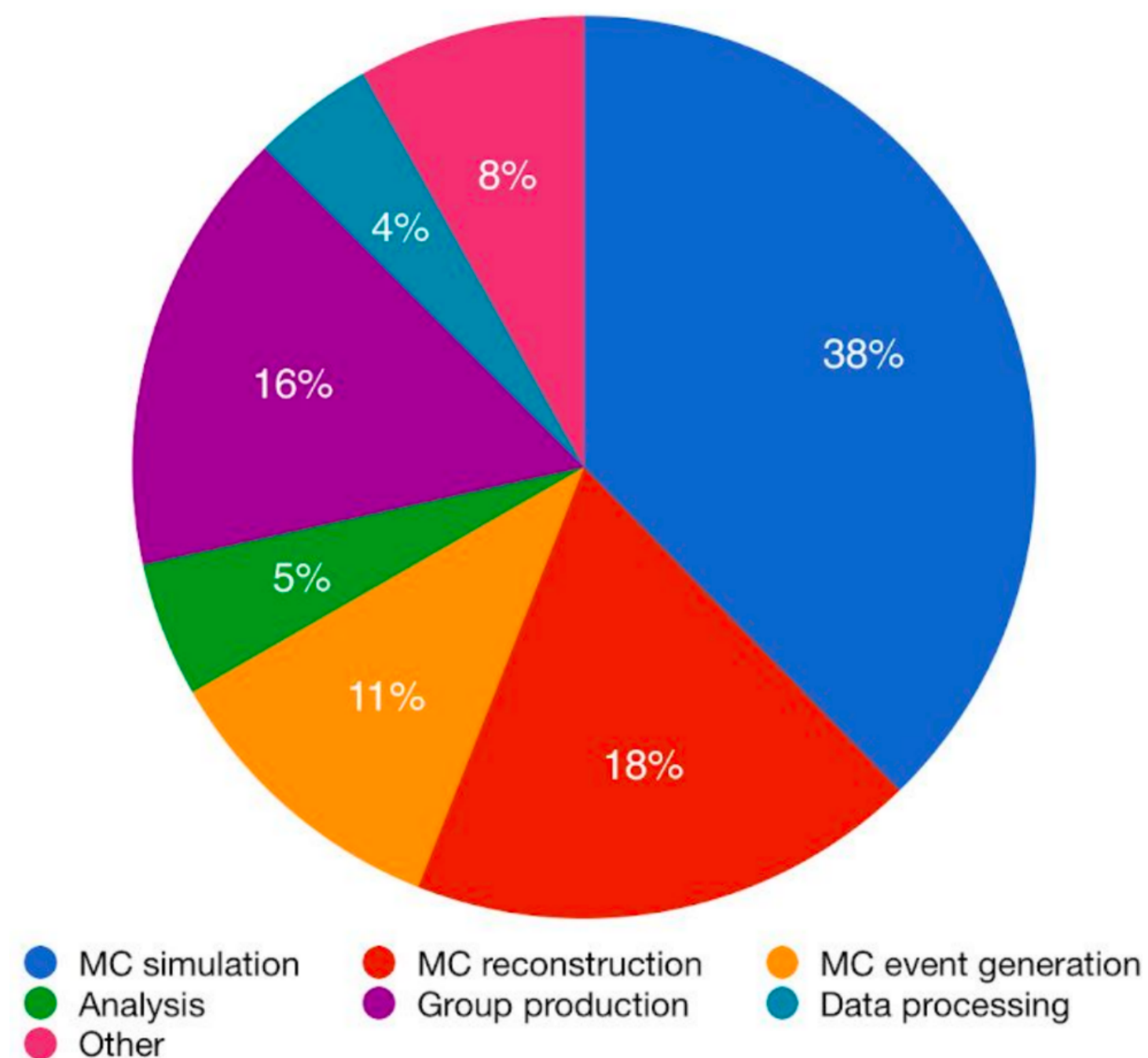
- Particles interact with detector material
- Ionization: leaves signature in detector
- Bremsstrahlung, Pair-production, Nuclear Interaction, Spallation → more particles
- New particles continue to interact
- All need to be simulated → expensive







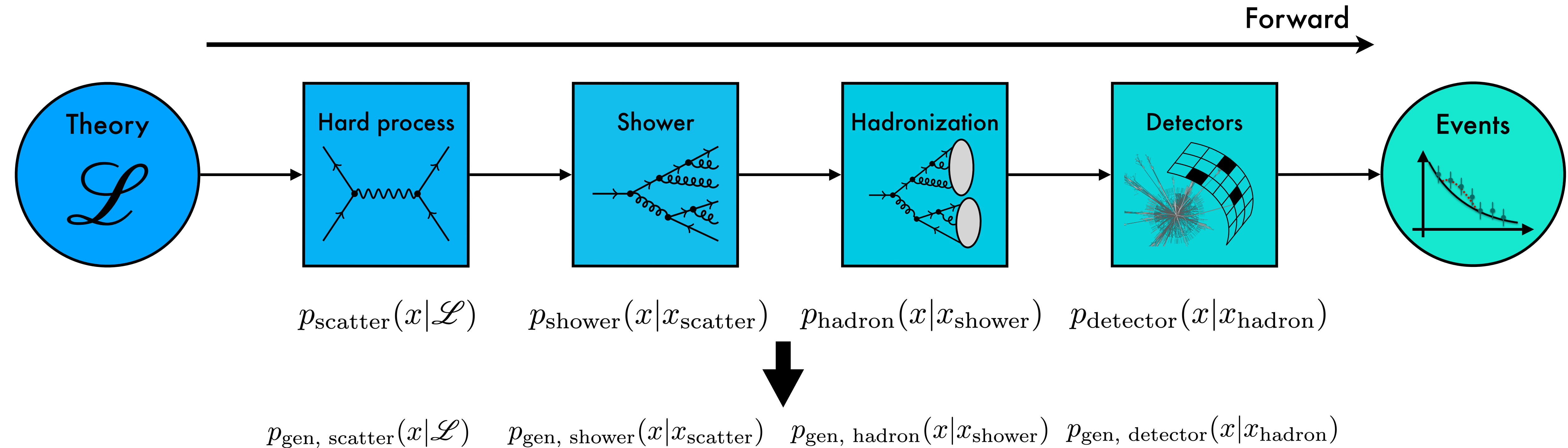
- ▶ First-principles precision simulations, accurate, expensive and slow
- ▶ Need more simulated data than recorded data
- ▶ Higher-rate experiments → need more and more precise simulation



- ▶ Simulation cost is computational bottleneck for future HEP experiments
- ▶ Need accelerated methods

Al-Turany et. al. JENA Computing Initiative WP2 Report: Software and Heterogeneous Architectures, [2503.09213](#)

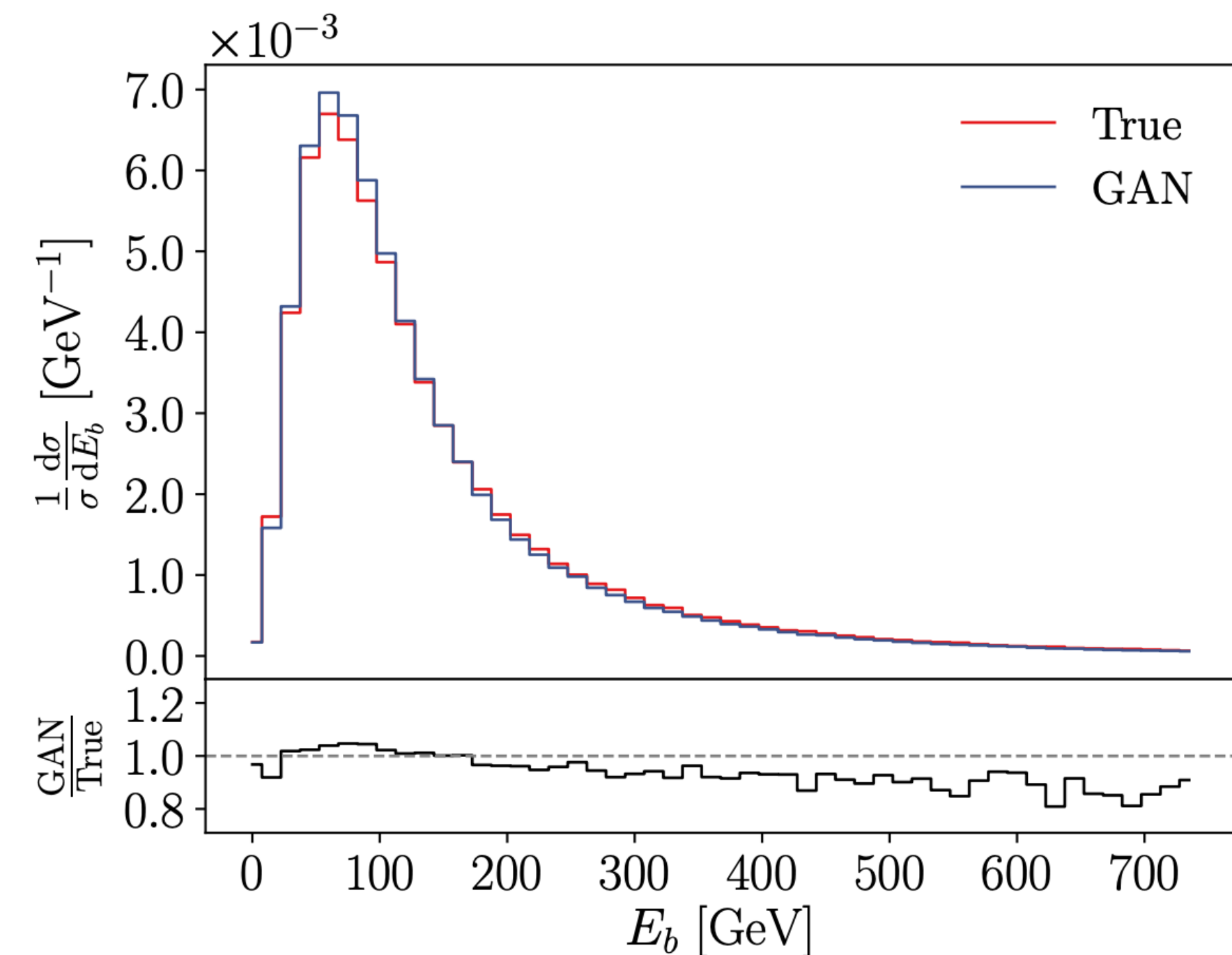
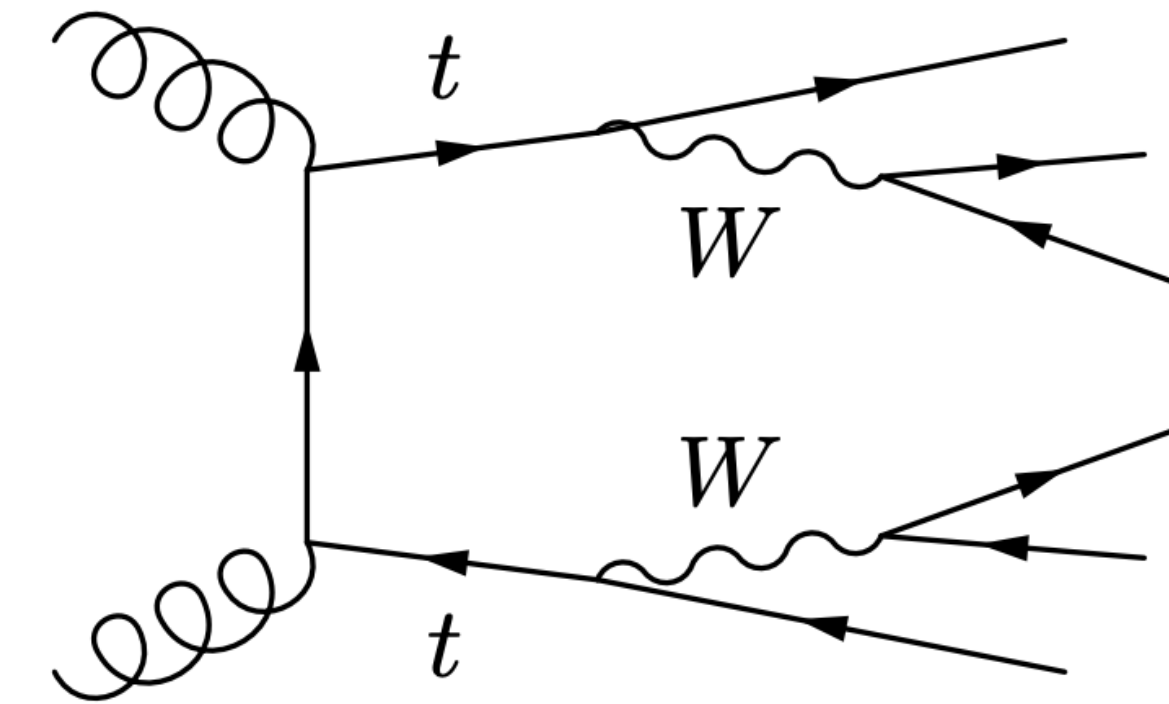
Catmore et. al. ATLAS HL-LHC Computing Conceptual Design Report, [CERN-LHCC-2020-015](#) ; [LHCC-G-178](#)



- Series of conditional densities, approximate with conditional generative networks
- Faster, more efficient, leverage data

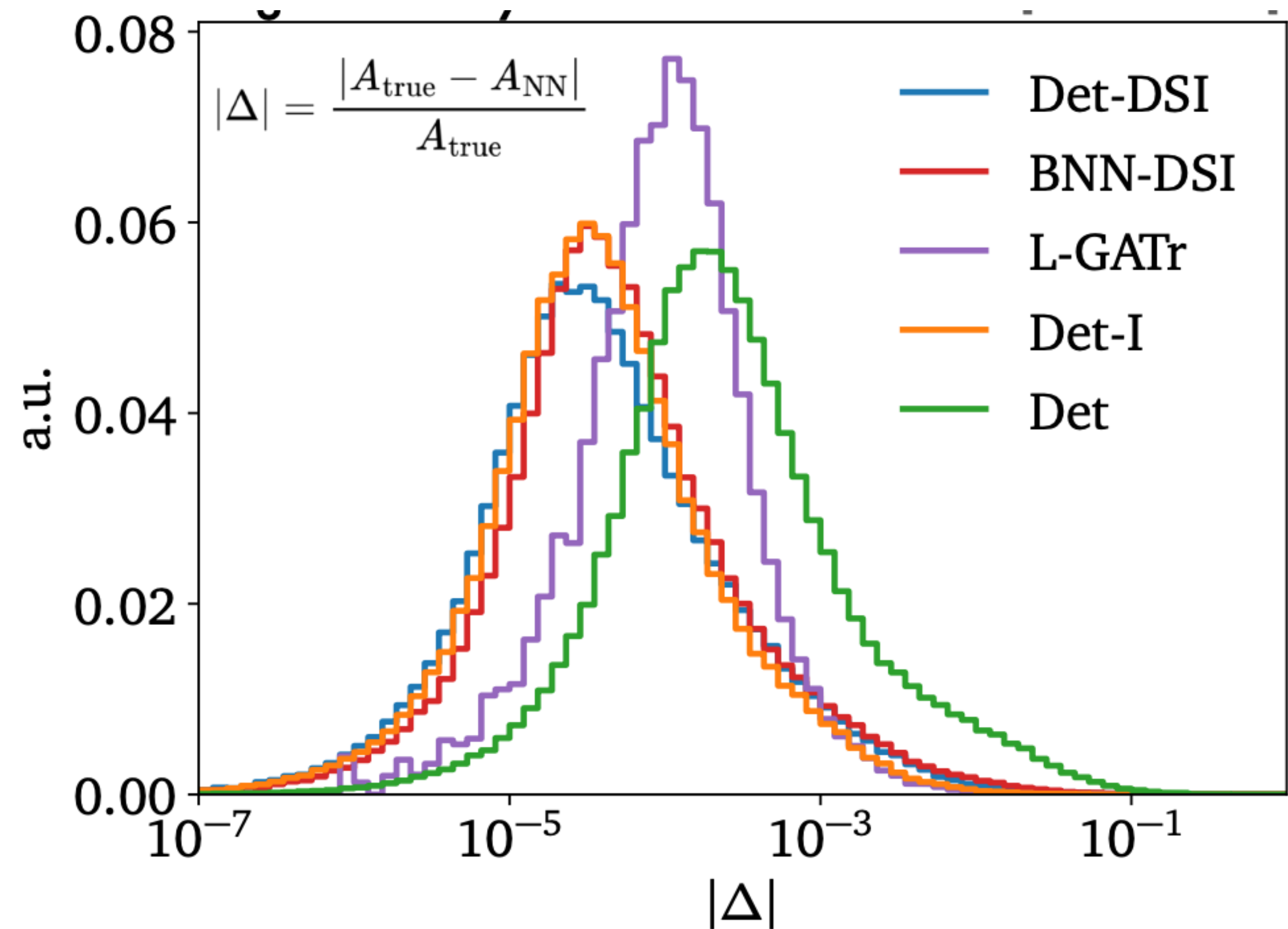
Hard Process

- Precise theory description
- Slow evaluation
- Slow sampling
- Initial approach:
 - Train Generative model on simulated data
 - Sample from model



More Recent:

- ▶ Slow evaluation
 - Amplitude surrogates
- ▶ Train regression model on scattering amplitudes
- ▶ Only needs grid of points
- ▶ Evaluate model
 - Massive acceleration

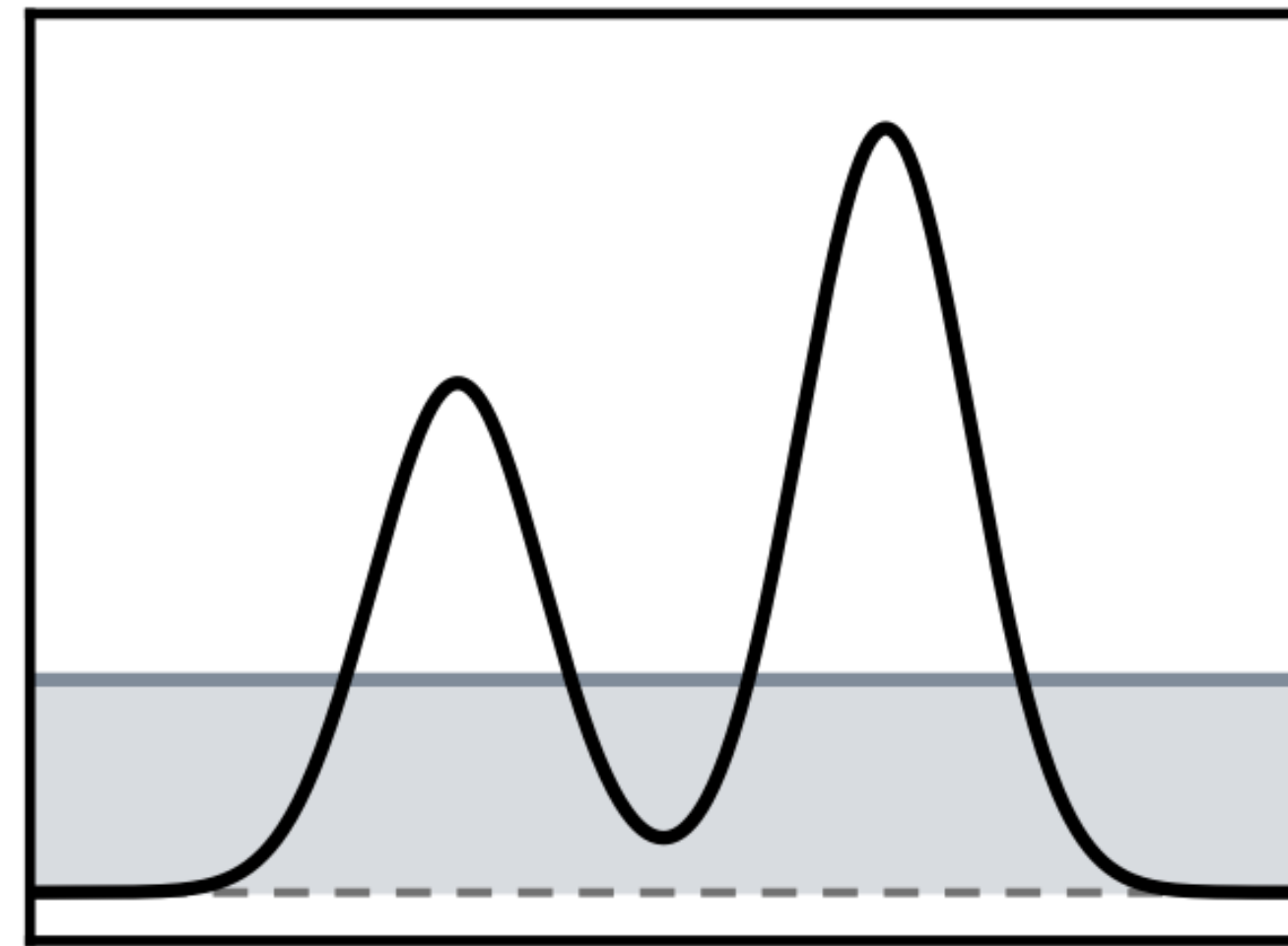


Winterhalder: Theory ex Machina [EuCAIFCon 2026](#)

