

# Improvement of time-of-flight resolution of PET scanner using additional prompt photon

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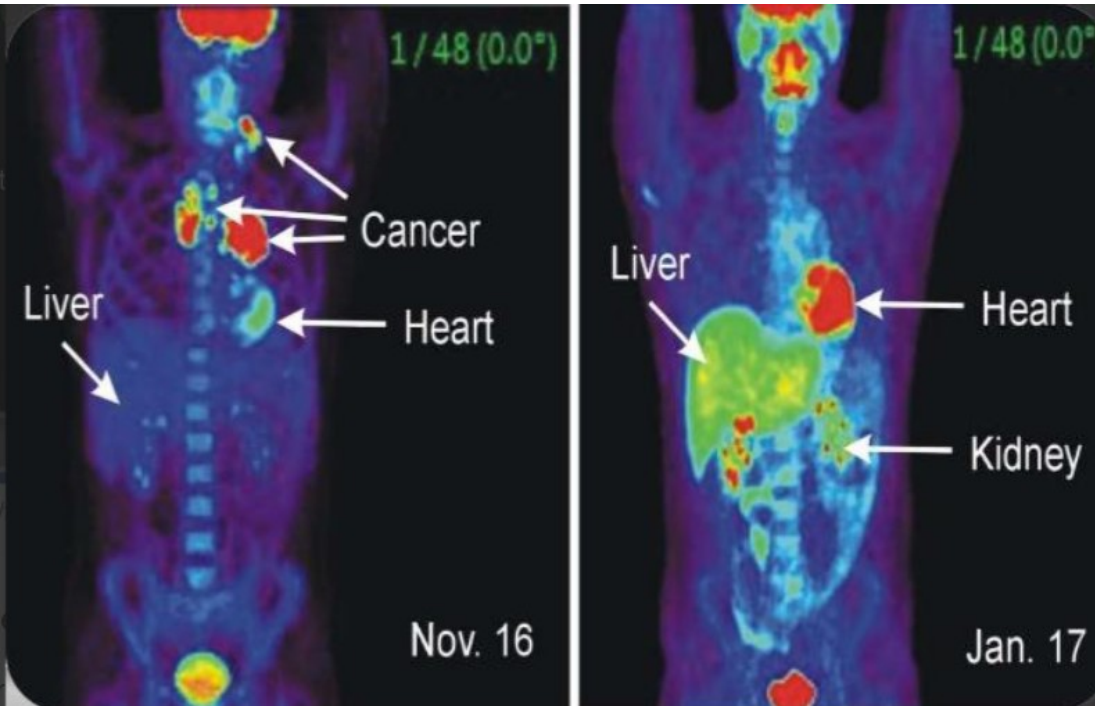


# Agenda:

- Introduction
- Position resolution improvement algorithm
- Simulation results
- Summary

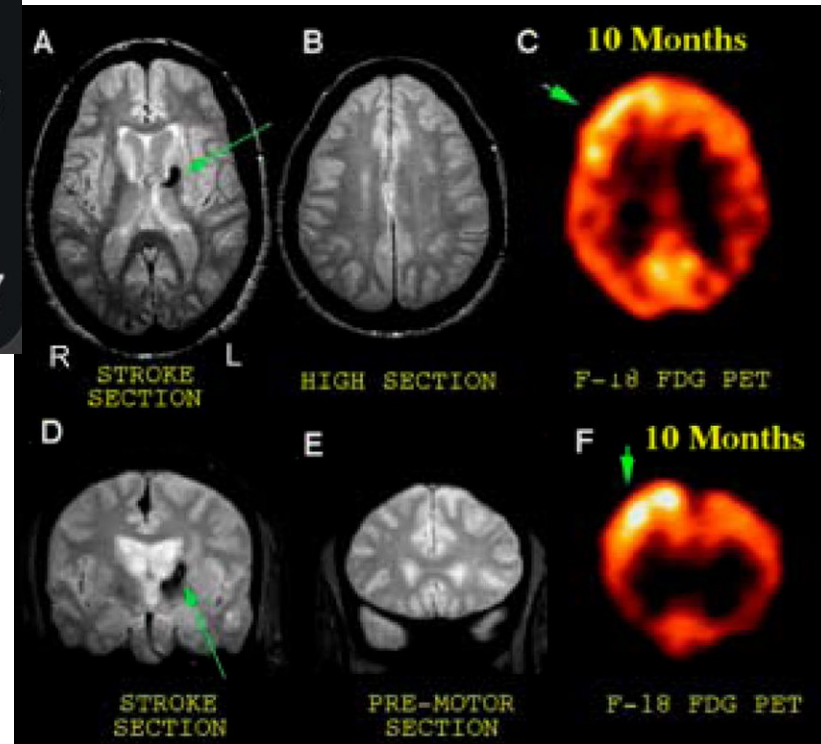
# Introduction

- Positron Emission Tomography (PET) is a functional imaging method.



\*Figure from:

<https://www.openpr.com/news/738094/global-positron-emission-tomography-pet-scanners-market-2017-toshiba-hitachi-neusoft-topgrade-ealthcare.html>

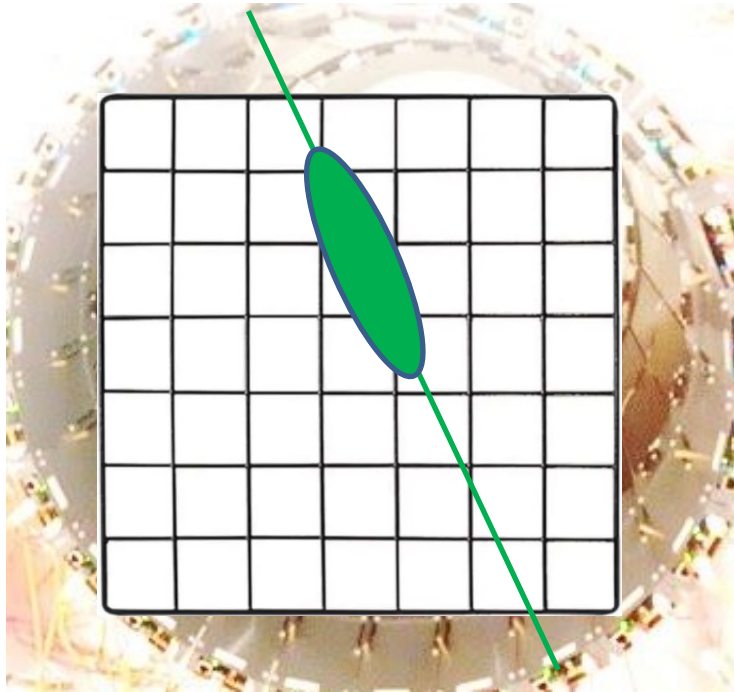


\*Figure from:

James C. Eliassen et al. *Brain-Mapping Techniques for Evaluating Poststroke Recovery and Rehabilitation: A Review*. *Top Stroke Rehabil.* 2008 ; 15(5): 427–450

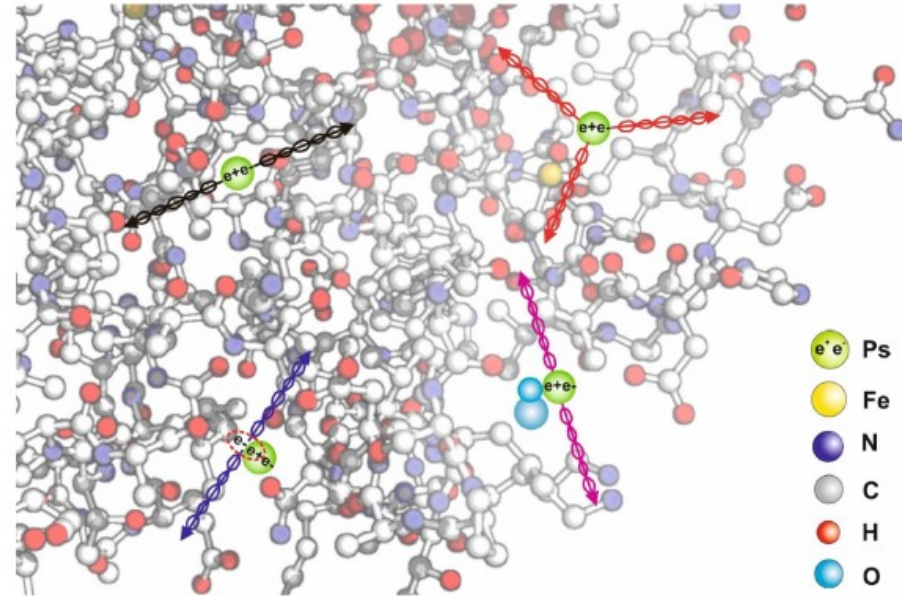
# Introduction

annihilation photon



annihilation photon

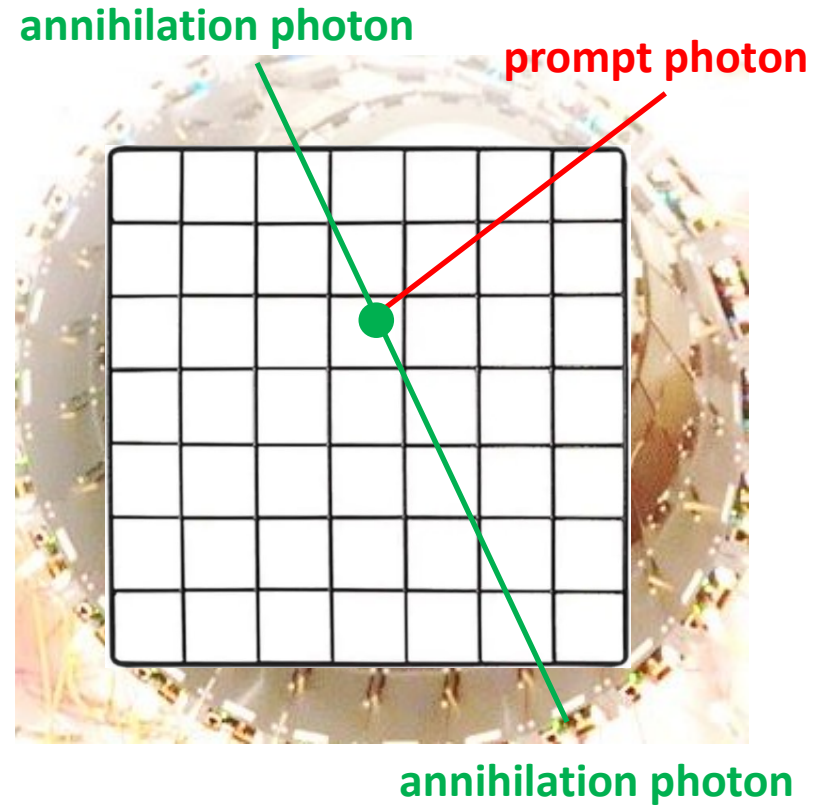
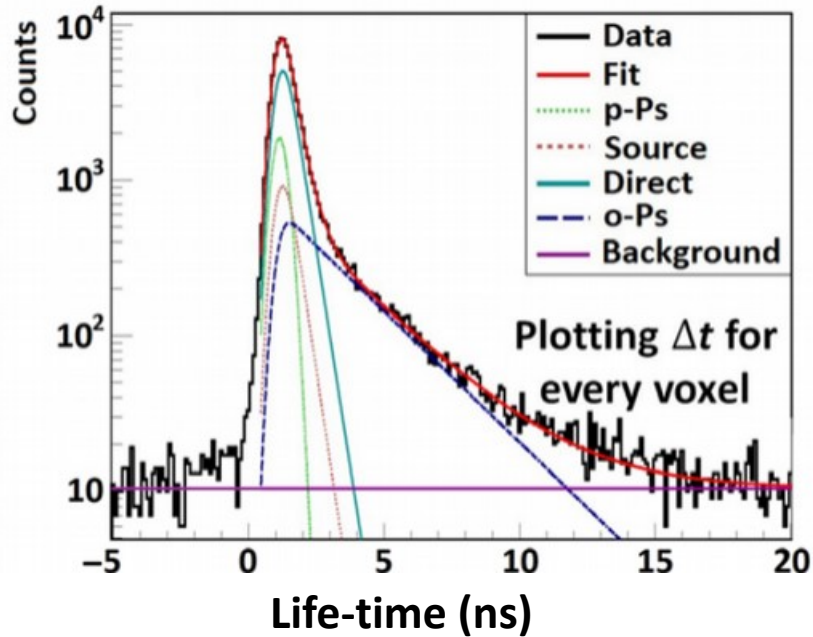
\*Figure is adapted from: P. Moskal et al., EJNMMI Phys. 7 (2020) 44.