Bahl et. al.: Accurate Surrogate Amplitudes with Calibrated Uncertainties [2412.12069](#)

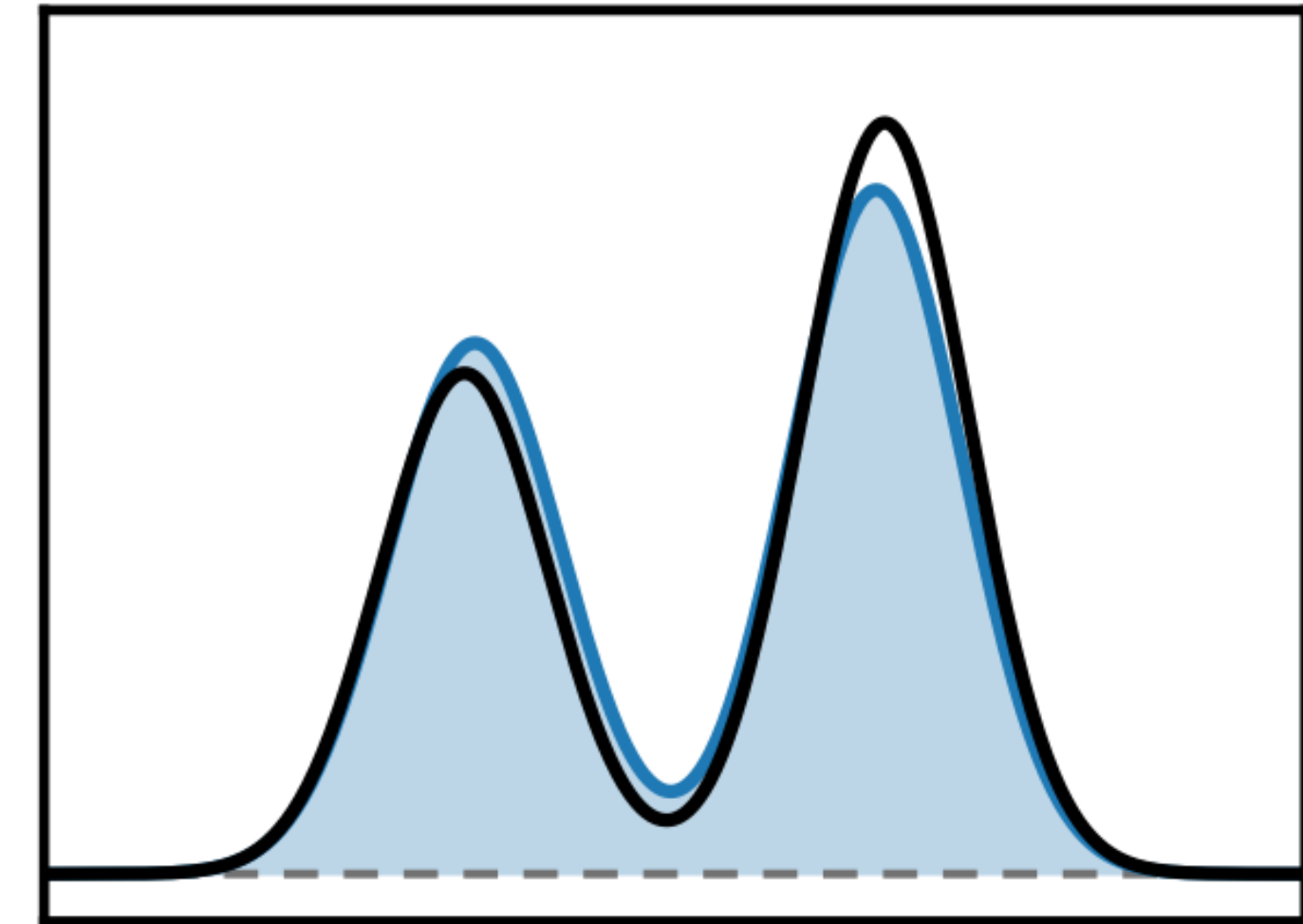
More Recent:

- ▶ Slow sampling
 - Neural Importance Sampling
- ▶ Integrate over phase space
- ▶ Needs numerical integration
- ▶ Speed up by sampling proposal from Normalizing flow
- ▶ Both surrogates and NIS already deployed in MadGraph



Flat sampling:
inefficient

$$I = \langle f(x) \rangle_{x \sim \text{unif}}$$

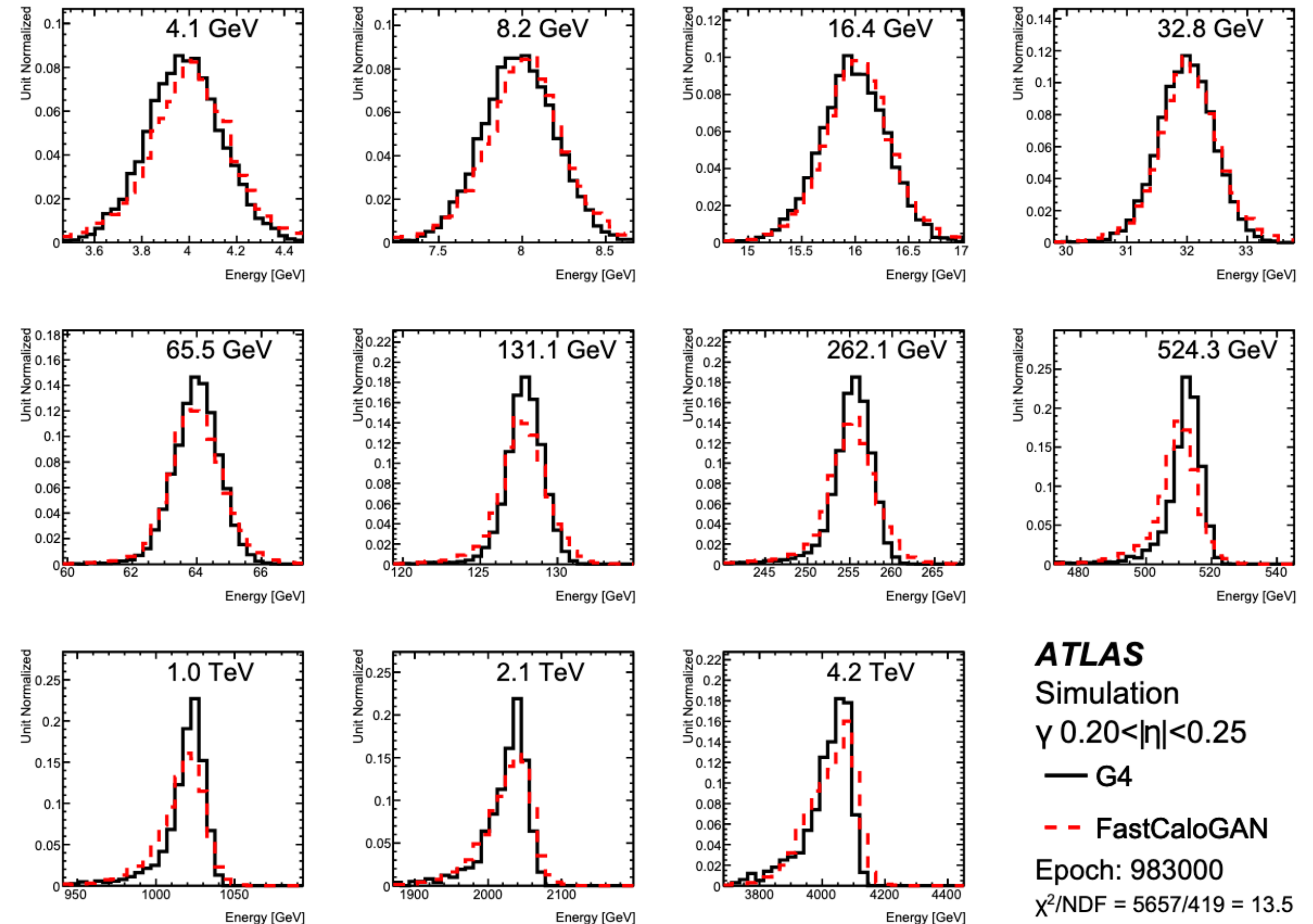


Importance sampling:
find p close to w

$$I = \left\langle \frac{f(x)}{g(x)} \right\rangle_{x \sim g(x)}$$

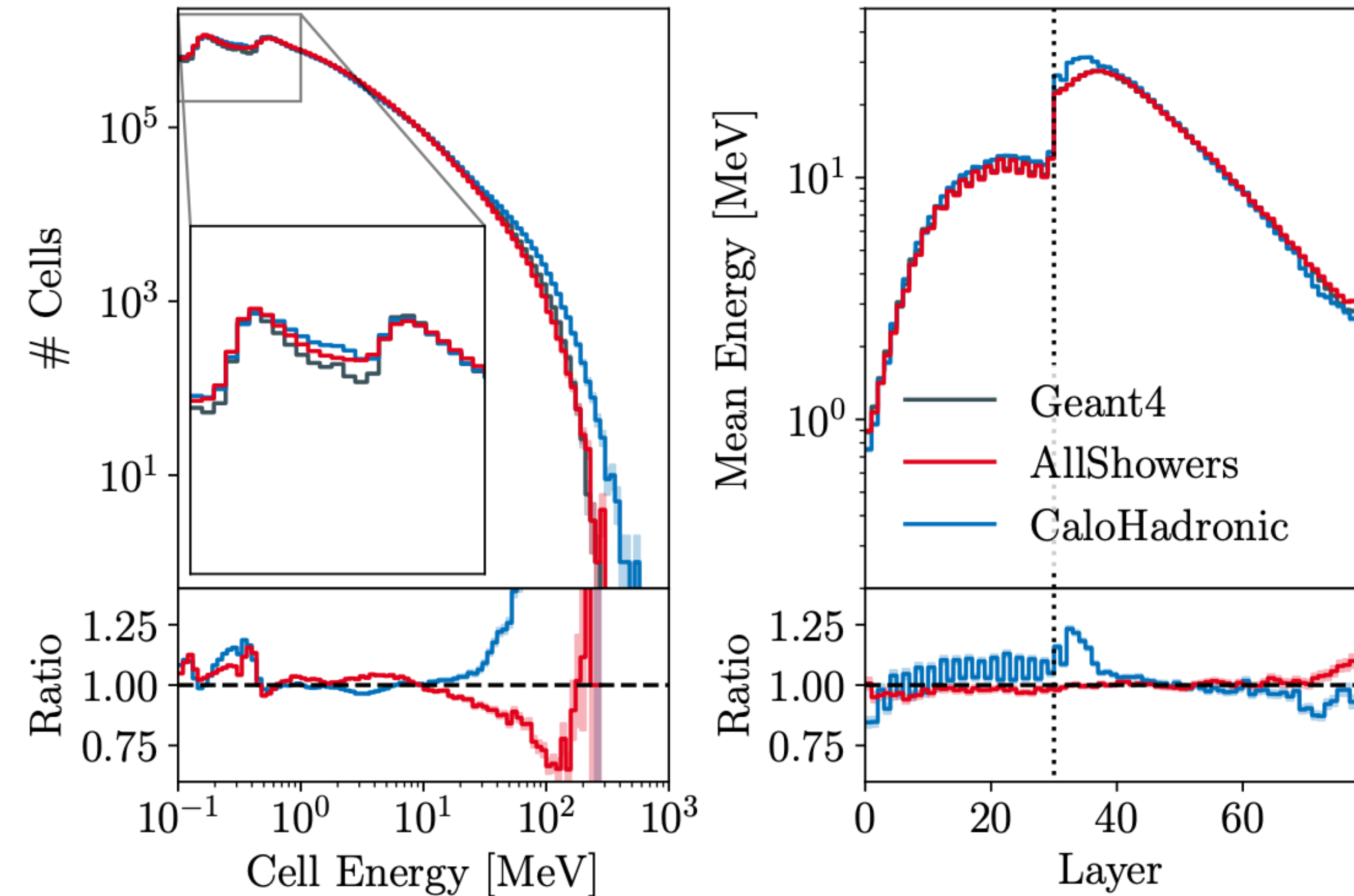
Calorimeter Simulation

- ▶ Stochastic understanding
- ▶ Very slow individual modeling
- ▶ High dimensional data
- ▶ Initial approach:
 - ▶ Skip all intermediate steps
 - ▶ Train model on end result
- Learn full calorimeter shower



Calorimeter Simulation

- ▶ Problem: detector are big, shower are localized
 - Learn only region around shower
 - ▶ Next Problem: shower position is not constant
 - Pointcloud model, project back to detector geometry
- Universal for position and angle