- Radioactive tracer, emitting positrons, is injected into the patient's body.
- Nowadays, in PET imaging two photons along LOR are considered.
- Reconstruction of annihilation position (green ellipse) is based on time measurement of arrival of the two photons at the detectors (left).

# Introduction

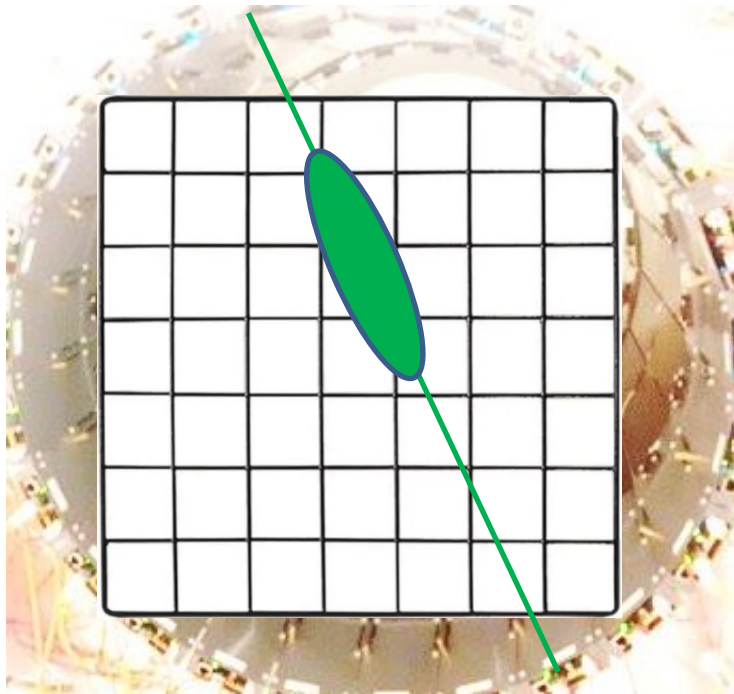
\*Figure is adapted from: P. Moskal et al., Science Advance, 2021 ; 7, eabh4394.



- In the Positronium Imaging, a special radiotracer that emits an additional prompt photon is required.
- The lifetime of Positronium may be estimated using two back-to-back annihilation photons and prompt photon.

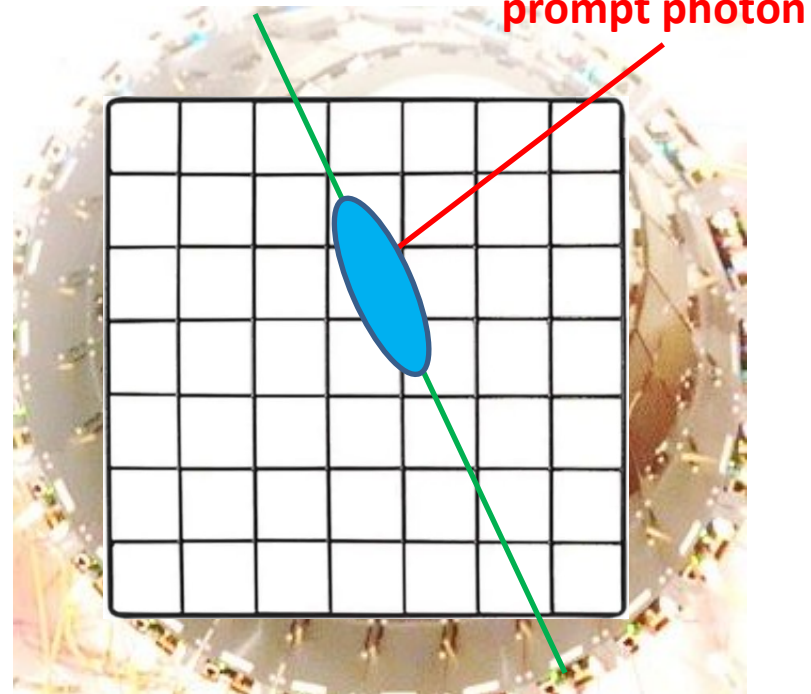
# Introduction

annihilation photon



annihilation photon

annihilation photon



annihilation photon

- Reconstruction of radiotracer activity using two annihilation photons only (left) and three photons (right).
- Is it possible to improve the position resolution (reduce the ellipse area) ?