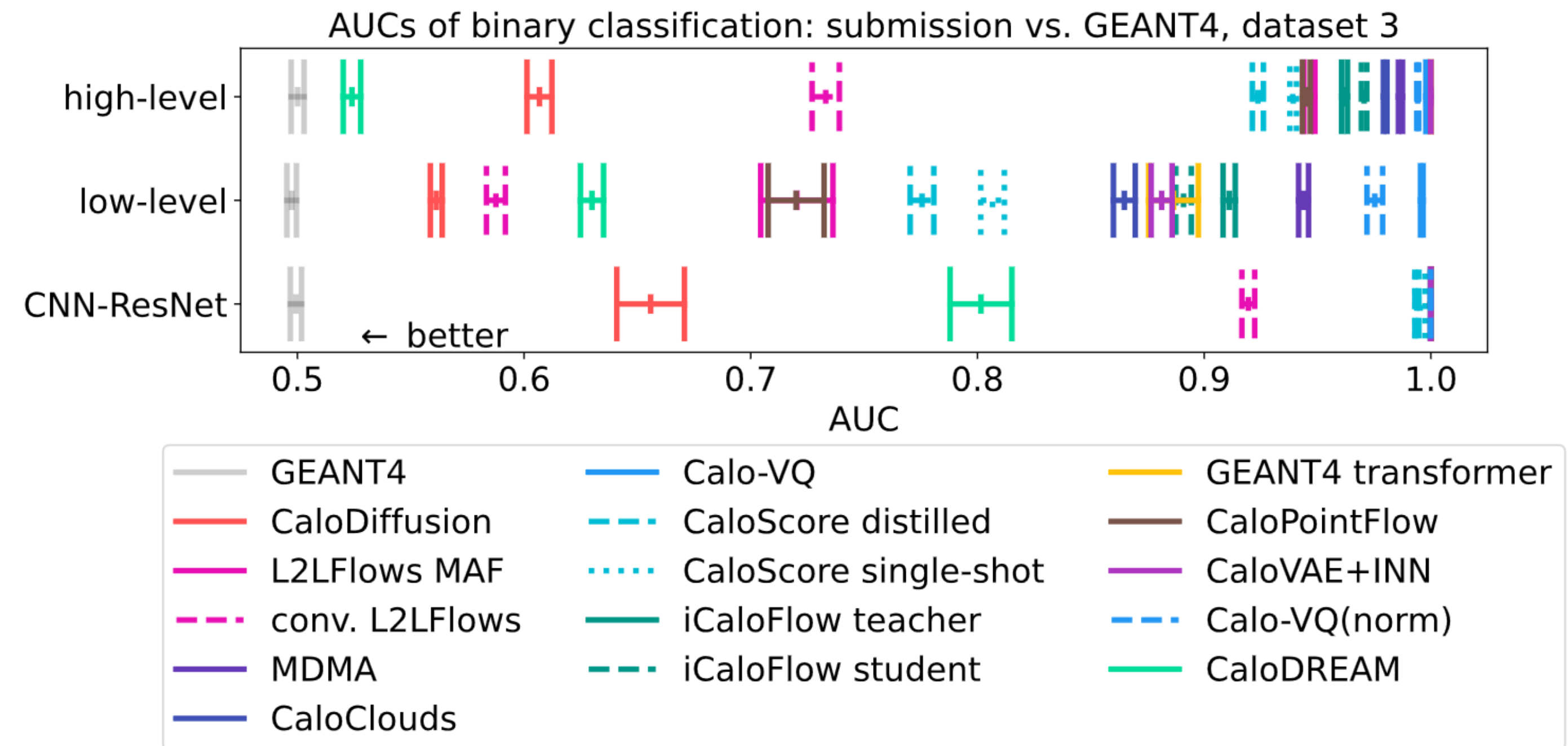


Calorimeter Simulation

- Highly active field of research

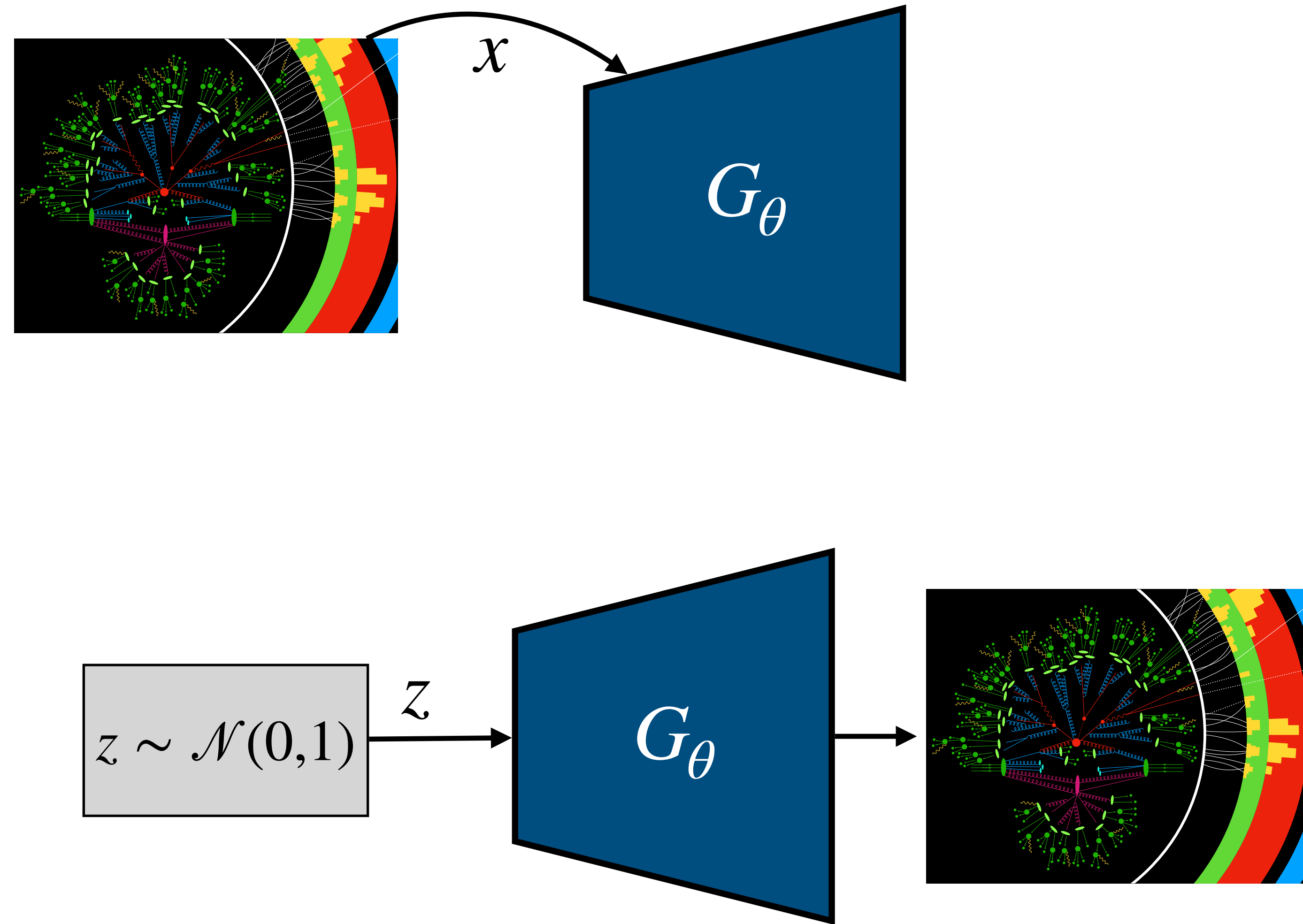


- Massive comparison challenge



Fast simulation

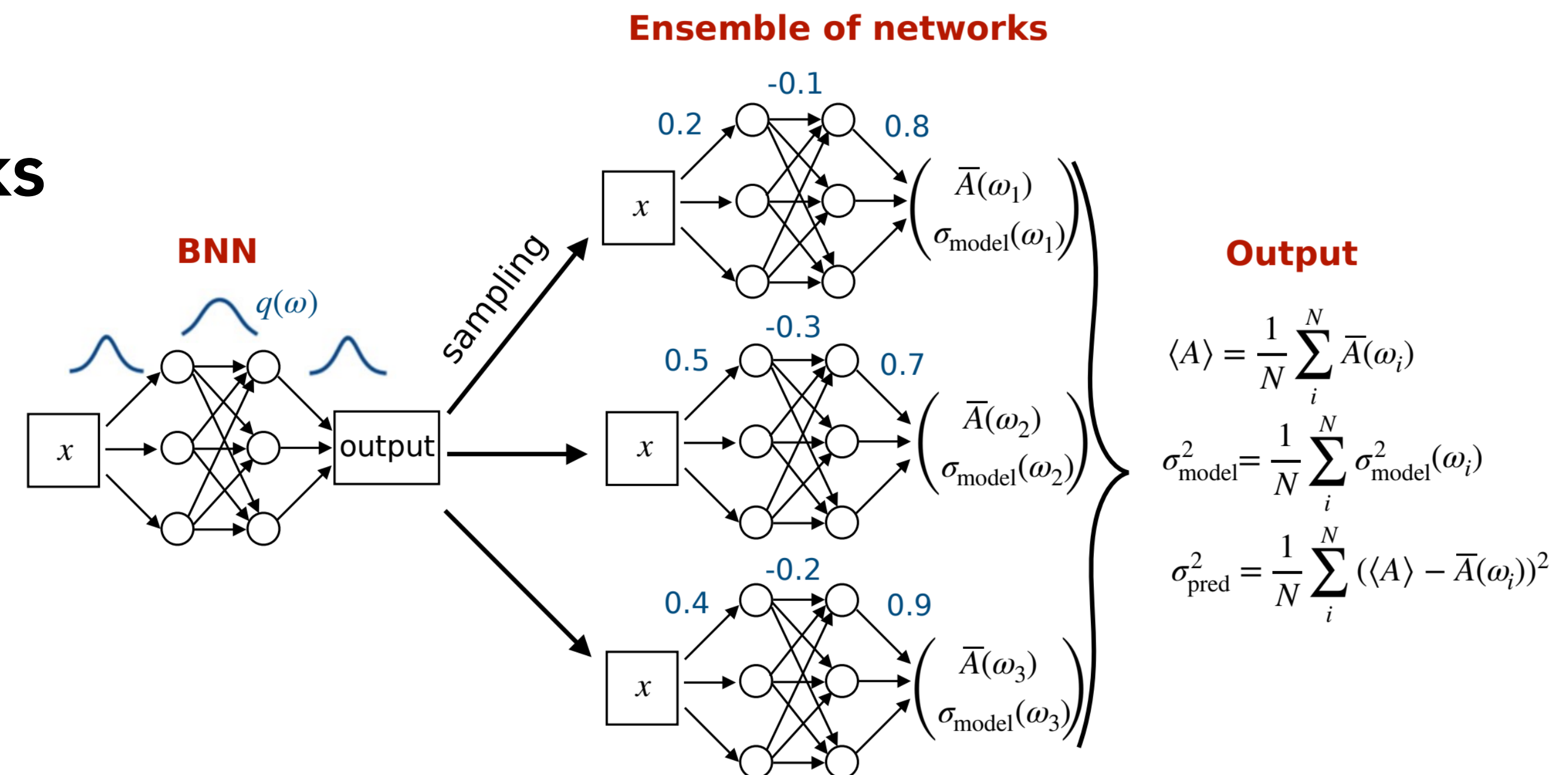
- ▶ Train on simulated data
- ▶ Sample from generative network
- ▶ Faster than classical simulation
 - ▶ GAN
 - ▶ Normalizing flow
 - ▶ Diffusion models
 - ▶ Autoregressive transformers



Physics needs uncertainty estimates

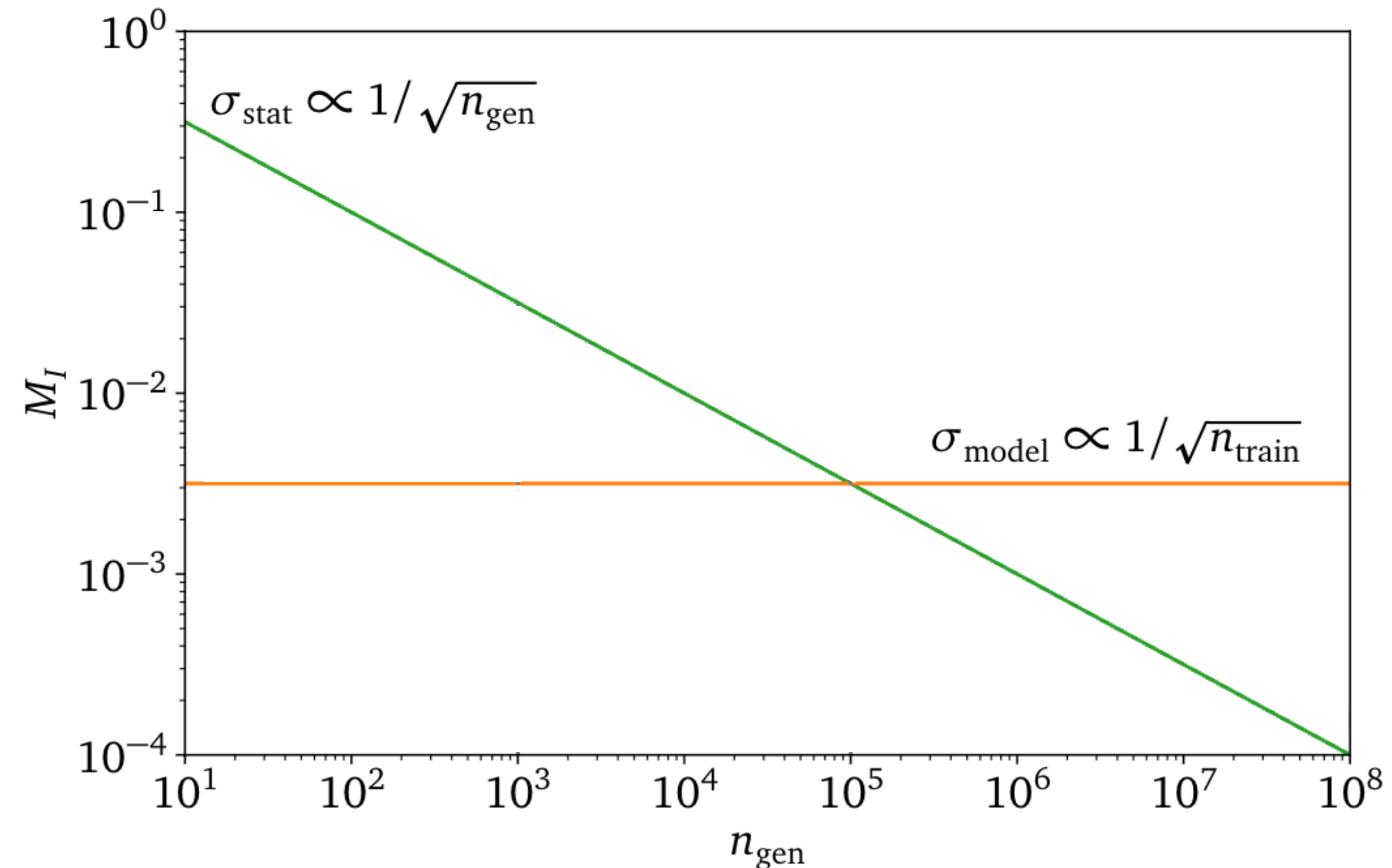
ML uncertainty quantification:

- ▶ Heteroscedastic losses, repulsive ensemble, **bayesian neural networks**
- ▶ Transferable to generative models with likelihood losses
- ▶ Bayesian normalizing flows
- ▶ Uncertainty on **density estimation**



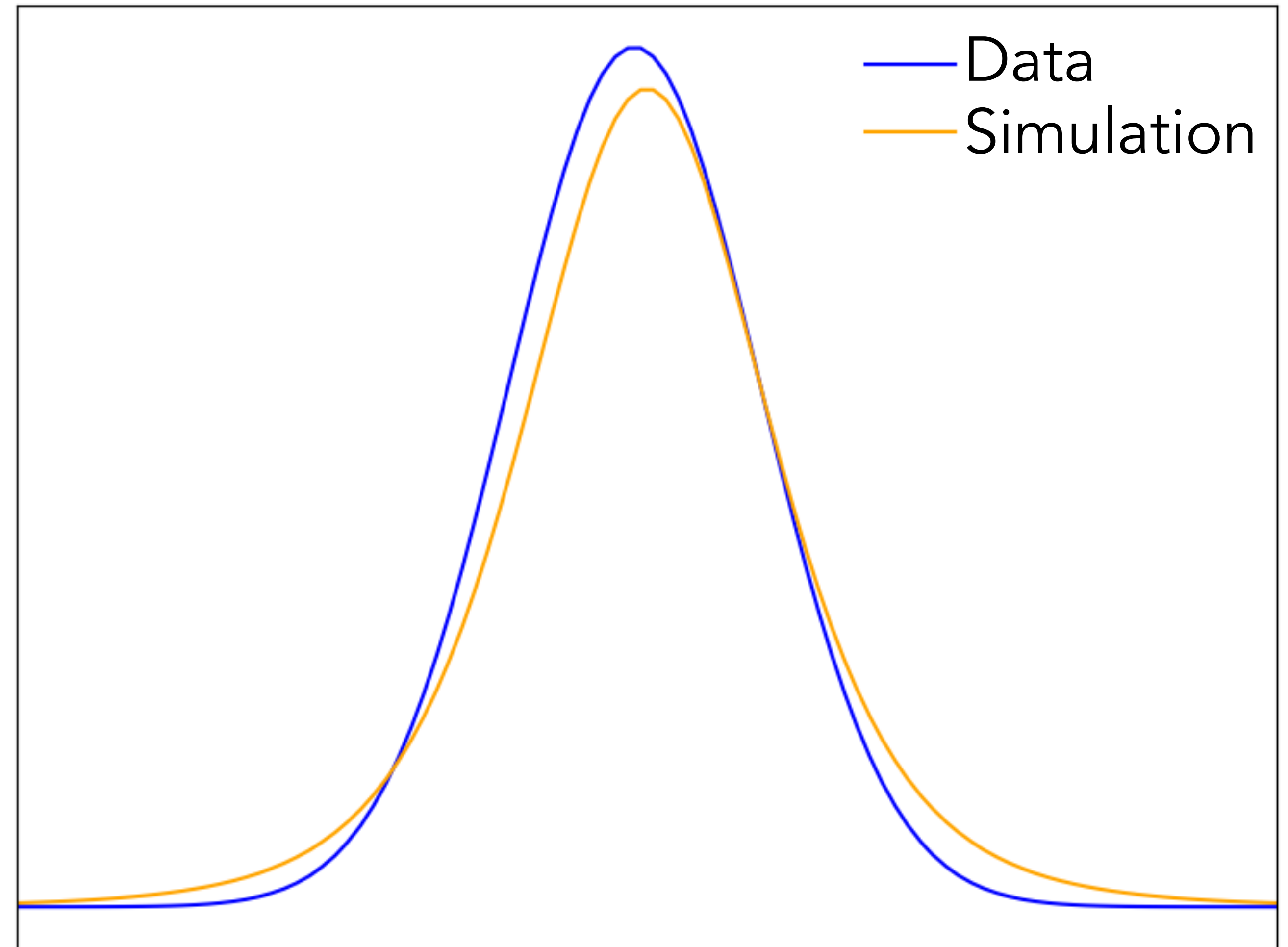
What uncertainty is learned?

- For Generative models:
- **Statistical uncertainty** σ_{stat}
 - Scales $\frac{a}{\sqrt{n_{\text{gen}}}}$
 - Infinitely reducible
- **Generalization uncertainty** σ_{model}
 - Scales $\frac{b}{\sqrt{n_{\text{train}}}}$
 - Irreducible by sampling



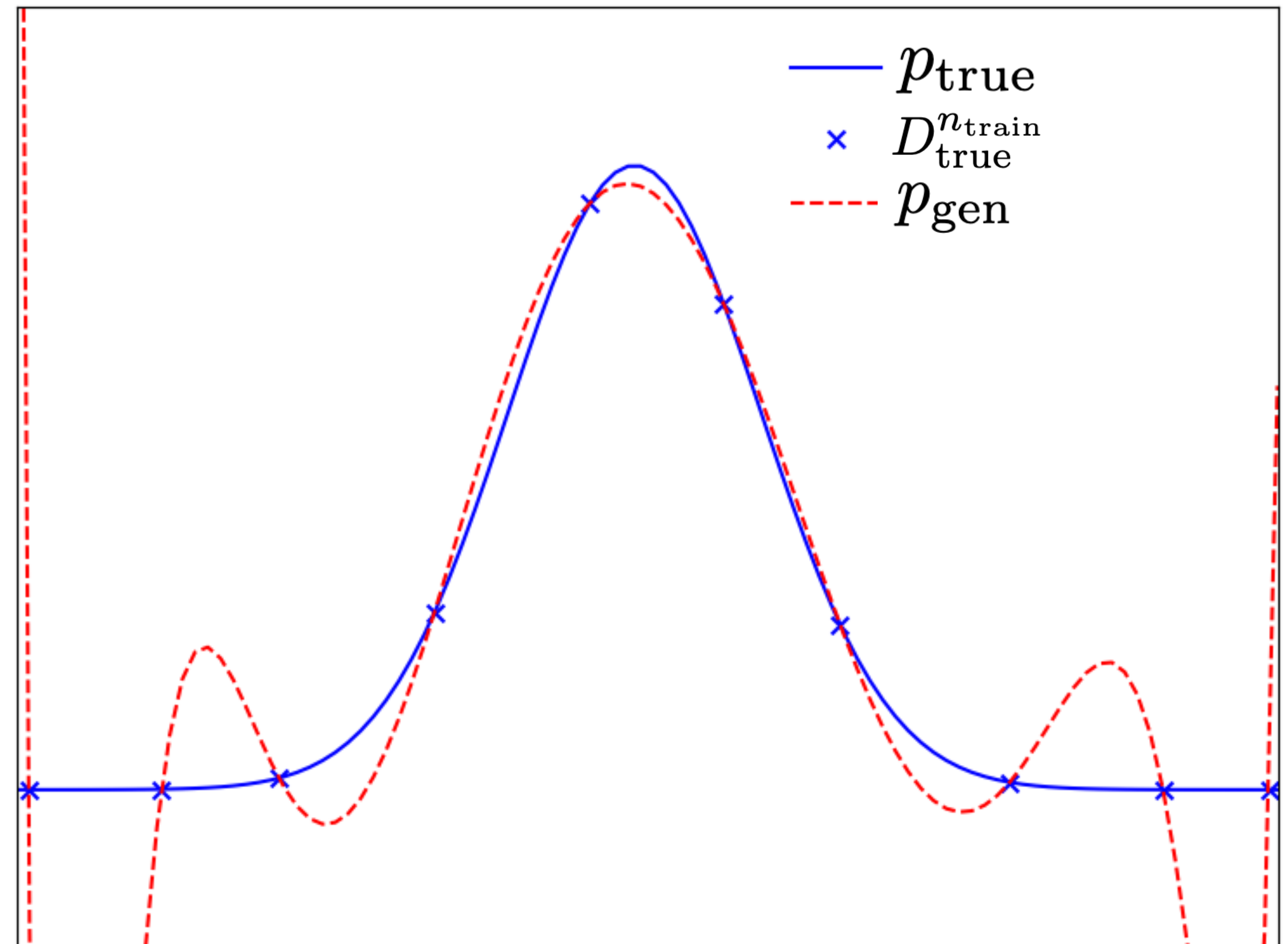
Generalization uncertainty

- Most applications:
 - Inference data $\neq$ training data
 - Extrapolation outside training



Generalization uncertainty

- ▶ Most applications:
 - ▶ Inference data $\neq$ training data
 - ▶ Extrapolation outside training
- ▶ Generative modeling:
 - ▶ Extrapolation in resolution