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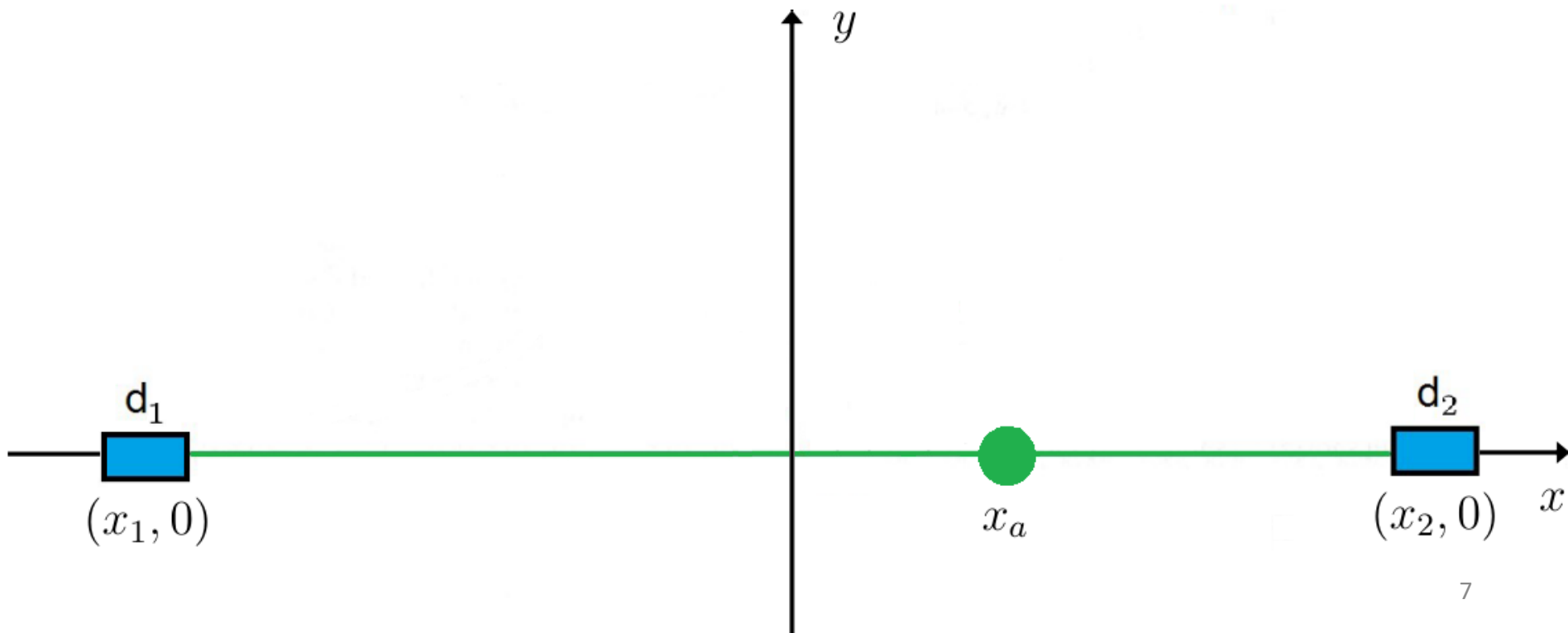
**Algorithm 1** Position reconstruction of emission point

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**Require:**  $x_1, x_2, t_1, t_2, x_3, y_3, t_3, \mu_\tau, \sigma_\tau$

1:  $x_a \leftarrow \frac{c(t_1 - t_2)}{2}$

2:  $t_a \leftarrow \frac{c(t_1 + t_2) - |x_1 - x_2|}{2c}$



## Algorithm 1 Position reconstruction of emission point

**Require:**  $x_1, x_2, t_1, t_2, x_3, y_3, t_3, \mu_\tau, \sigma_\tau$

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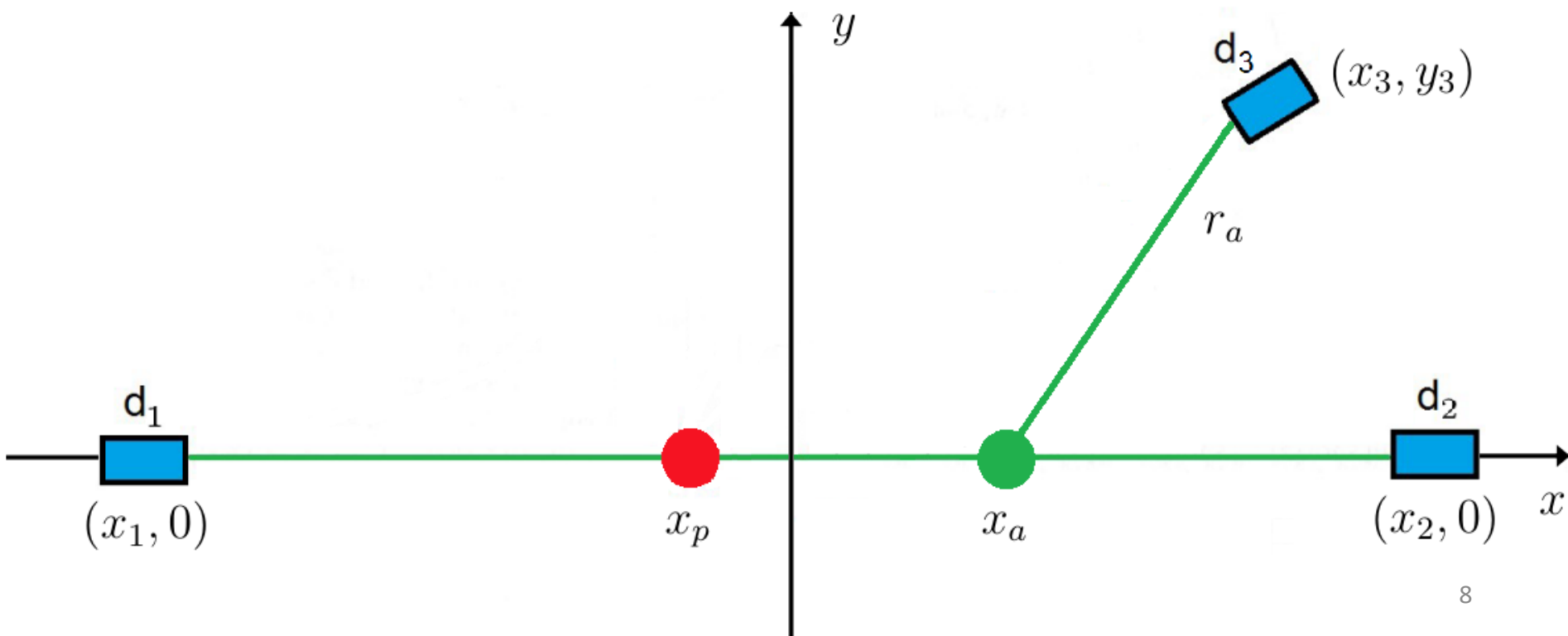
2:  $t_a \leftarrow \frac{c(t_1 + t_2) - |x_1 - x_2|}{2c}$

3:  $r_a \leftarrow \sqrt{(x_a - x_3)^2 + y_3^2}$

4:  $\tau \leftarrow t_a - t_3 + \frac{r_a}{c}$

▷ calculate distance  $r_a$  using annihilation position

▷ calculate lifetime





## Algorithm 1 Position reconstruction of emission point

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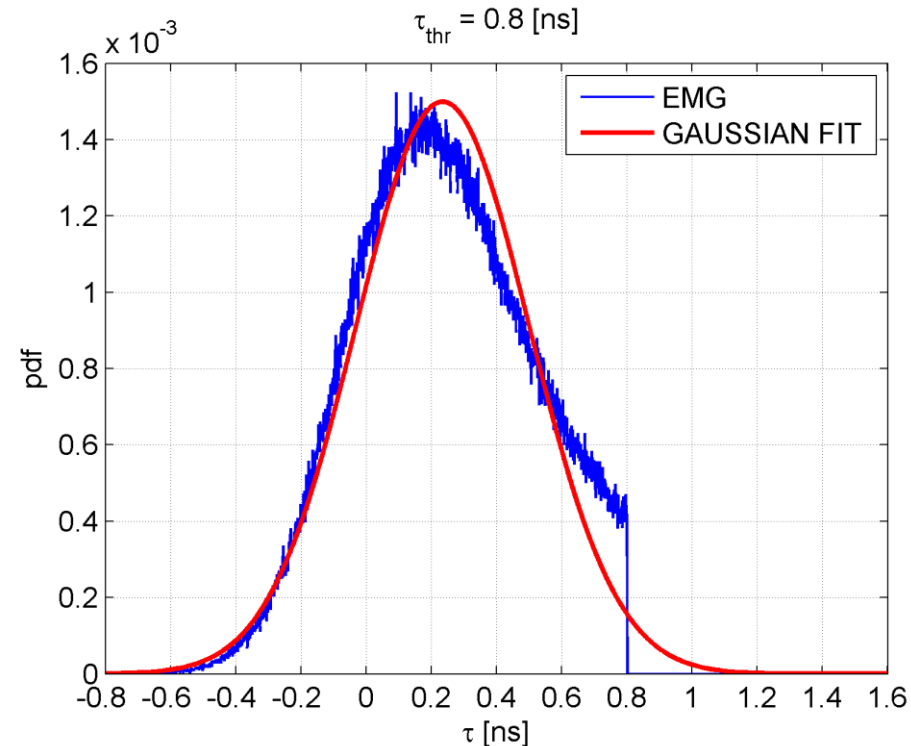
▷ calculate distance  $r_a$  using annihilation position

▷ calculate lifetime

$$\tau \sim \sum_{k=1}^3 I_k \cdot \text{EMG} \left( \lambda_k, \frac{3}{2} \sigma_t^2 \right)$$

$$\tau \sim \mathcal{N}(\mu_\tau, \sigma_\tau^2)$$

	Intensity ( $I_k$ )	Mean lifetime ( $1/\lambda_k$ )
<b>Direct</b>	0.65	0.388 ns
<b>p-Ps</b>	0.15	0.125 ns
<b>o-Ps</b>	0.20	2.000 ns



\*Data is adapted from: P. Moskal et al., Science Advance, 2021 ; 7, eabh4394.

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4:  $\tau \leftarrow t_a - t_3 + \frac{r_a}{c}$

5: **if**  $\tau < \tau_{\text{thr}}$  **then**

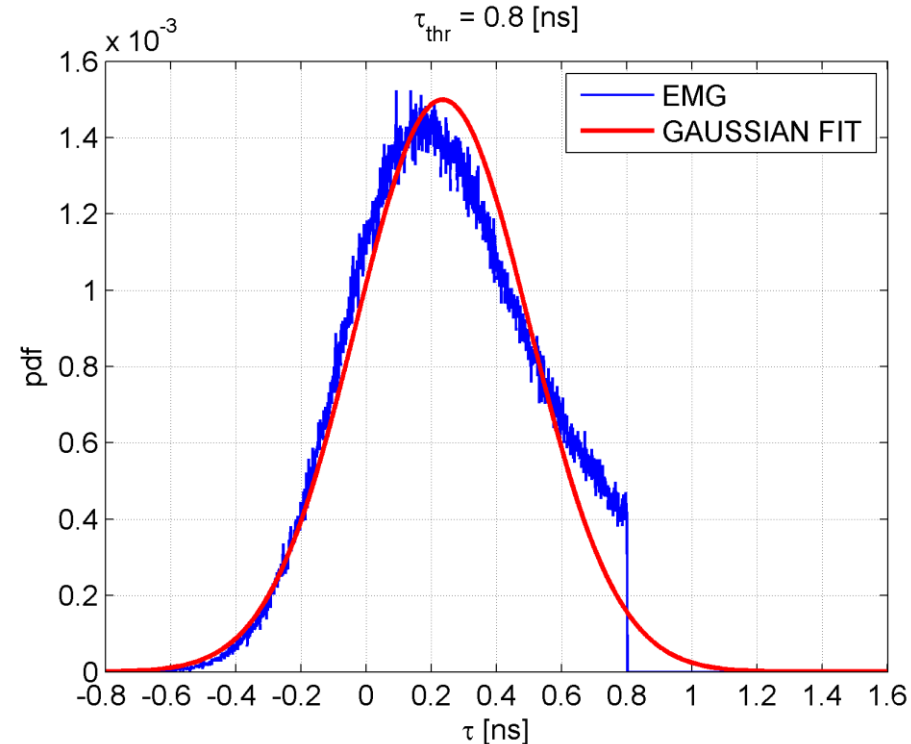
6:  $r_p \leftarrow c(t_3 - t_a + \mu_\tau)$