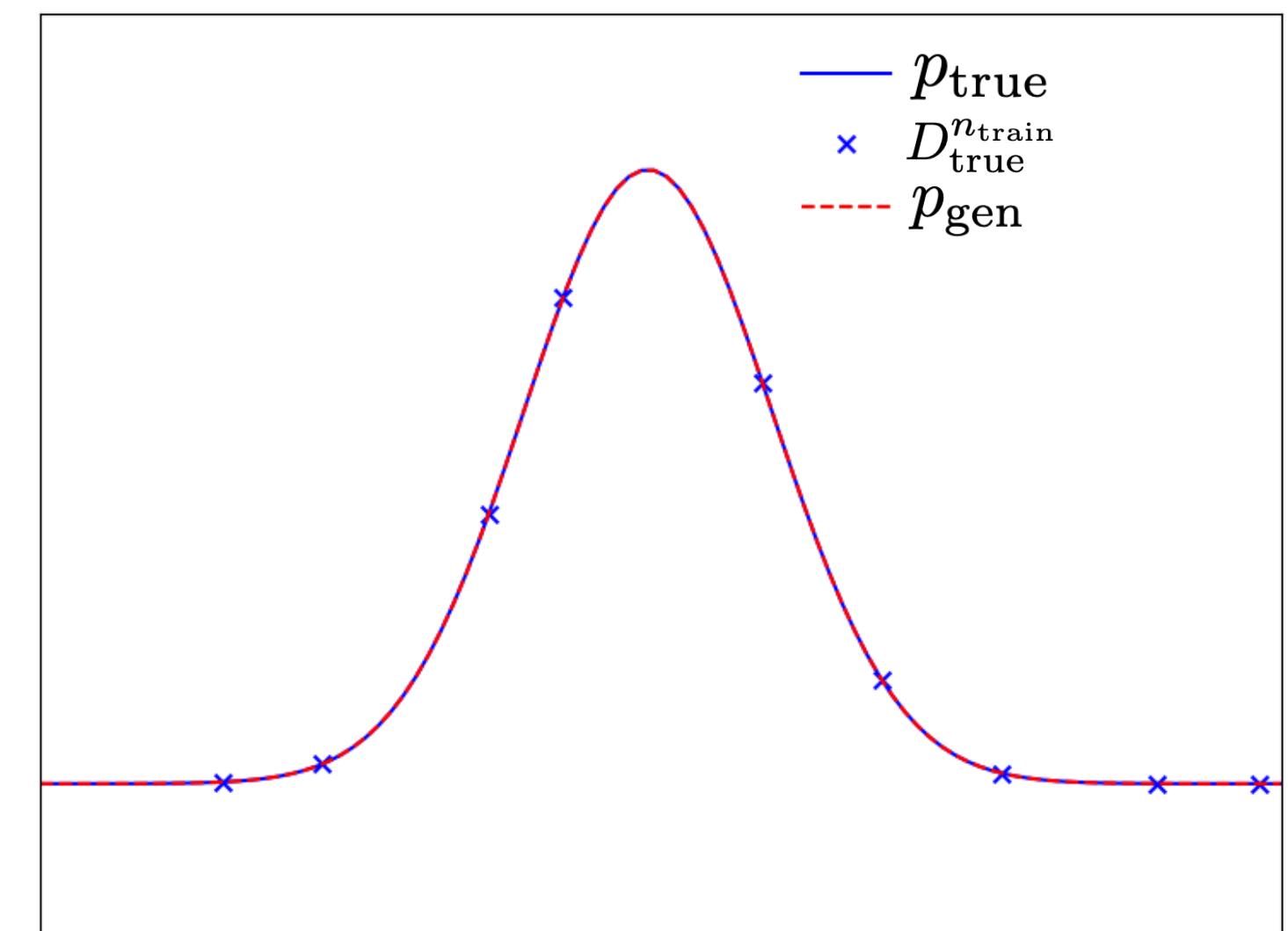
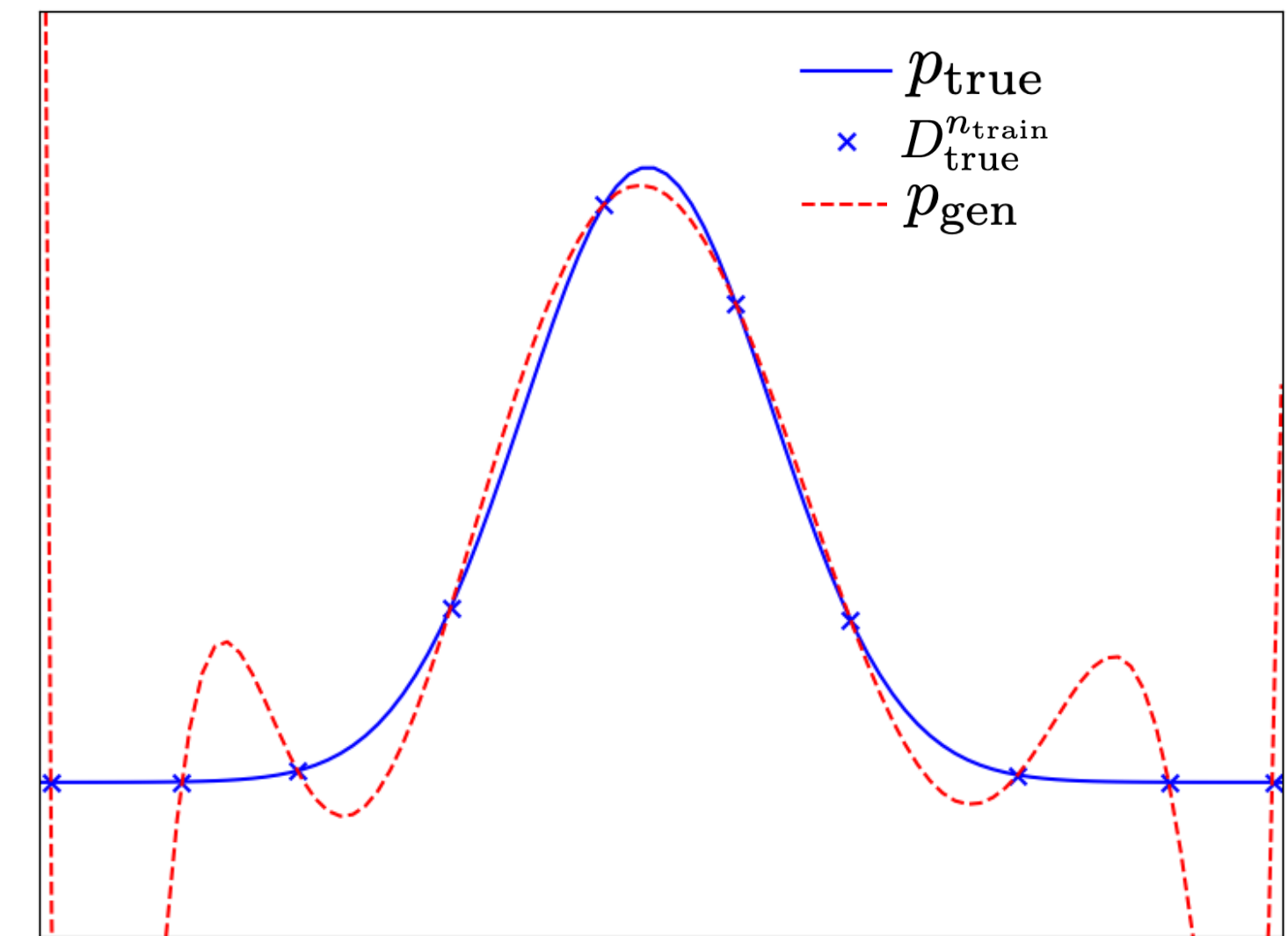
Fundamental question

- ▶ What happens if I exceed the training resolution?
- ▶ How many points n_{gen} can I draw?
- ▶ Generative simulation assumes $n_{\text{gen}} > n_{\text{train}}$
- ▶ Is this really true?

“If I train a model on 1 million data points,
how many can I draw from that model?”

—Louis Lyons

→ Amplification



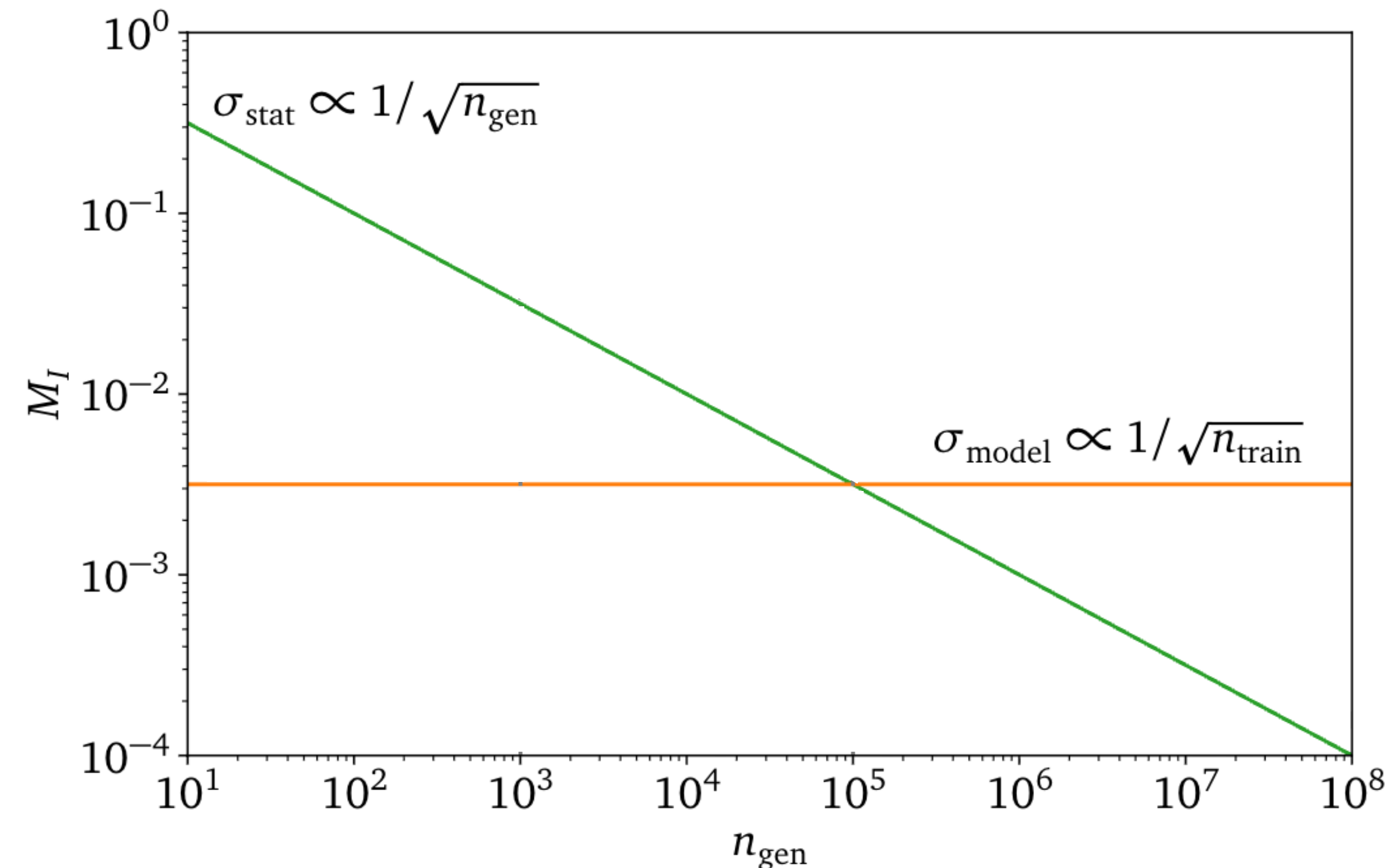
How many generative points can I sample from the model?

$$\sigma_{\text{gen}}^2 = \sigma_{\text{model}}^2 + \sigma_{\text{stat}}^2$$

$\sigma_{\text{model}} > \sigma_{\text{stat}}$: new points stop being useful

$$\sigma_{\text{stat}}(n) \Big|_{n=n_{\text{equiv}}} \stackrel{!}{=} \sigma_{\text{model}}$$

n_{equiv} : size of true data set with same stat. uncertainty as generalization uncertainty



How many generative points can I sample from the model?

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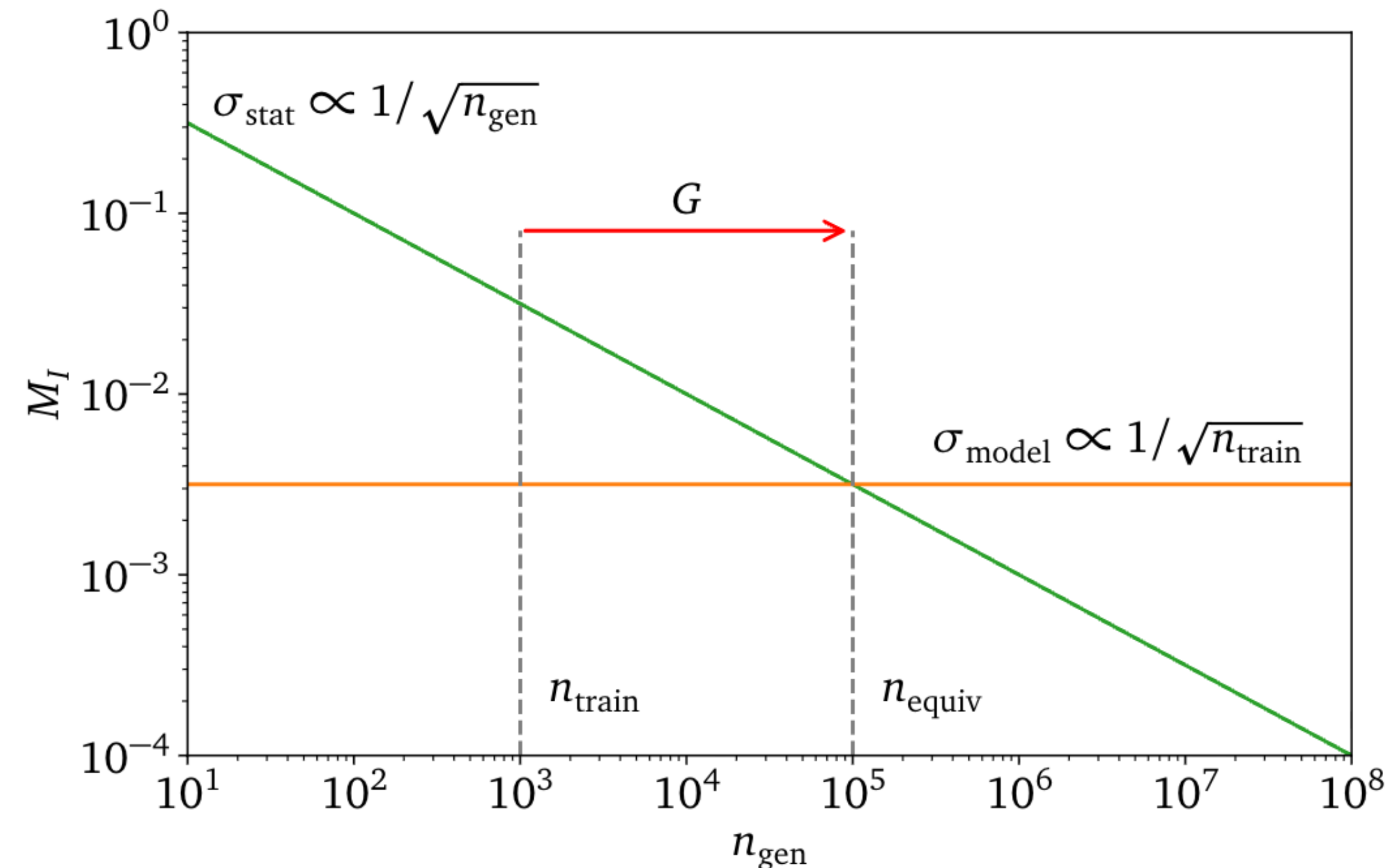
$$\sigma_{\text{stat}}(n) \Big|_{n=n_{\text{equiv}}} \stackrel{!}{=} \sigma_{\text{model}}$$

n_{equiv} : size of true data set with same stat. uncertainty as generalization uncertainty

$n_{\text{equiv}} \leq n_{\text{train}}$: No Amplification

$n_{\text{equiv}} > n_{\text{train}}$: Amplification

$$G = \frac{n_{\text{equiv}}}{n_{\text{train}}} : \text{Amplification factor}$$



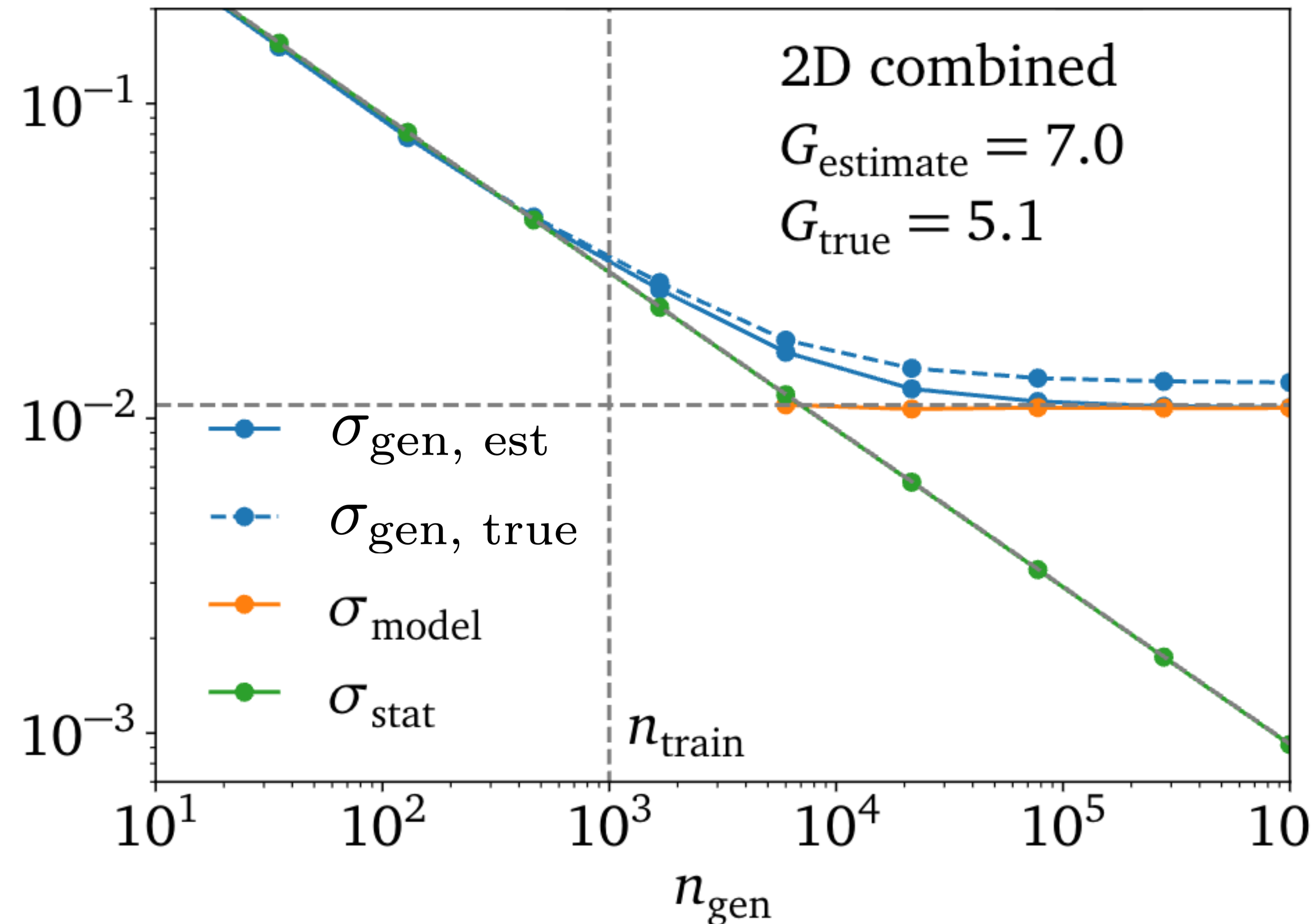
Example: Gaussian Ring Radius

- ▶ Plot σ_{gen}
- ▶ Get $\sigma_{\text{stat}}(n)$ from falling section
- ▶ Get σ_{model} from asymptotic part

$$\sigma_{\text{stat}}(n) \Big|_{n=n_{\text{equiv}}} \stackrel{!}{=} \sigma_{\text{model}}$$

$$G = \frac{n_{\text{equiv}}}{n_{\text{train}}}$$

- ▶ Estimated G agrees with truth



How to get σ_{gen} ?

► Uncertainty quantification?