▷ calculate distance  $r_a$  using annihilation position

▷ calculate lifetime

▷ calculate distance  $r_p$  using prior distribution

$$\tau \sim \mathcal{N}(\mu_\tau, \sigma_\tau^2)$$



\*Data is adapted from: P. Moskal et al., Science Advance, 2021 ; 7, eabh4394.

## Algorithm 1 Position reconstruction of emission point

**Require:**  $x_1, x_2, t_1, t_2, x_3, y_3, t_3, \mu_\tau, \sigma_\tau$

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4:  $\tau \leftarrow t_a - t_3 + \frac{r_a}{c}$

5: **if**  $\tau < \tau_{\text{thr}}$  **then**

6:  $r_p \leftarrow c(t_3 - t_a + \mu_\tau)$

7:  $\kappa \leftarrow \frac{r_p - |y_3|}{c\sigma_\tau}$

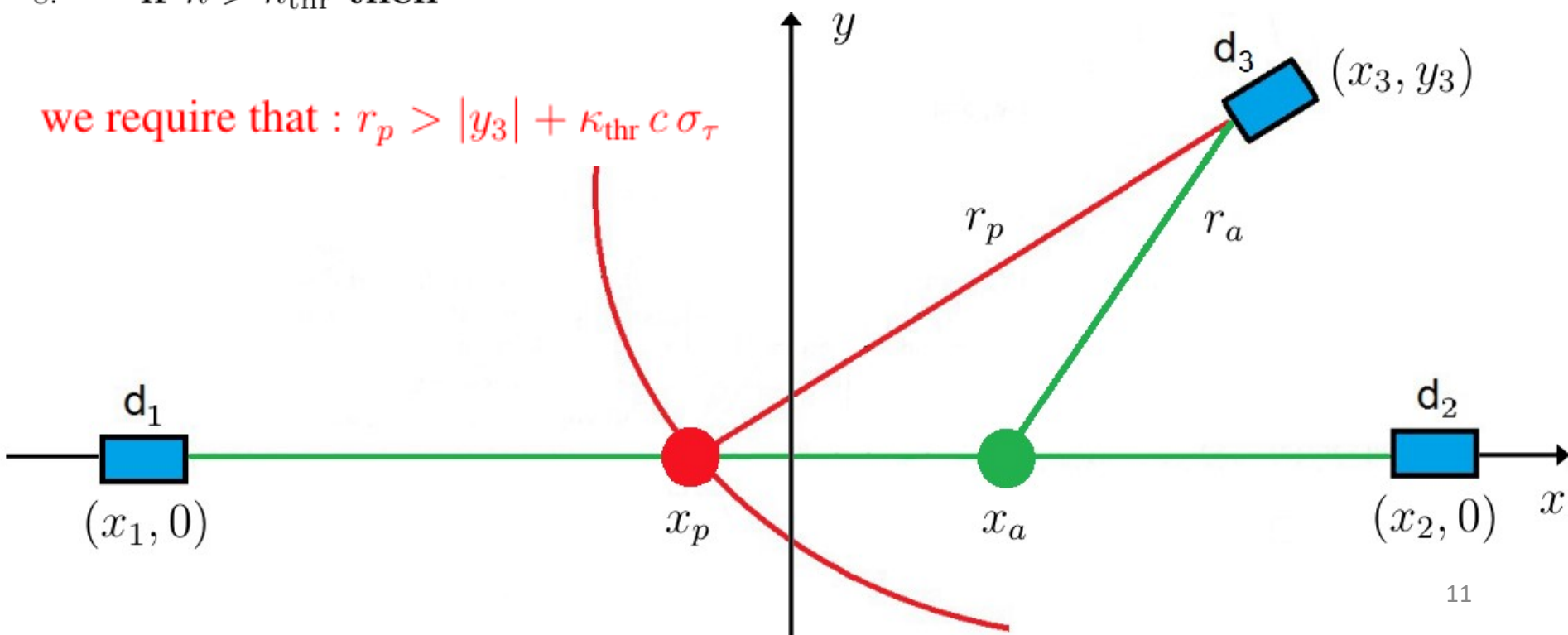
8: **if**  $\kappa > \kappa_{\text{thr}}$  **then**

▷ calculate distance  $r_a$  using annihilation position

▷ calculate lifetime

▷ calculate distance  $r_p$  using prior distribution

we require that :  $r_p > |y_3| + \kappa_{\text{thr}} c \sigma_\tau$



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**Algorithm 1** Position reconstruction of emission point

---

**Require:**  $x_1, x_2, t_1, t_2, x_3, y_3, t_3, \mu_\tau, \sigma_\tau$ 

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3:  $r_a \leftarrow \sqrt{(x_a - x_3)^2 + y_3^2}$

 $\triangleright$  calculate distance  $r_a$  using annihilation position

4:  $\tau \leftarrow t_a - t_3 + \frac{r_a}{c}$

 $\triangleright$  calculate lifetime5: **if**  $\tau < \tau_{\text{thr}}$  **then**