► Only σ_{model} not σ_{stat}

→ Need metric $M [D_{\text{gen}}^n, p_{\text{true}}]$ agreement (generated) set vs. true density

$$M [D_{\text{true}}^n, p_{\text{true}}] \approx \sigma_{\text{stat}}$$

$$M [D_{\text{gen}}^n, p_{\text{true}}] \Big|_{n_{\text{gen}} \rightarrow \infty} \rightarrow \sigma_{\text{model}}$$

$$\begin{array}{ccc} \sigma_{\text{stat}}(n) \Big|_{n=n_{\text{equiv}}} & \stackrel{!}{=} & \sigma_{\text{model}} \\ & \Updownarrow & \\ M [D_{\text{true}}^n, p_{\text{true}}] \Big|_{n=n_{\text{equiv}}} & \stackrel{!}{=} & M [D_{\text{gen}}^n, p_{\text{true}}] \Big|_{n_{\text{gen}} \rightarrow \infty} \end{array}$$

First Metric: Averaging Amplification

- Fractions inside phase space region V

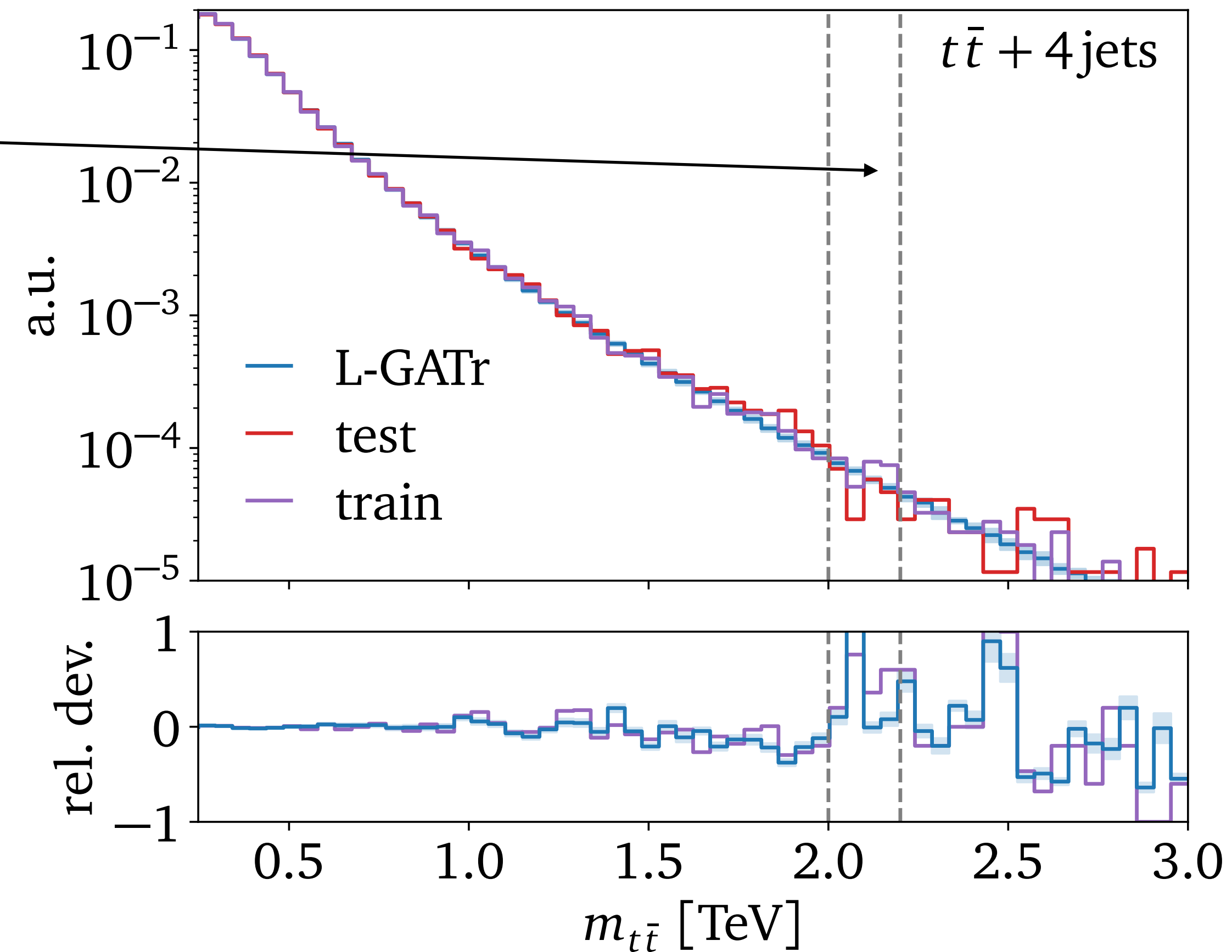
$$I = \int_V dx p_{\text{true}}(x)$$

$$\bar{I} = \frac{1}{n_{\text{gen}}} \sum_{x \in D_{\text{gen}}^{n_{\text{gen}}}} \mathbf{1}_{x \in V}$$

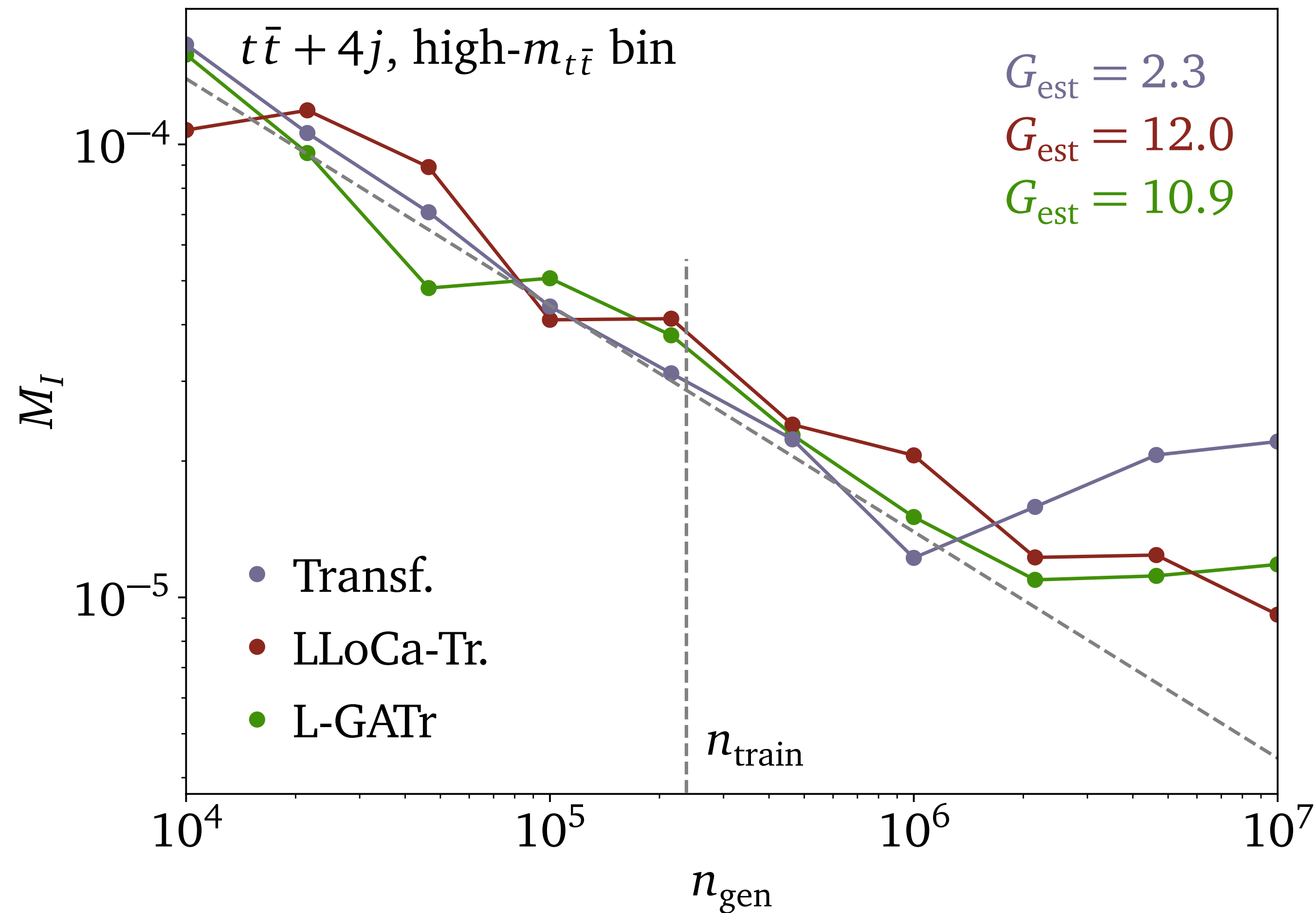
- Expected difference as metric

$$M_I [D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}}] = \langle [I(p_{\text{true}}) - \bar{I}(D_{\text{gen}}^{n_{\text{gen}}})]^2 \rangle$$

- Estimate this variance via BNN



Example: Di-Top + 4 jet events



Second Metric: Differential Amplification

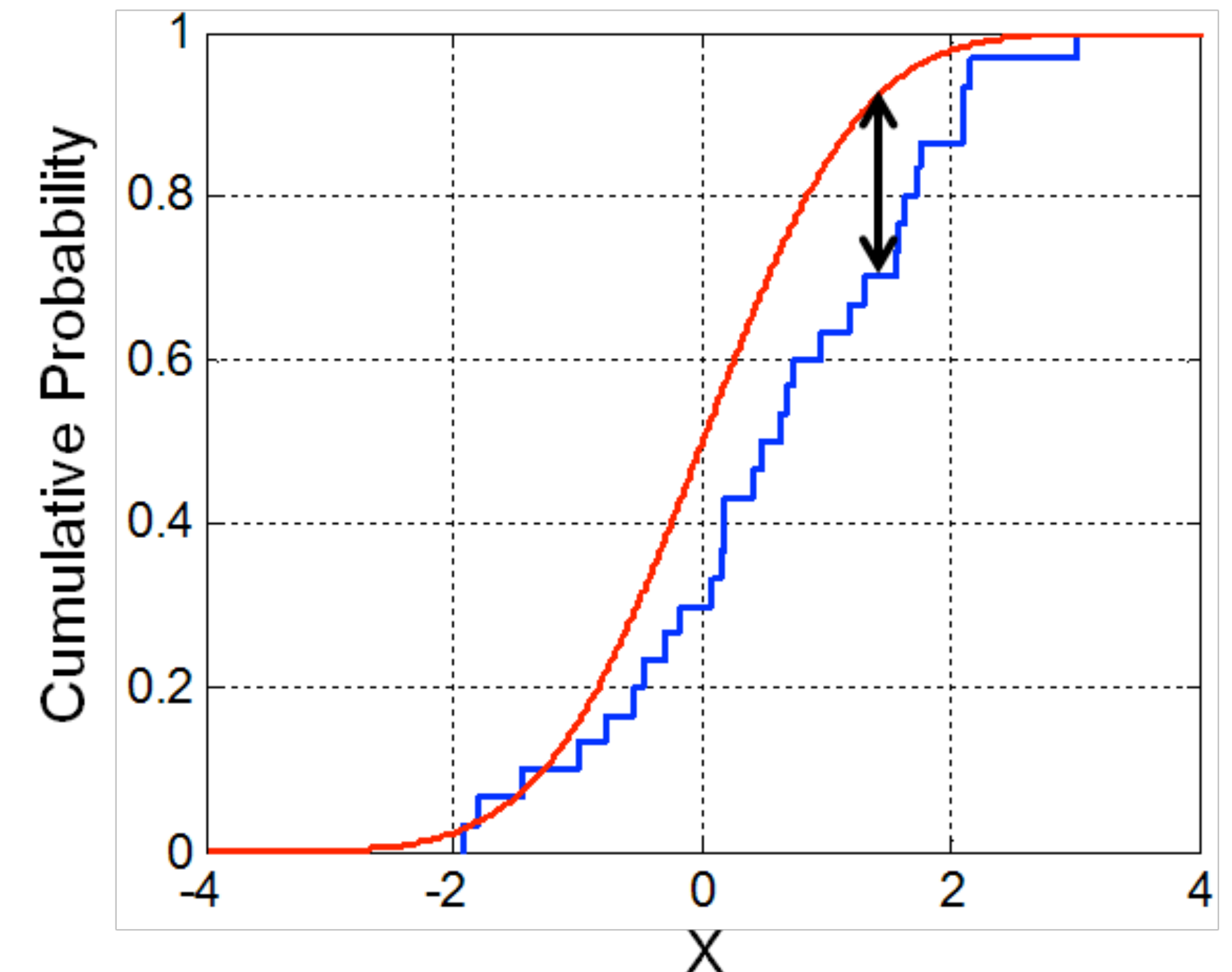
- Approximate unknown distribution with data sample

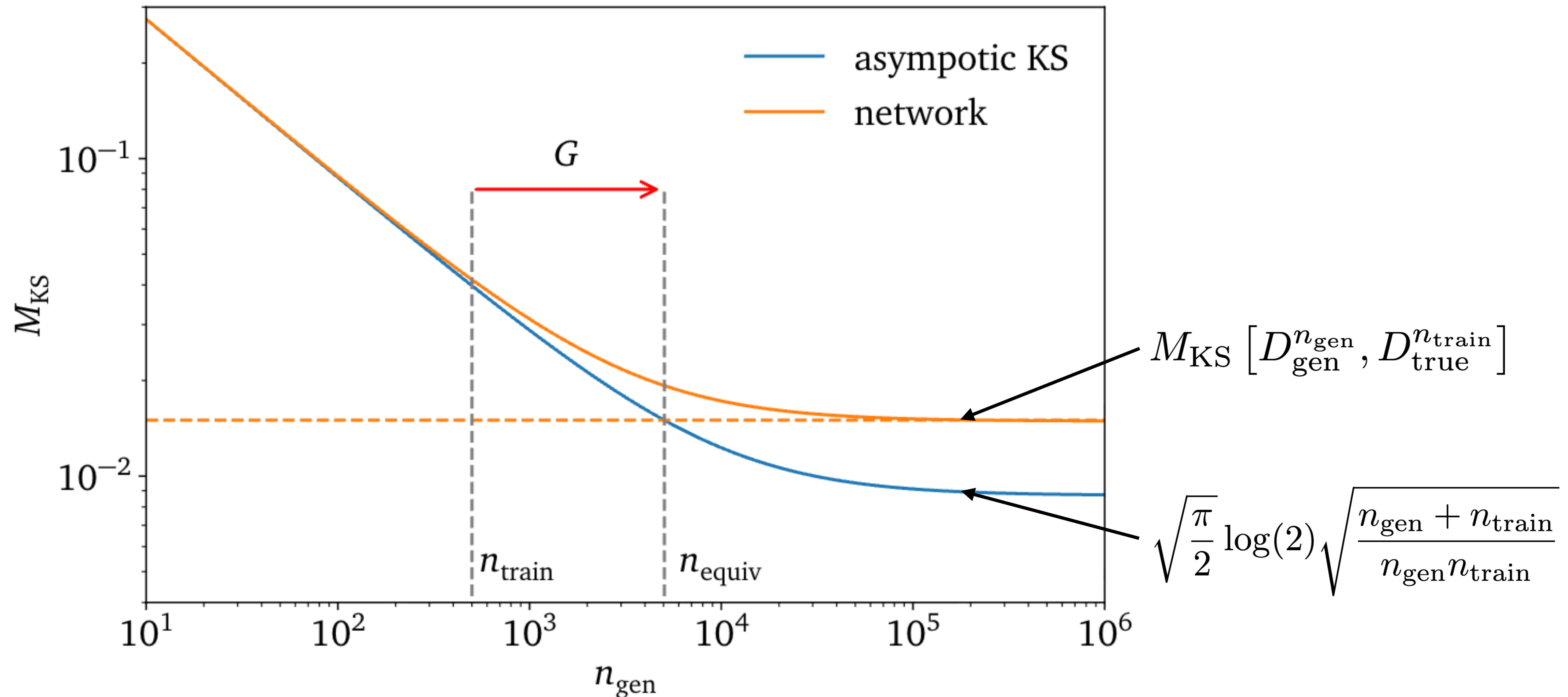
$$M[D_{\text{true}}^n, D_{\text{true}}^{n_{\text{train}}}] \approx M[D_{\text{true}}^n, p_{\text{true}}] \quad \text{with} \quad D_{\text{true}}^{n_{\text{train}}} \sim p_{\text{true}}$$

$$M[D_{\text{gen}}^{n_{\text{gen}}}, D_{\text{true}}^{n_{\text{train}}}] \approx M[D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}}]$$

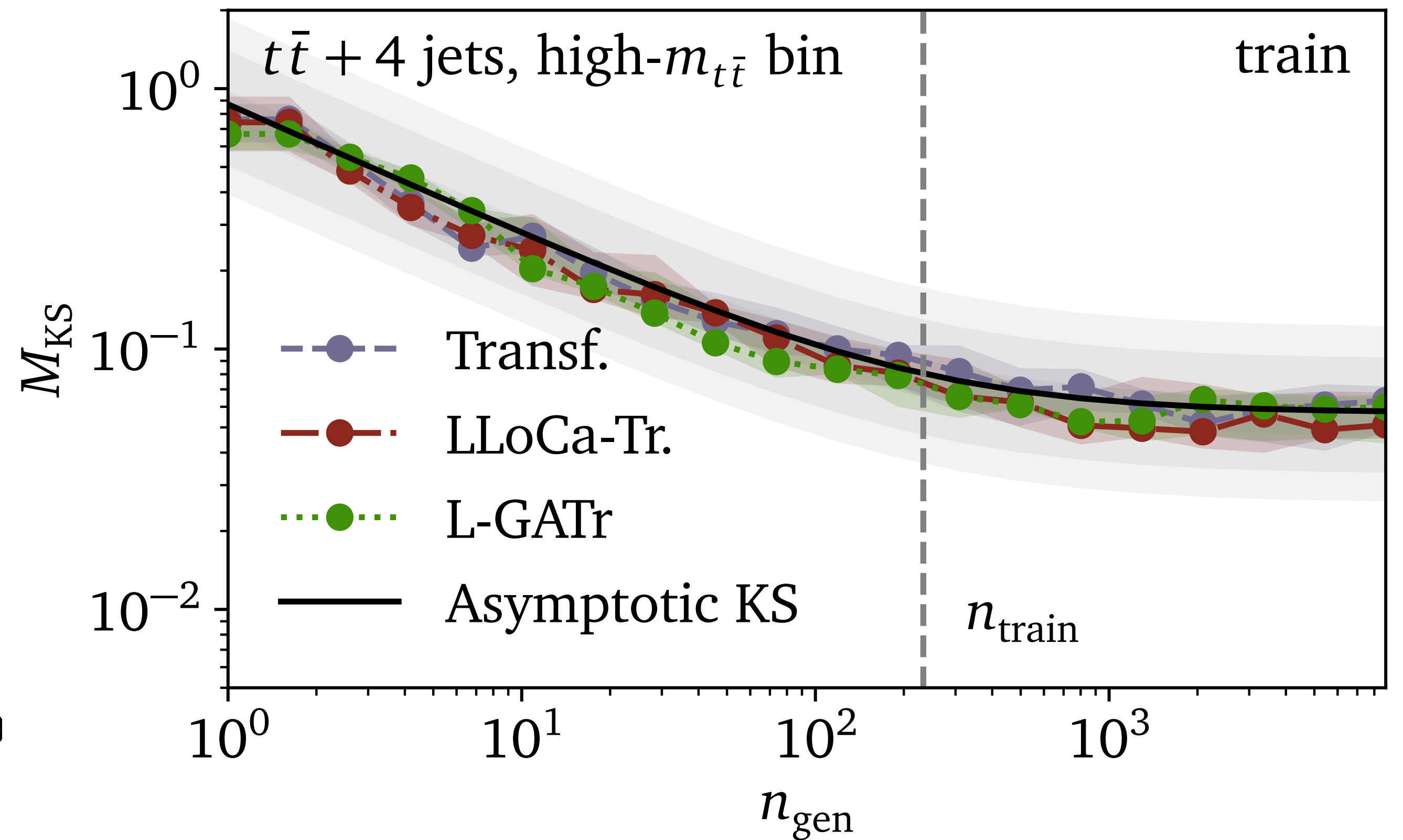
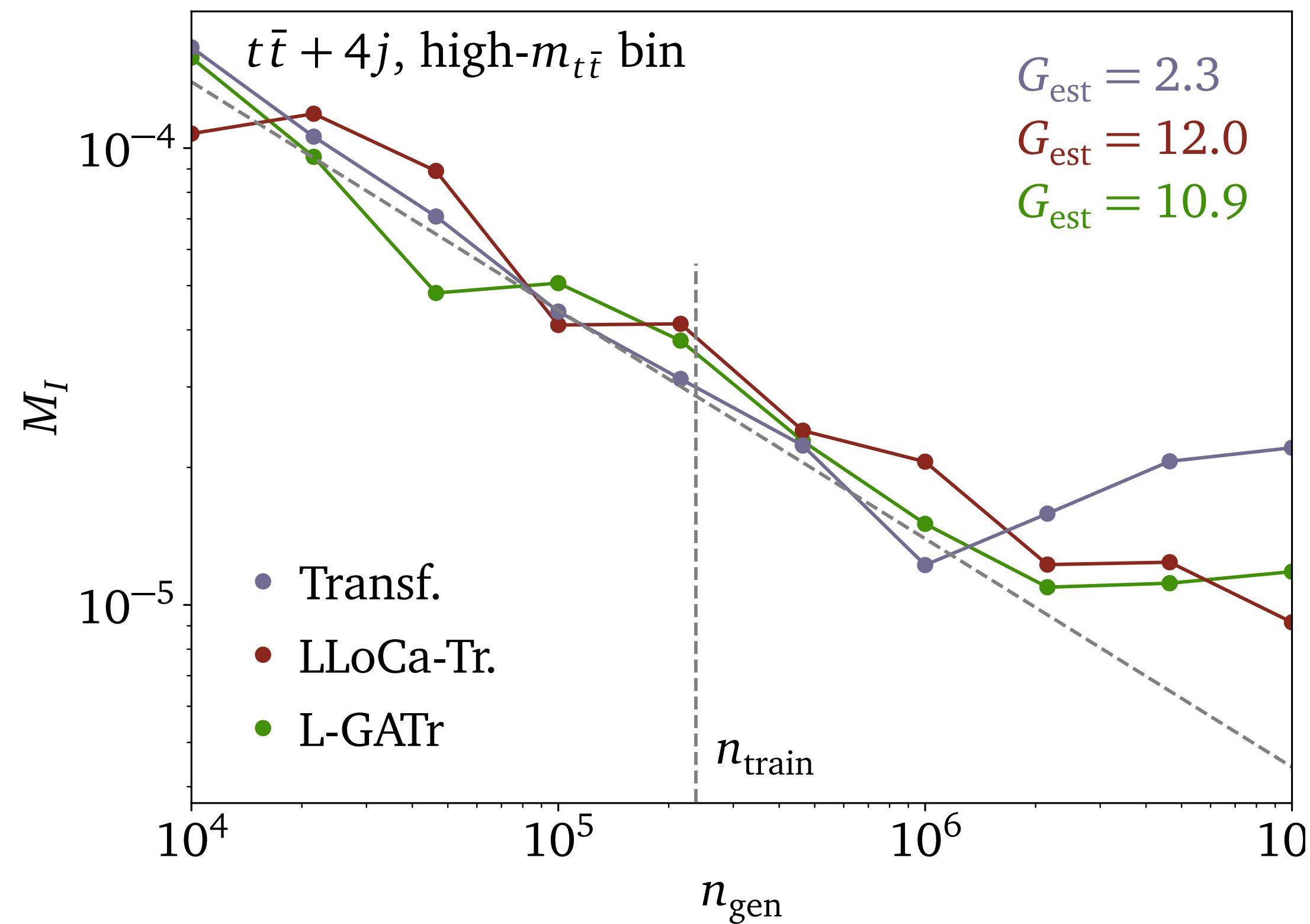
- Use two sample Kolmogorov Smirnov test
- Has analytical expectation value

$$\langle M_{\text{KS}} [D_{\text{true}}^n, D_{\text{true}}^m] \rangle = \sqrt{\frac{\pi}{2}} \log(2) \sqrt{\frac{n+m}{nm}}$$





Example: Di-Top + 4 jet events with both methods



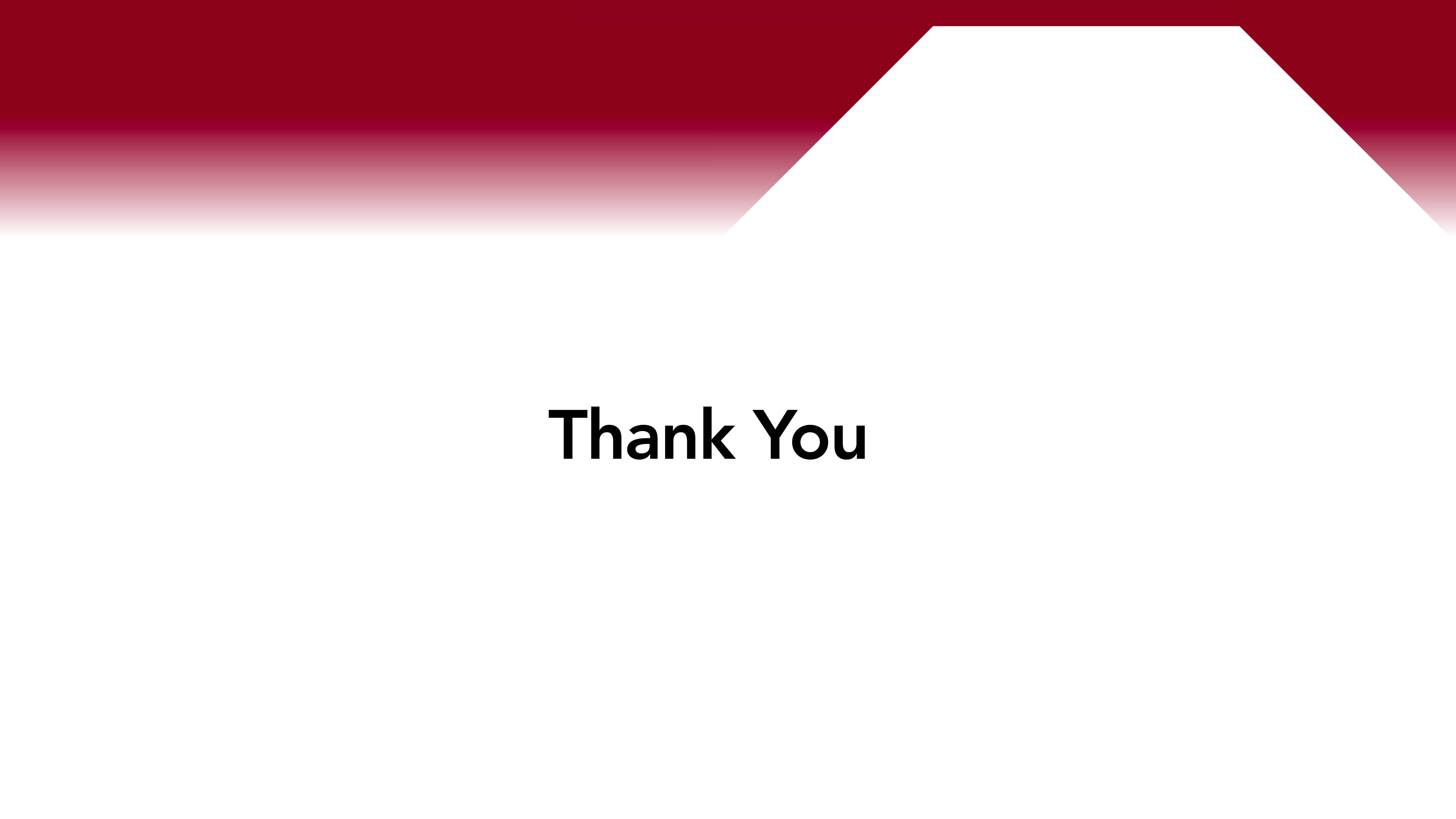
- ▶ **Amplification Investigation**

- ▶ Generative networks can sample beyond training data
- ▶ Quantify by how much
- ▶ Core to generative uncertainties

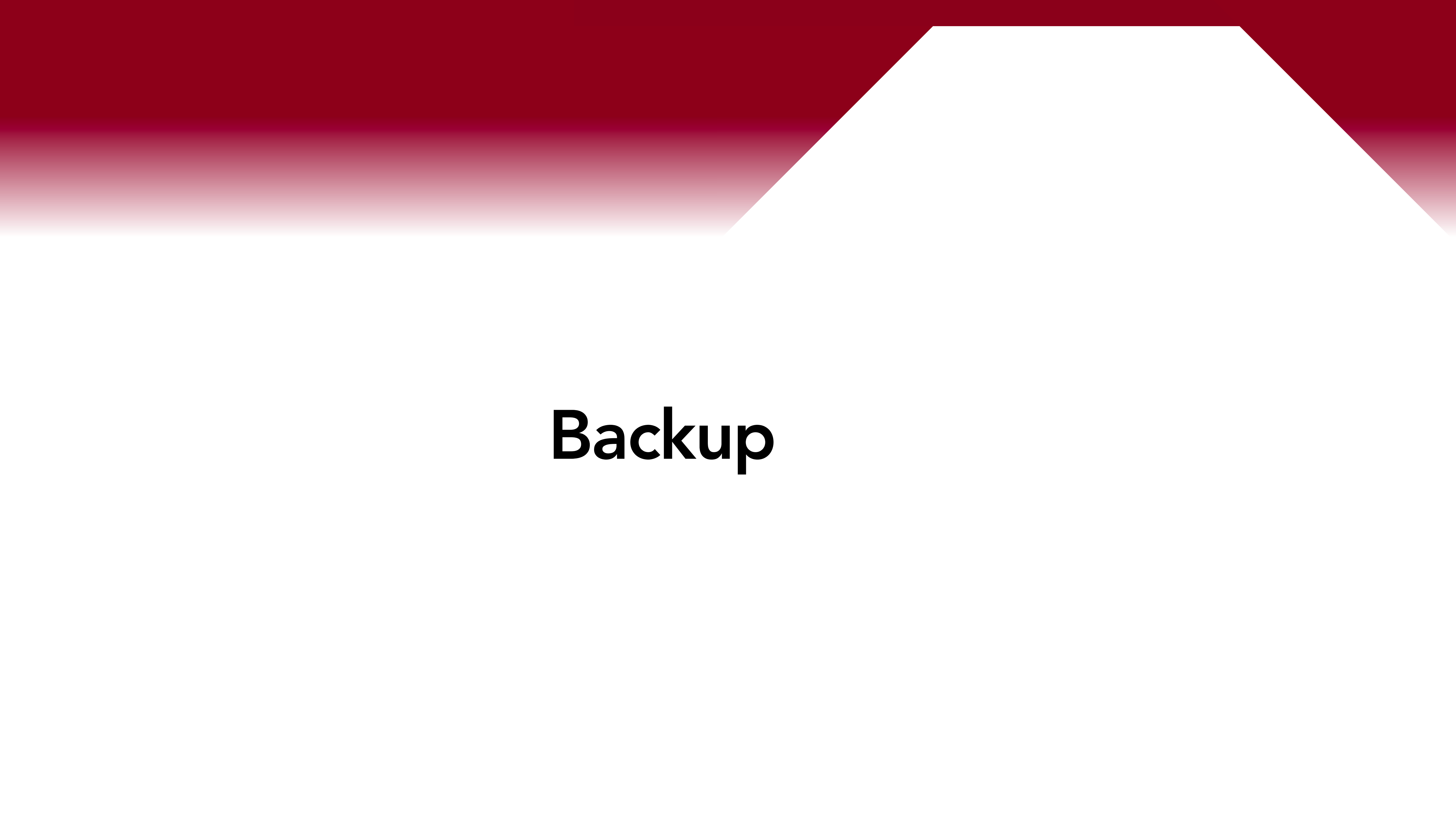
- ▶ **Enables generative approaches in HEP**

- ▶ Amplification key for generative simulations
- ▶ Simulation-based inference, generative unfolding need uncertainties

- ▶ **ML methods bring unprecedented precision**
 - ▶ LHC environment highly complex
 - ▶ $t\bar{t}H$, CP violation measurements impossible without
 - ▶ Directly enabled by ML
- ▶ **Fundamental physics understanding**
 - ▶ $t\bar{t}H$: early universe Higgs potential
 - ▶ CP violation: matter-antimatter asymmetry, baryogenesis



Thank You



Backup

► Example Metric: Averaging Amplification

- Fractions inside phase space region V :

$$I = \int_V dx p_{\text{true}}(x)$$

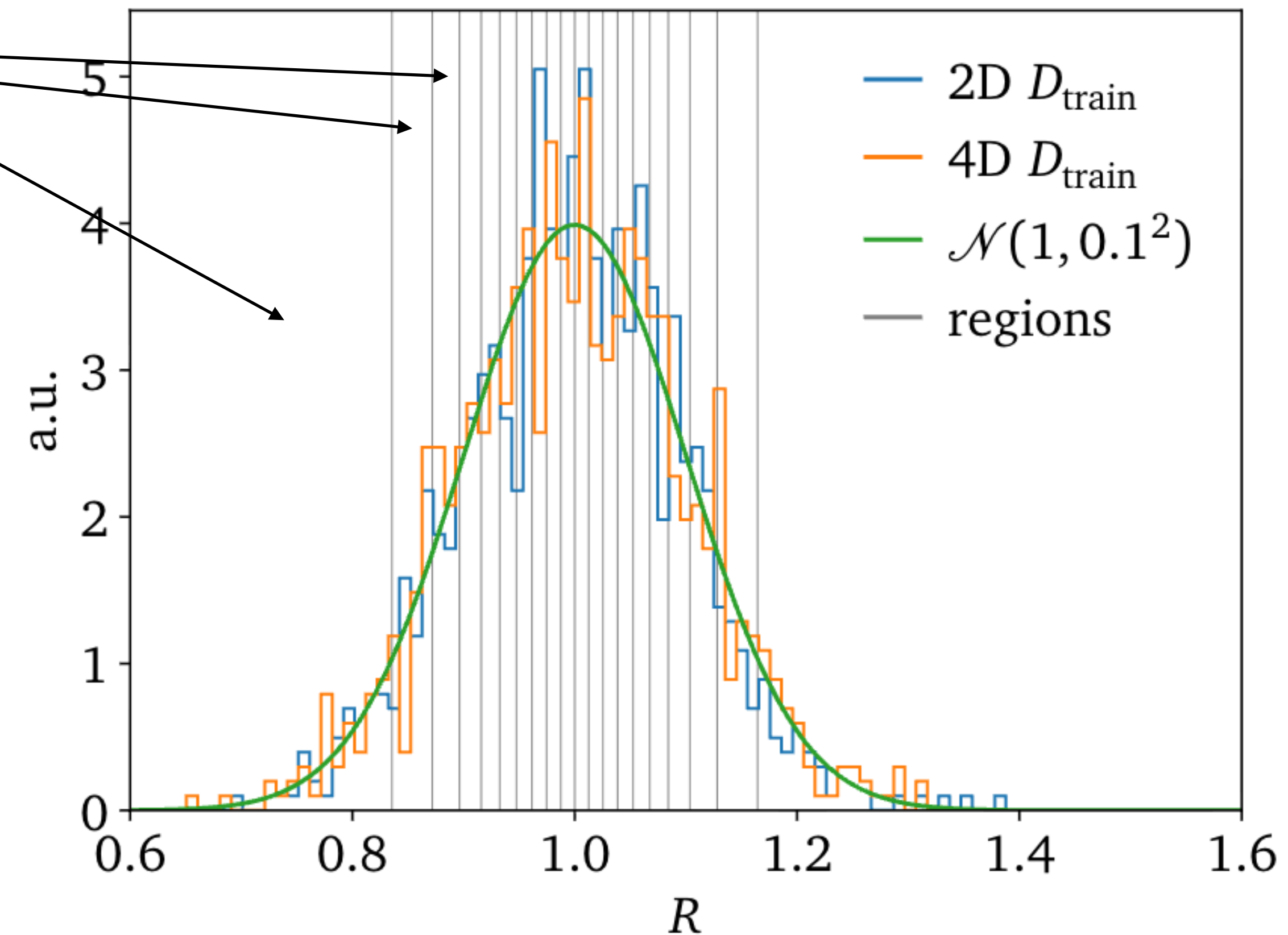
$$\bar{I} = \frac{1}{n_{\text{gen}}} \sum_{x \in D_{\text{gen}}^{n_{\text{gen}}}} \mathbf{1}_{x \in V}$$

- Expected difference as metric

$$M \left[D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}} \right] = \left\langle \left[I(p_{\text{true}}) - \bar{I}(D_{\text{gen}}^{n_{\text{gen}}}) \right]^2 \right\rangle$$

- Estimate via Bayesian Network variance in V

Radius of Gaussian Ring



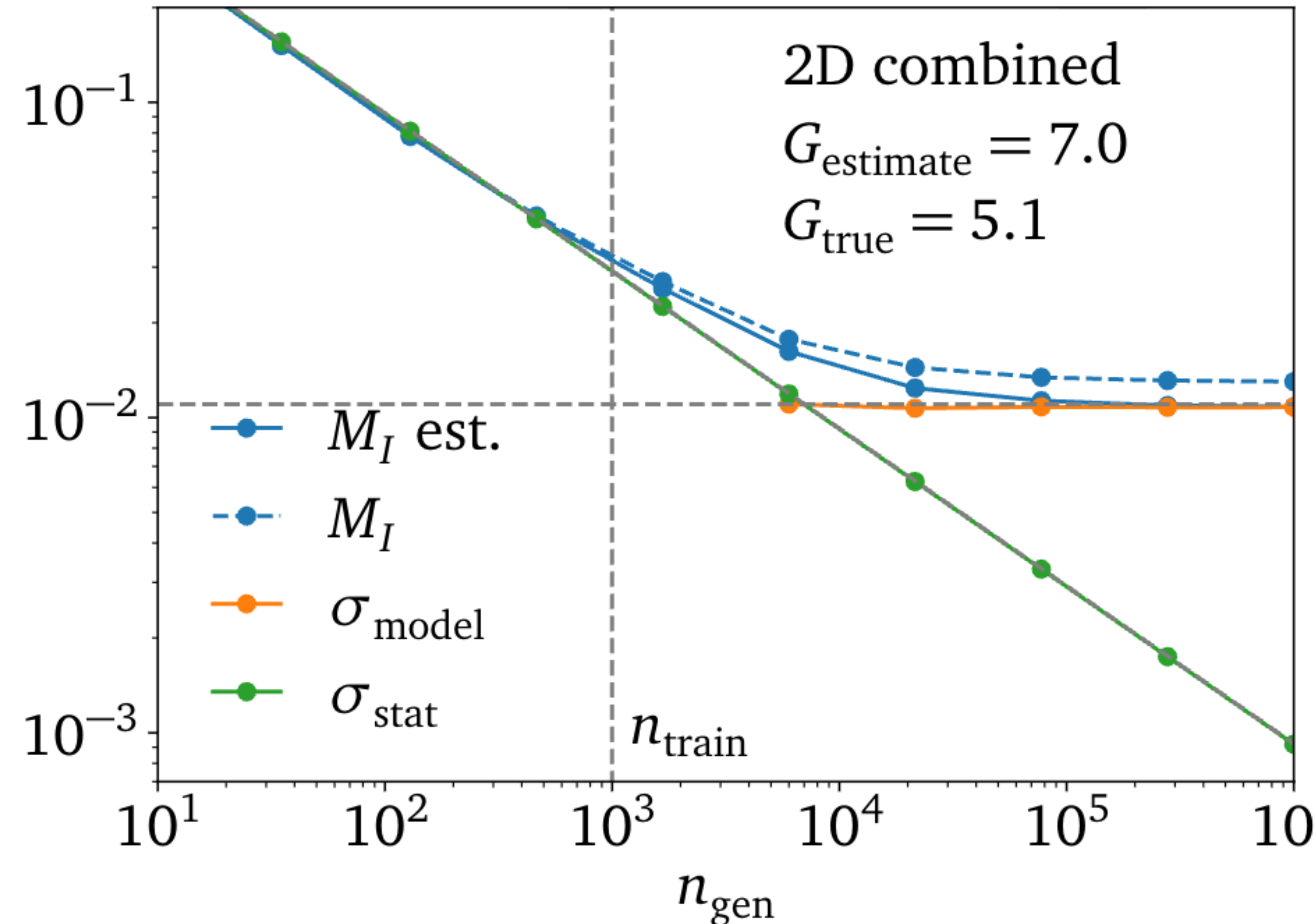
► Example: Gaussian Ring Radius

- Plot $M_I \left[D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{data}} \right] (n_{\text{gen}})$
- Get $\sigma_{\text{stat}}(n)$ from falling section
- Get σ_{model} from asymptotic part
- Combine regions V_i