6:  $r_p \leftarrow c(t_3 - t_a + \mu_\tau)$

 $\triangleright$  calculate distance  $r_p$  using prior distribution

7:  $\kappa \leftarrow \frac{r_p - |y_3|}{c\sigma_\tau}$

8: **if**  $\kappa > \kappa_{\text{thr}}$  **then**

9:  $x_p \leftarrow x_3 - \text{sign}(x_3) \sqrt{r_p^2 - y_3^2}$

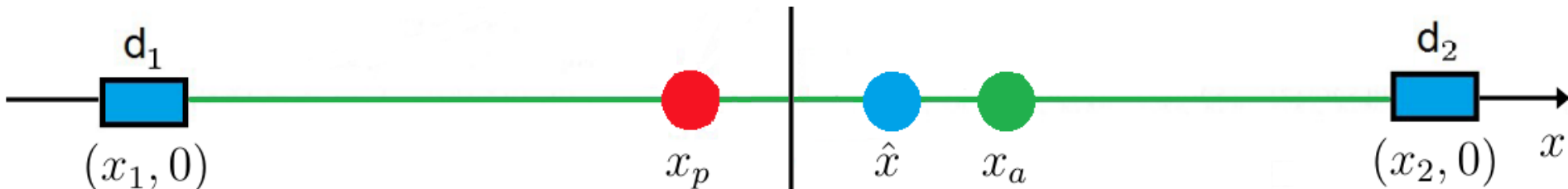
 $\triangleright$  calculate position  $x_p$  using prompt photon

10:  $\sigma_p \leftarrow c\sigma_\tau \frac{r_p}{\sqrt{r_p^2 - y_3^2}}$

11:  $\hat{x} \leftarrow x_a \frac{\sigma_p^2}{\sigma_a^2 + \sigma_p^2} + x_p \frac{\sigma_a^2}{\sigma_a^2 + \sigma_p^2}$

 $\triangleright$  calculate final position  $\hat{x}$ 12: **end if**13: **end if**

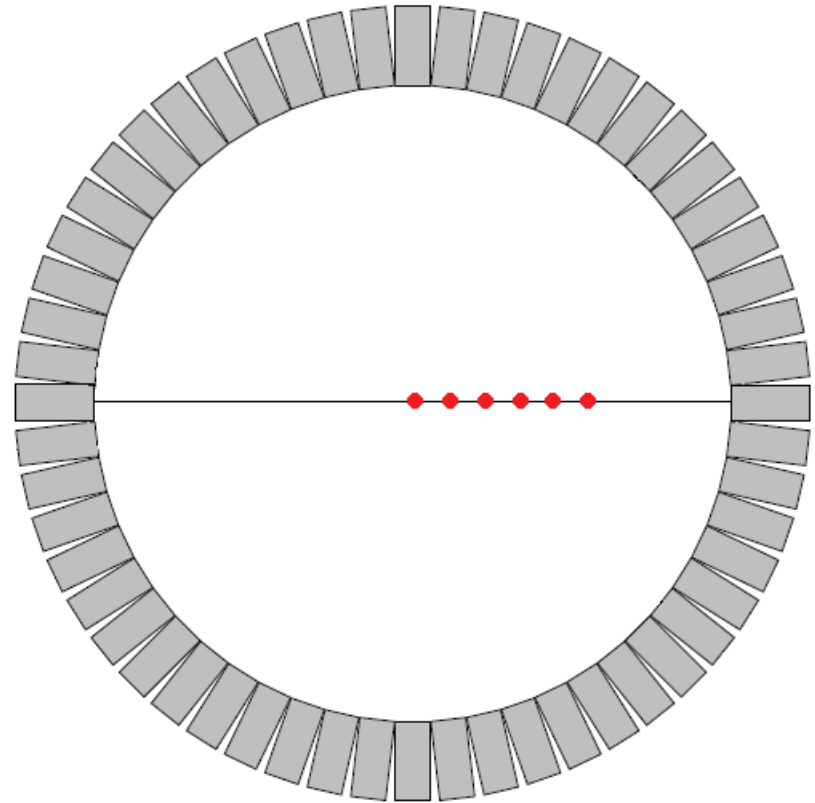
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# Simulation results

## Measurement setup:

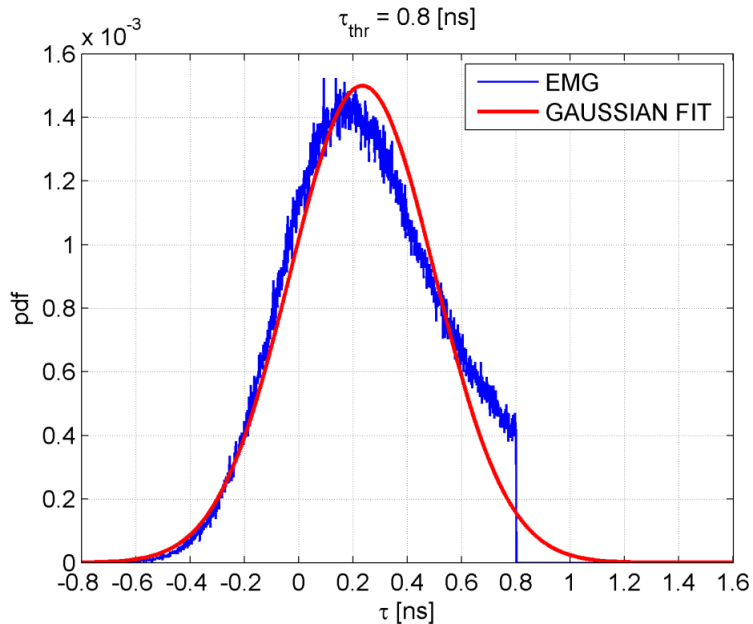
- 2-dimensional geometry
- Detector radius: 40 [cm]
- **Coincidence resolving time (CRT): 500 [ps]**
- Radial positions of source [cm]:  
0, 2, 4, 6, 8, 10, 12, 14, 15
- Number of events at each position: 100,000