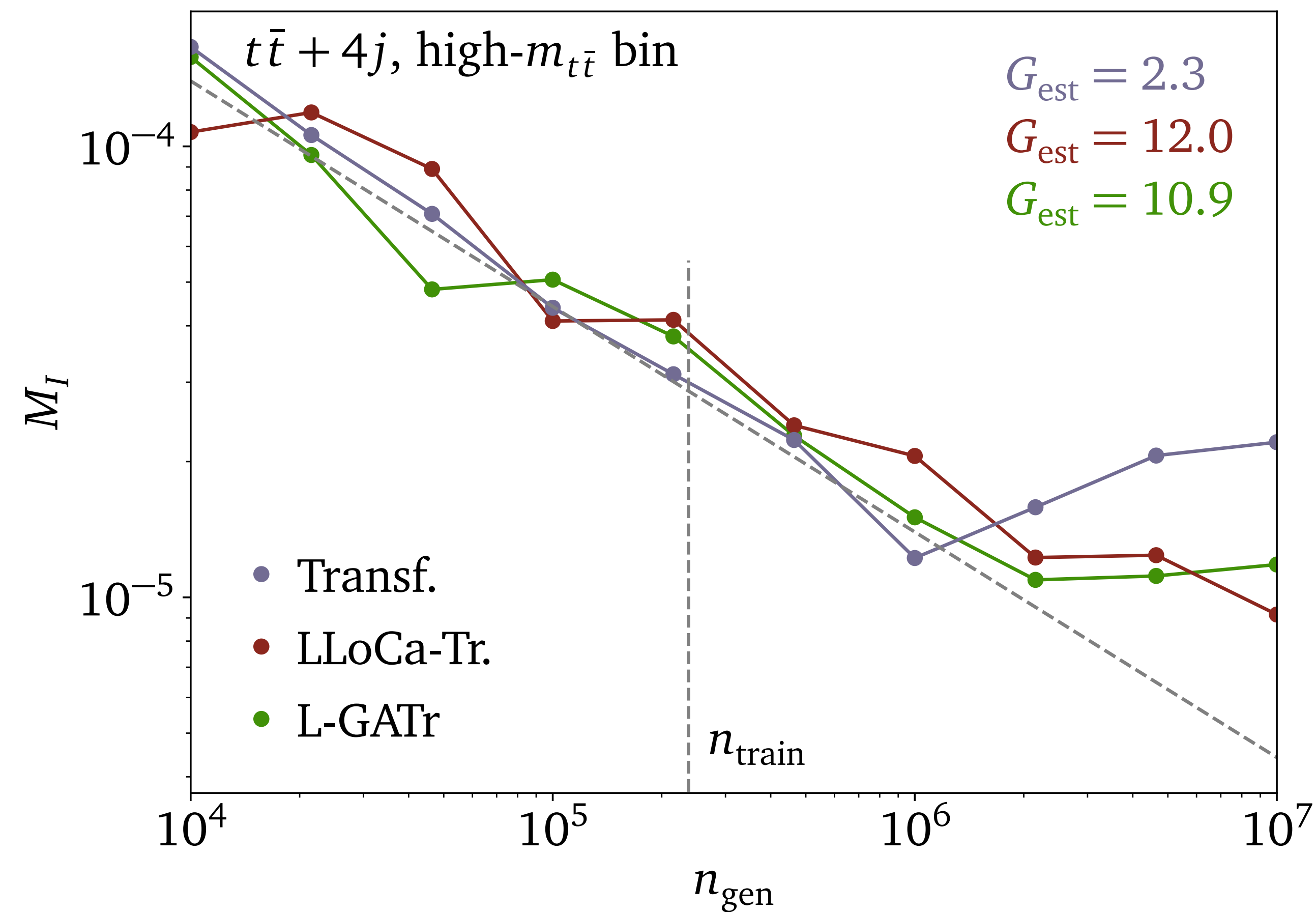
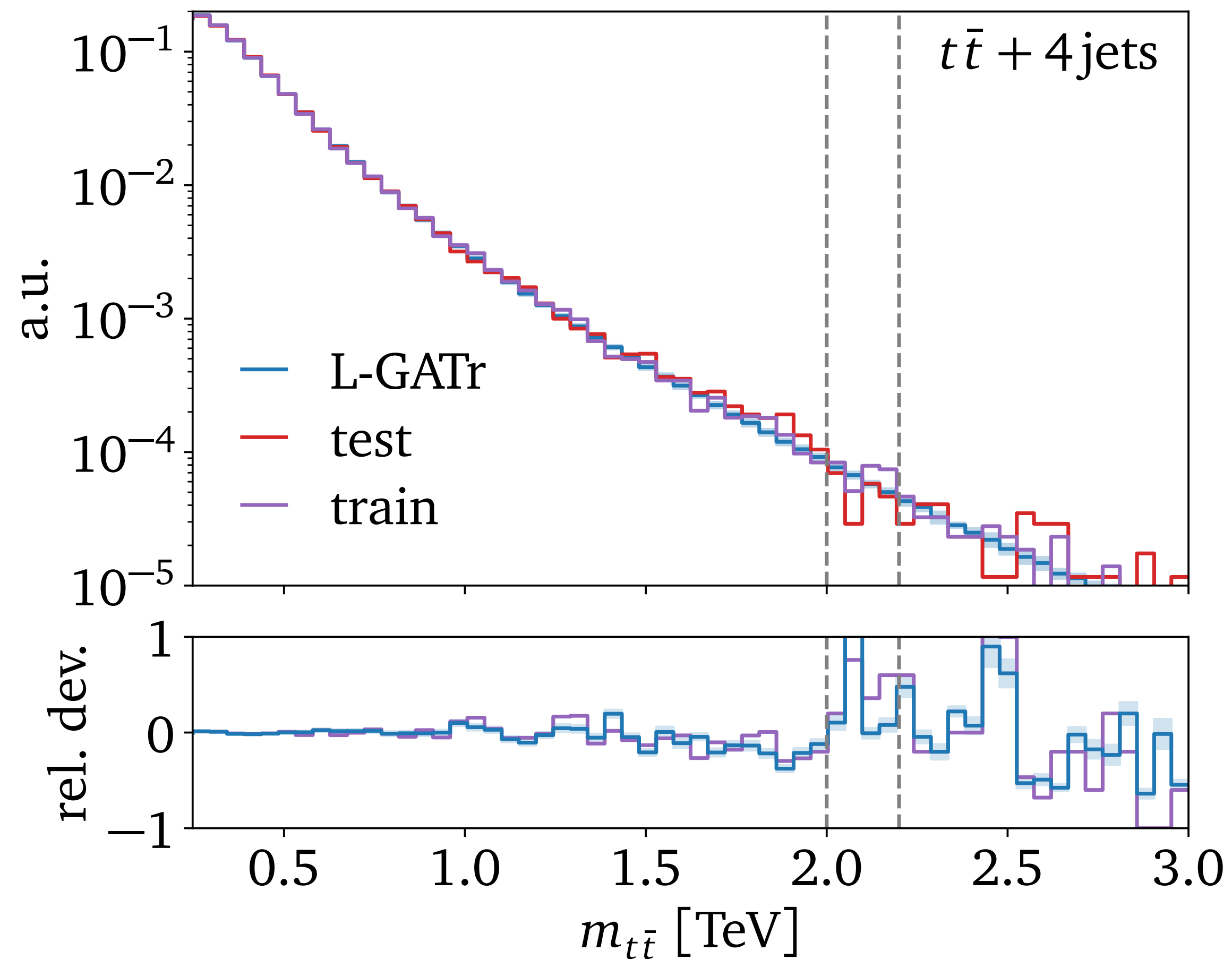
$$\sigma_{\text{stat}}^2 = \sum_i^{n_v} \sigma_{\text{stat}, V_i}^2 \quad \sigma_{\text{model}}^2 = \sum_i^{n_v} \sigma_{\text{model}, V_i}^2$$

$$\sigma_{\text{stat}}(n_{\text{equiv}}) \stackrel{!}{=} \sigma_{\text{model}}$$

- Estimate G , agrees with truth

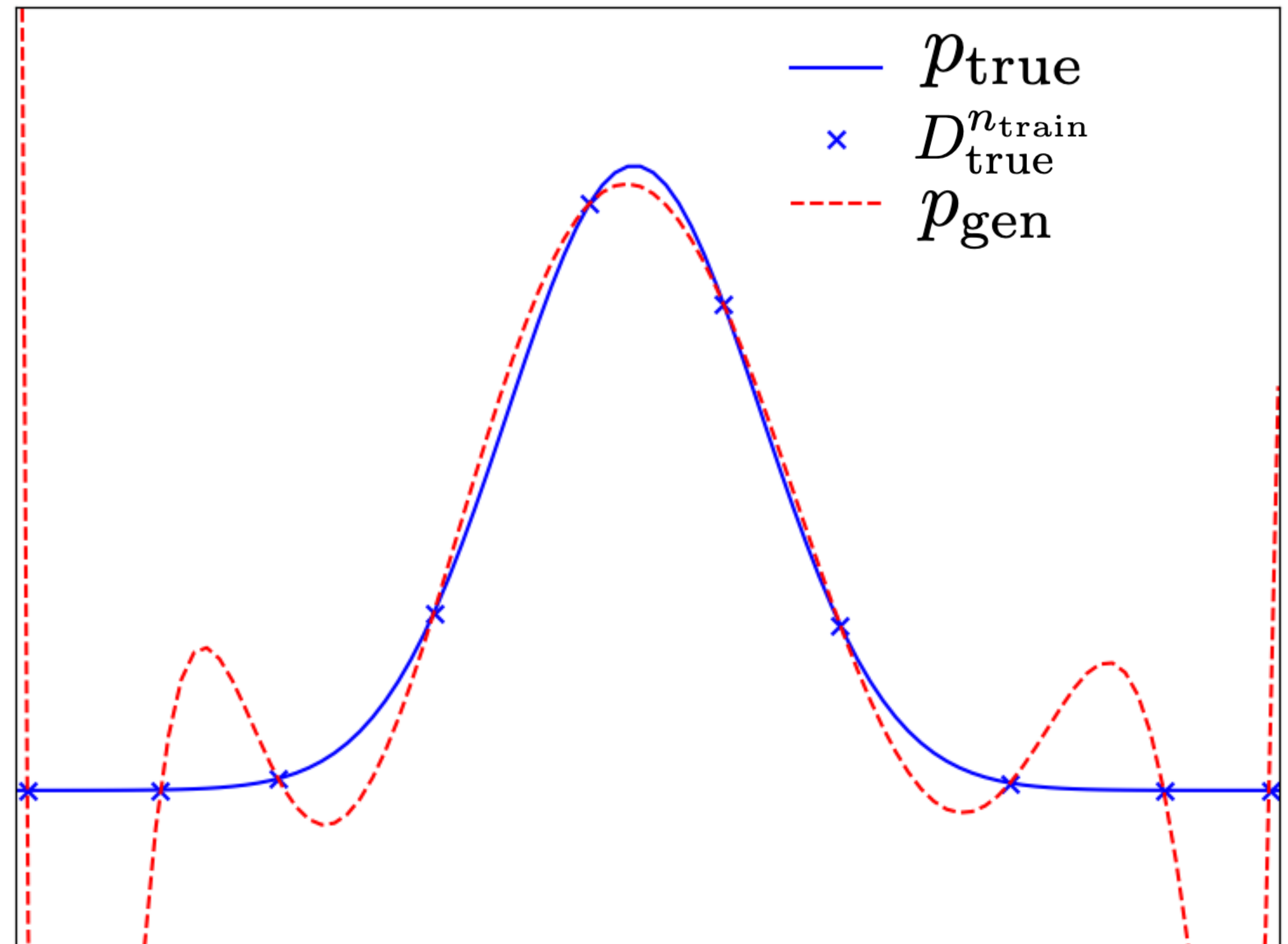


► Example: Di-Top + 4 jet events



► Generalization Uncertainty: Generative

- Cannot learn $p_{\text{gen}}(p_{\text{true}})$
- Instead $p_{\text{gen}}(D_{\text{true}}^{n_{\text{train}}})$
with $D_{\text{true}}^{n_{\text{train}}} \sim p_{\text{true}}$
- Extrapolation in Fourier space
- What happens at higher resolutions than in training?



- Measure for generalization uncertainty σ_{model}

$$\sigma_{\text{model}} \approx M[p_{\text{gen}}, p_{\text{true}}]$$

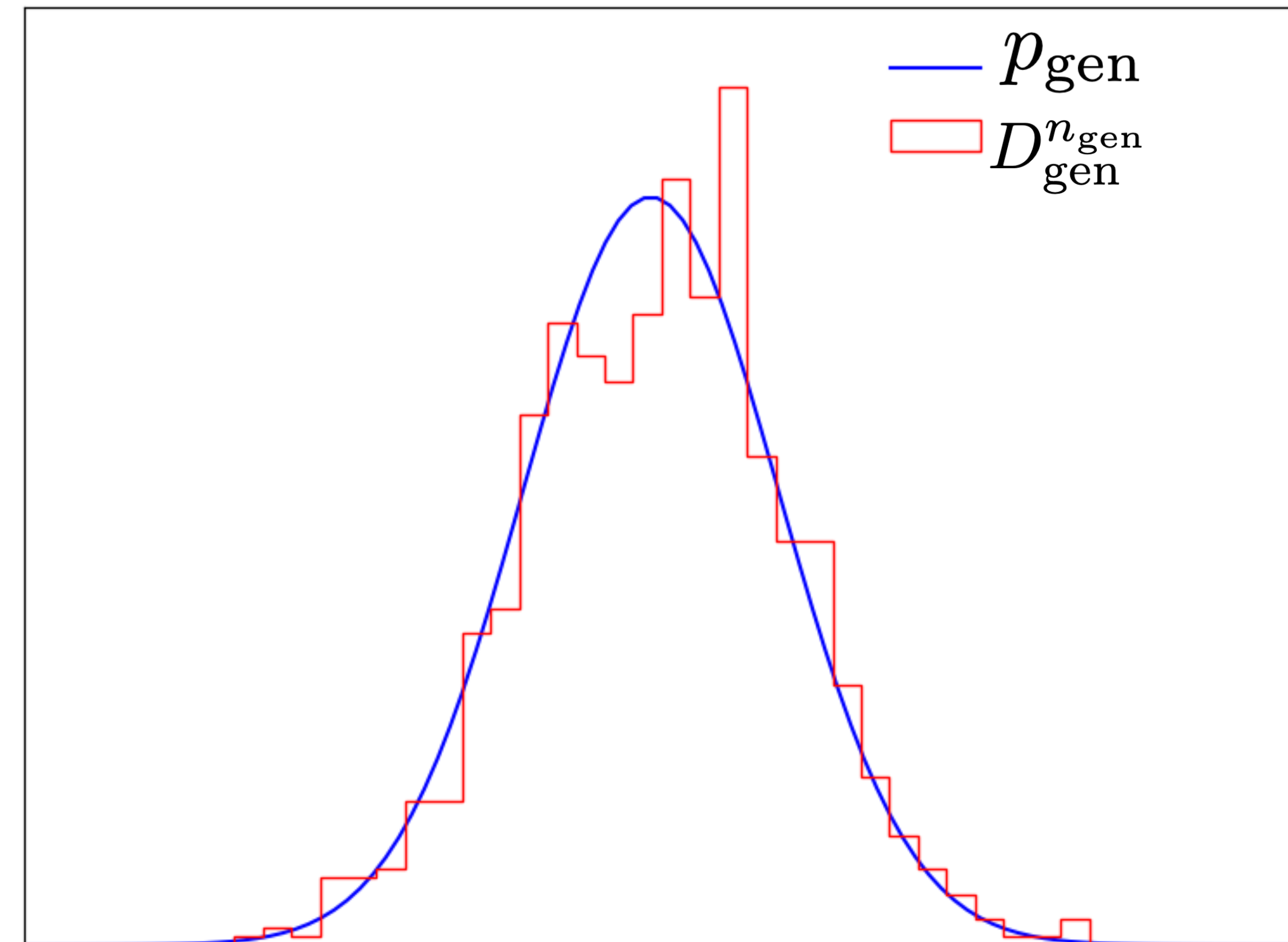
- With metric M

- p_{gen} intractable $\rightarrow$ approximate

$$D_{\text{gen}}^{n_{\text{gen}}} \sim p_{\text{gen}}$$

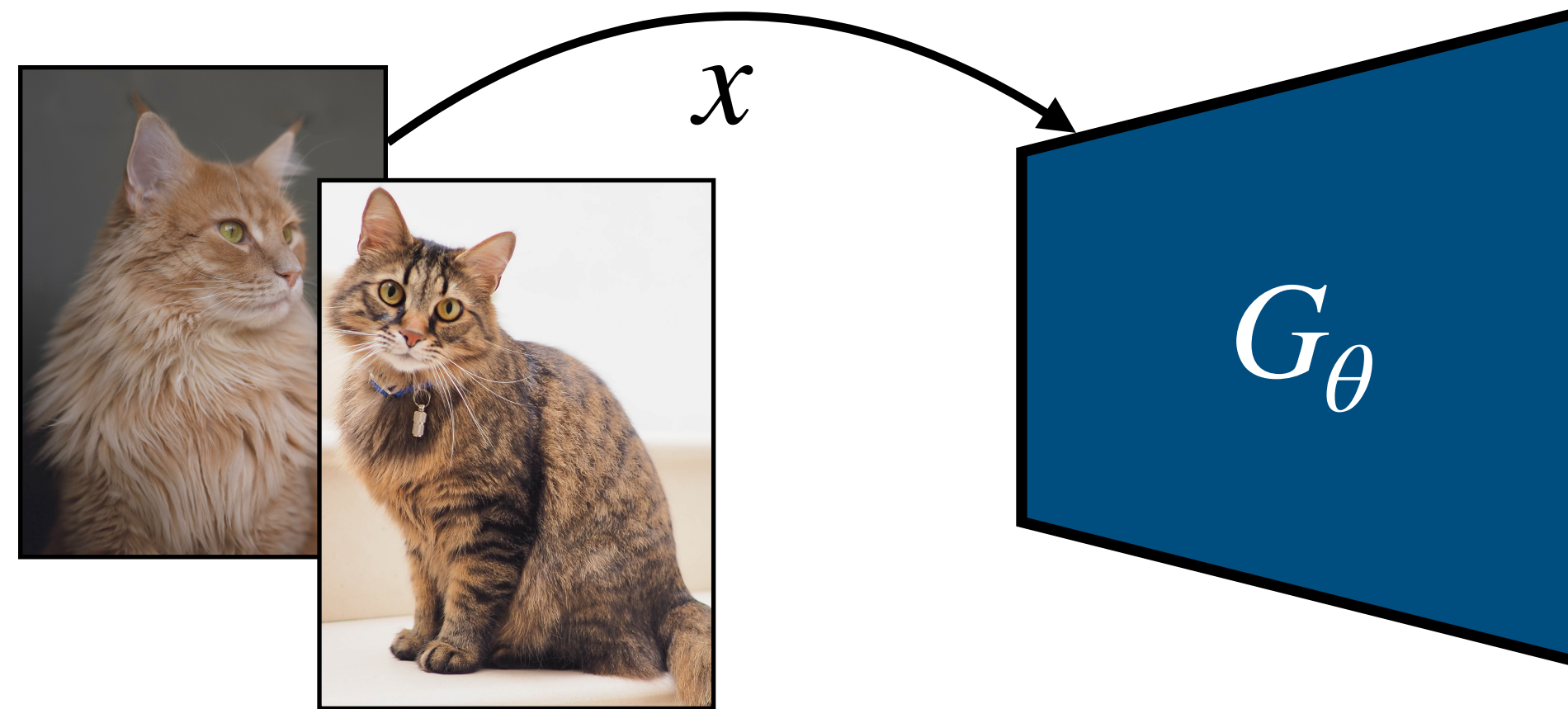
- Sample to arbitrary precision

$$\sigma_{\text{model}} \approx M[D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}}] \Big|_{n_{\text{gen}} \rightarrow \infty}$$



- **Generative networks**

- Trained on samples $x \sim p_{\text{true}}(x)$



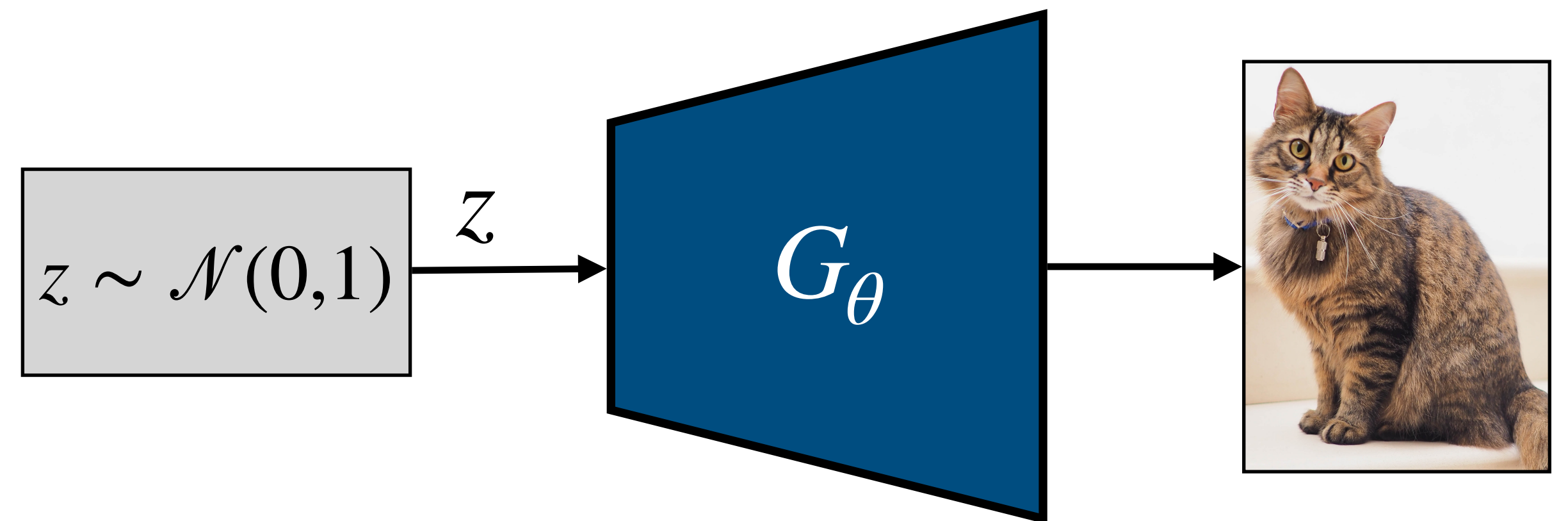
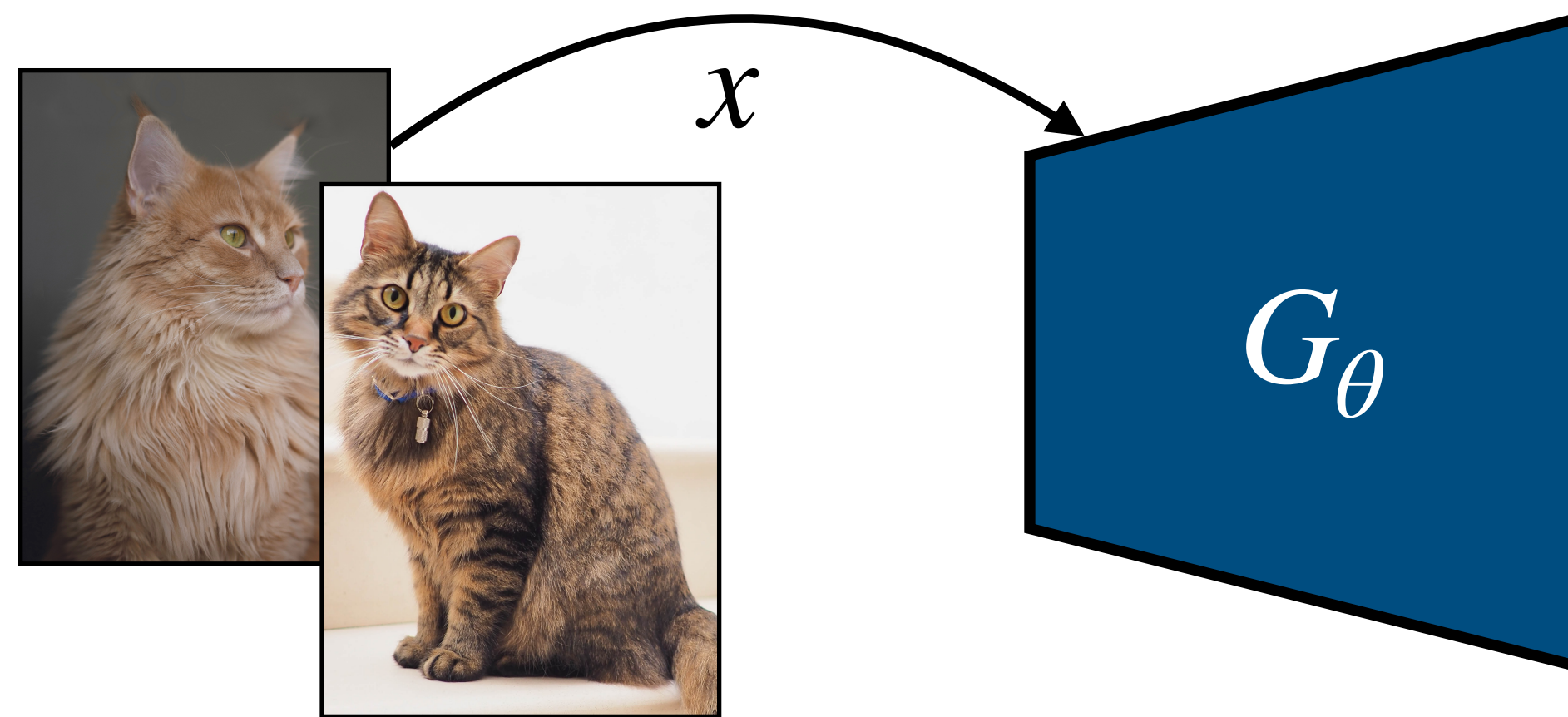
- **Generative networks**

- Trained on samples $x \sim p_{\text{true}}(x)$

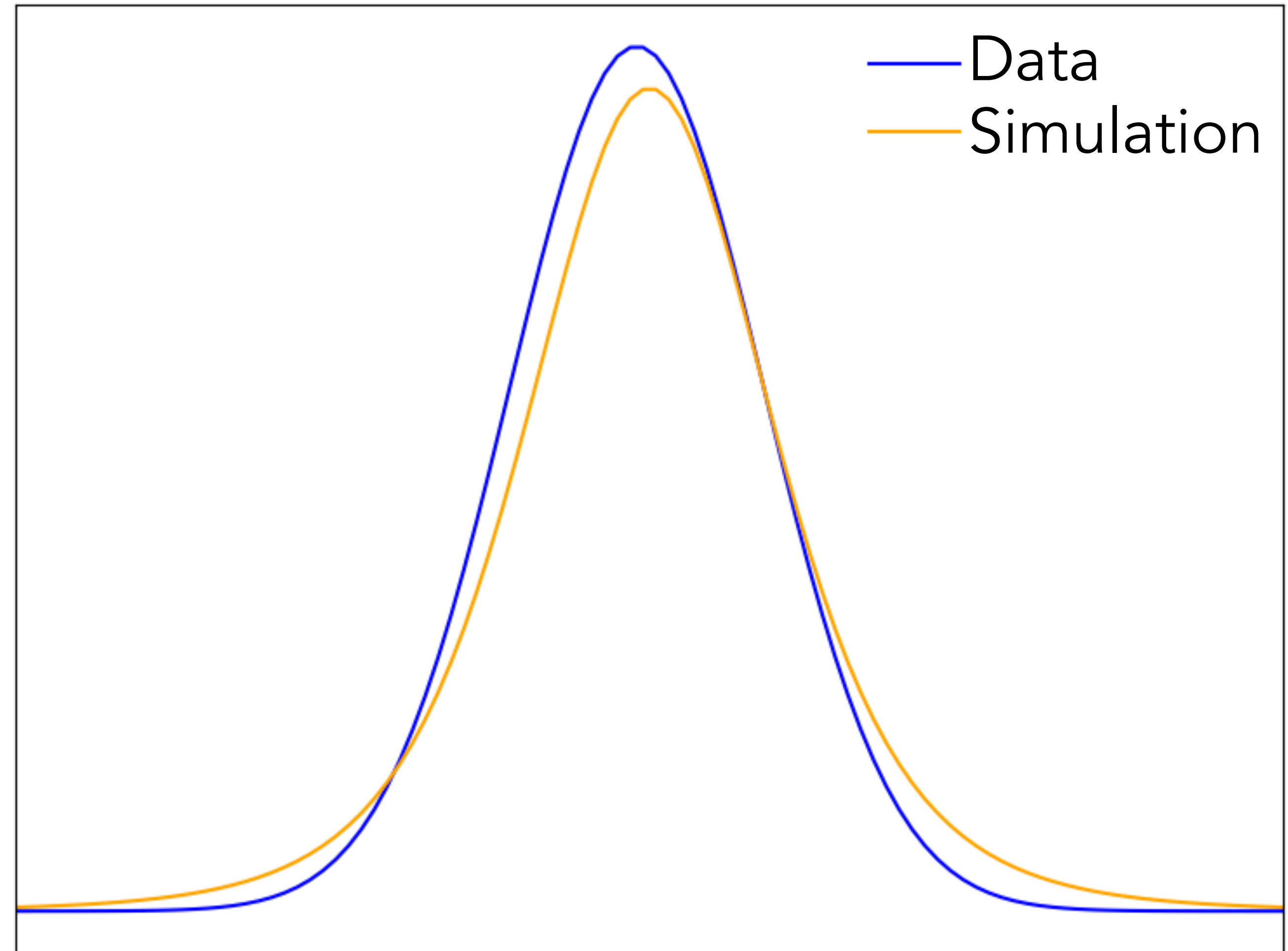
- Learns to map noise to $p_{\text{gen}}(x)$

$$z \sim \mathcal{N}(0, 1) \xrightarrow{G_{\theta}(z|c)} x \sim p_{\text{gen}}(x)$$

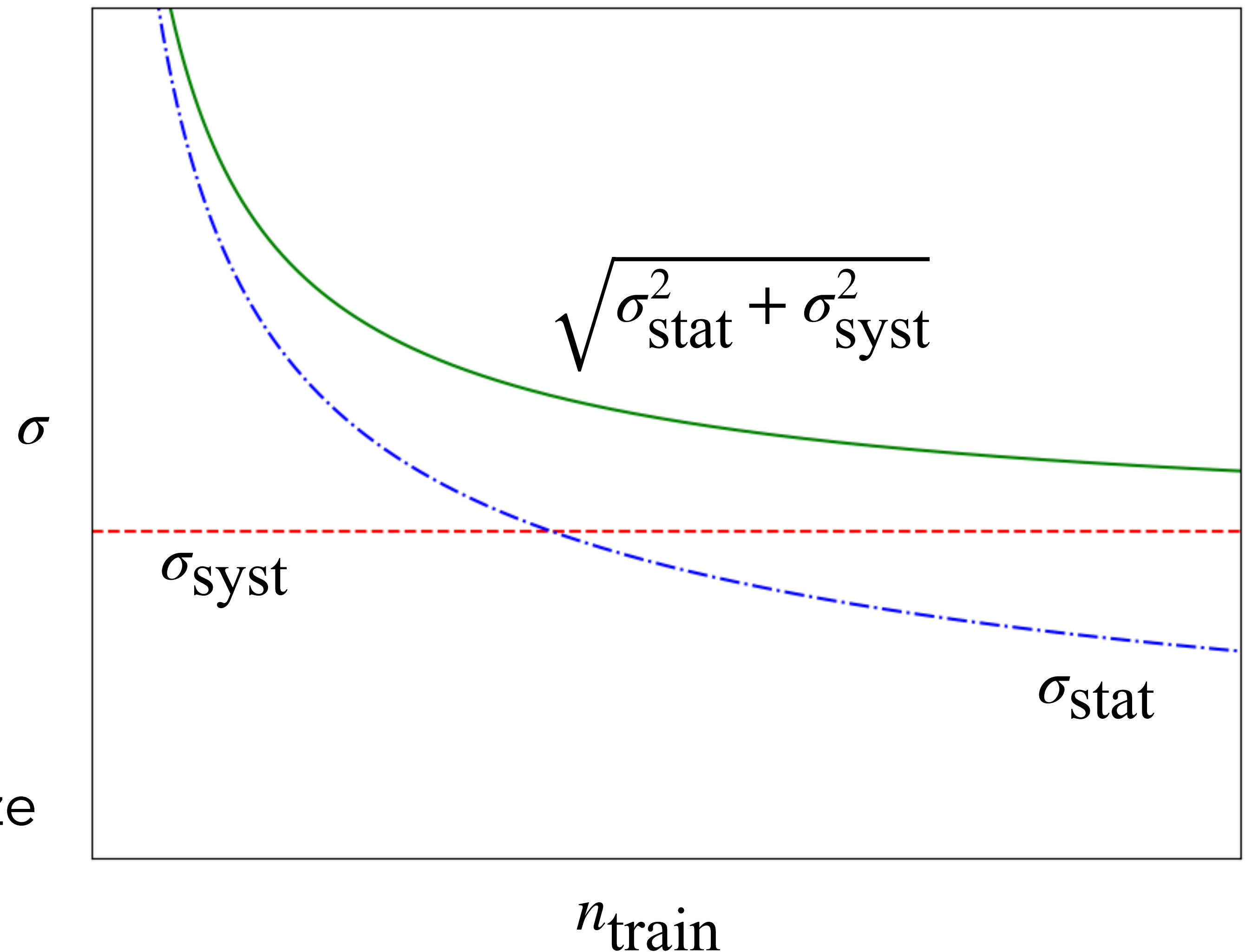
- Goal: $p_{\text{gen}}(x) \approx p_{\text{true}}(x)$



- ▶ **Statistical Uncertainty**
- ▶ **Systematic Uncertainty**
- ▶ **Generalization Uncertainty**
 - ▶ Inference data $\neq$ training data
 - ▶ Extrapolation outside training



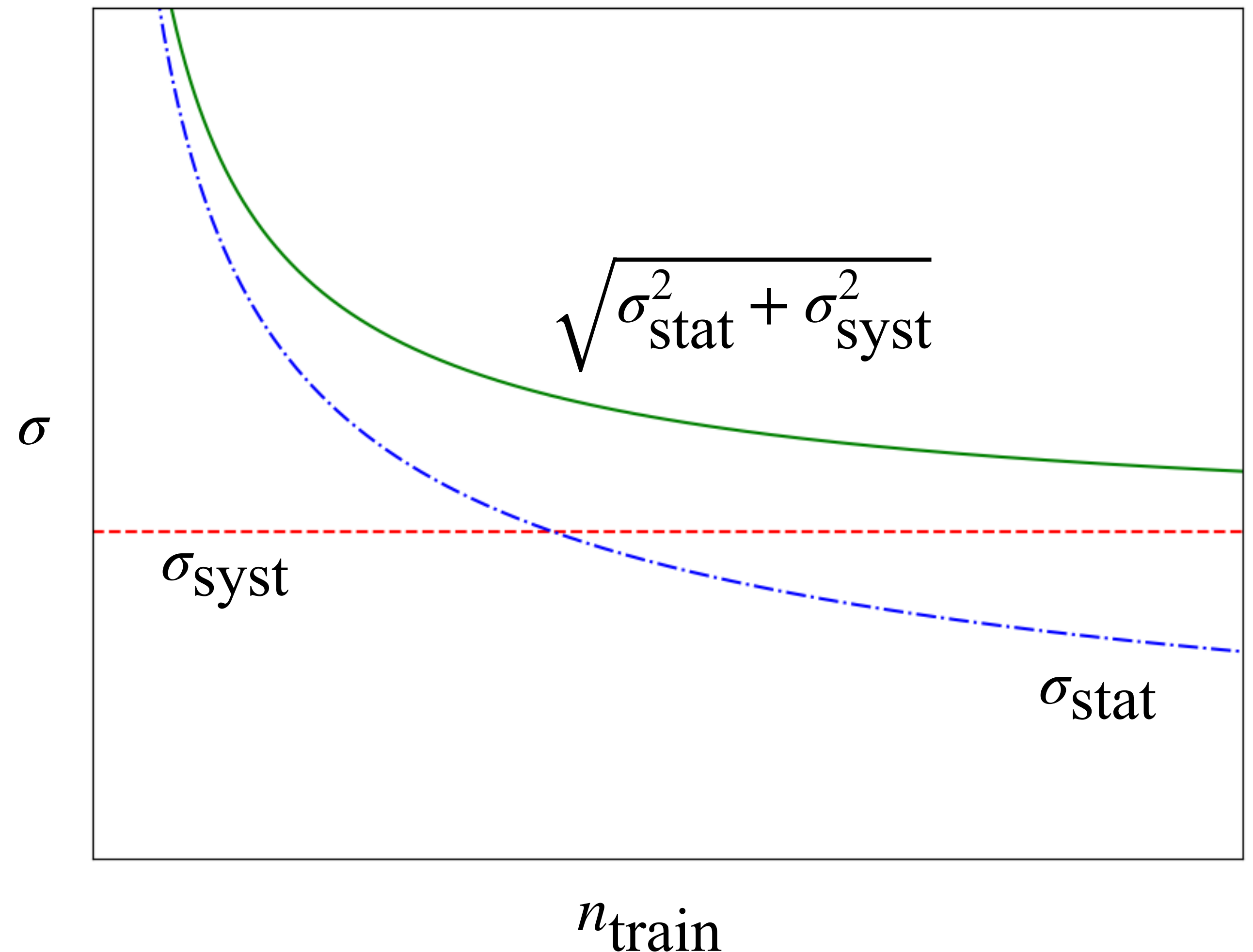
- ▶ **Statistical Uncertainty** σ_{stat}
 - ▶ Or epistemic, reducible
 - ▶ Scales with training data size
- ▶ **Systematic Uncertainty** σ_{syst}
 - ▶ Or aleatoric, irreducible
 - ▶ Independent of training data size



Physics needs uncertainties

Classifier model:

- ▶ **Statistical Uncertainty** σ_{stat}
 - ▶ Or epistemic, reducible
 - ▶ Scales with training data size
- ▶ **Systematic Uncertainty** σ_{syst}
 - ▶ Or aleatoric, irreducible
 - ▶ Independent of training data size



$$M\left[D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}}\right]$$

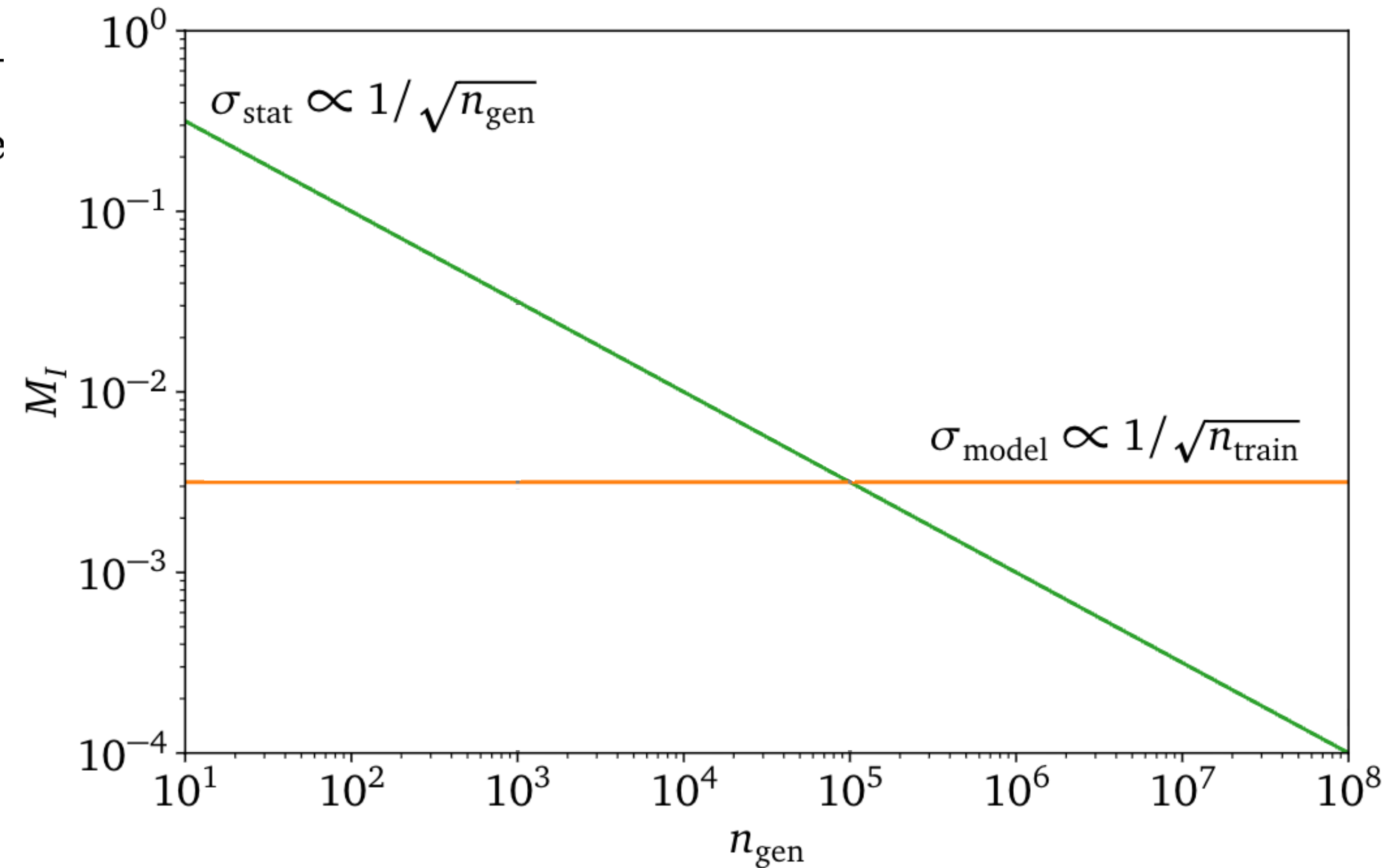
$$= \sqrt{\sigma_{\text{stat}}(n_{\text{gen}})^2 + \sigma_{\text{model}}(p_{\text{gen}}, p_{\text{true}})}$$

$\swarrow \propto \frac{1}{\sqrt{n_{\text{gen}}}} \quad \quad \quad \swarrow \propto \frac{1}{\sqrt{n_{\text{train}}}}$

$$M\left[D_{\text{true}}^{n_{\text{equiv}}}, p_{\text{true}}\right]$$

$$= \sigma_{\text{stat}}(n_{\text{equiv}})$$

$\nwarrow \propto \frac{1}{\sqrt{n_{\text{equiv}}}}$



- ▶ How to get $M[D_{\text{true}}^n, p_{\text{true}}]$ and $M[D_{\text{gen}}^n, p_{\text{true}}]$?
 - ▶ Option 1: Extrapolate
 - ▶ Option 2: Calculate Approximately