**We simulate only time uncertainty (positions are exact!)**

# Simulation results

- **Coincidence resolving time (CRT): 500 [ps]**



	Intensity ( $I_k$ )	Mean lifetime ( $1/\lambda_k$ )
<b>Direct</b>	0.65	0.388 ns
<b>p-Ps</b>	0.15	0.125 ns
<b>o-Ps</b>	0.20	2.000 ns

$$\tau \sim \sum_{k=1}^3 I_k \cdot \text{EMG} \left( \lambda_k, \frac{3}{2} \sigma_t^2 \right) \approx \mathcal{N} (\mu_\tau, \sigma_\tau^2)$$

Prior gaussian distribution of lifetime:

$$\mu_\tau = 250 \text{ ps}$$

$$\sigma_\tau = 250 \text{ ps}$$

# Simulation results

- **Coincidence resolving time (CRT): 500 [ps]**

Standard deviation along LOR based on prompt photon only:

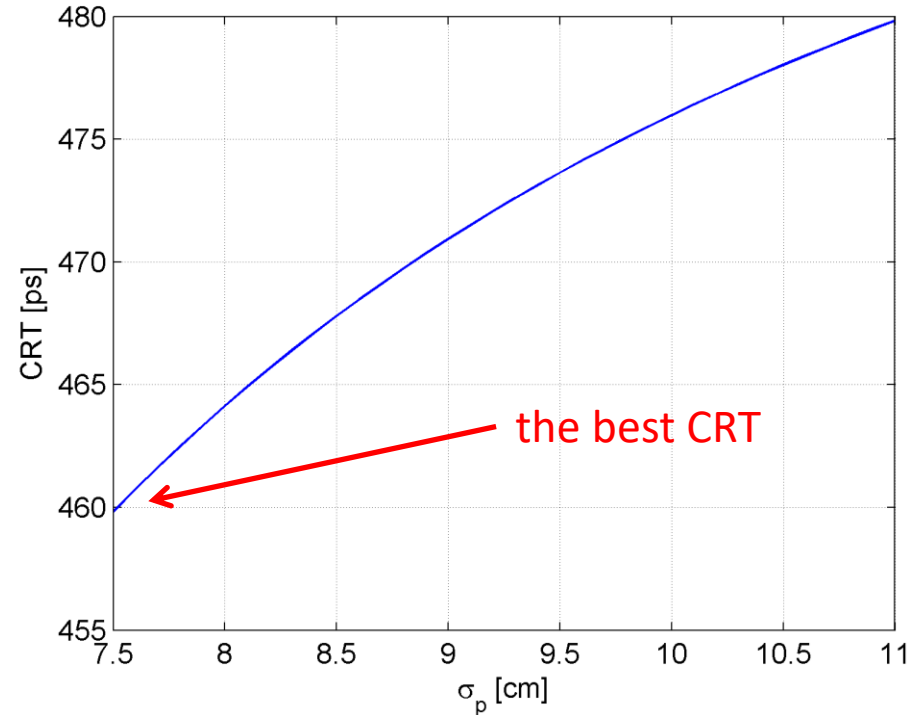
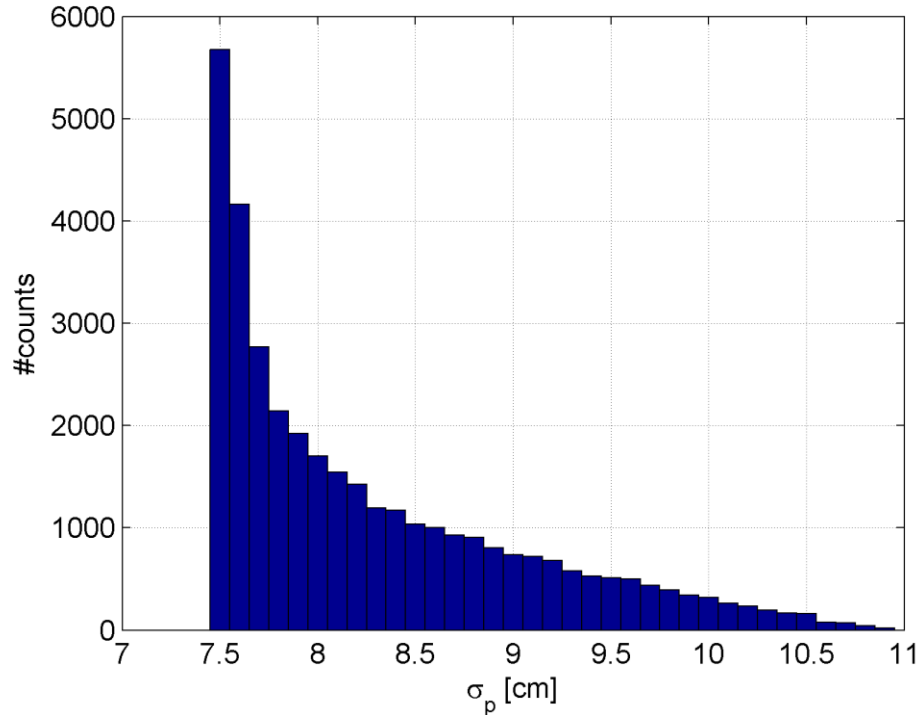
$$\sigma_p = \sigma_r \frac{r_p}{\sqrt{r_p^2 - y_3^2}} \geq 7.5 \text{ cm} \quad (\sigma_r = c \sigma_\tau = 7.5 \text{ cm})$$

Standard deviation along LOR based on two annihilation photons only:

$$\sigma_a = 3.18 \text{ cm}$$

# Simulation results

- Calculation of CRT for point source in (0,0):



$$\sigma_p = \sigma_r \frac{r_p}{\sqrt{r_p^2 - y_3^2}} \geq 7.5 \text{ cm}$$

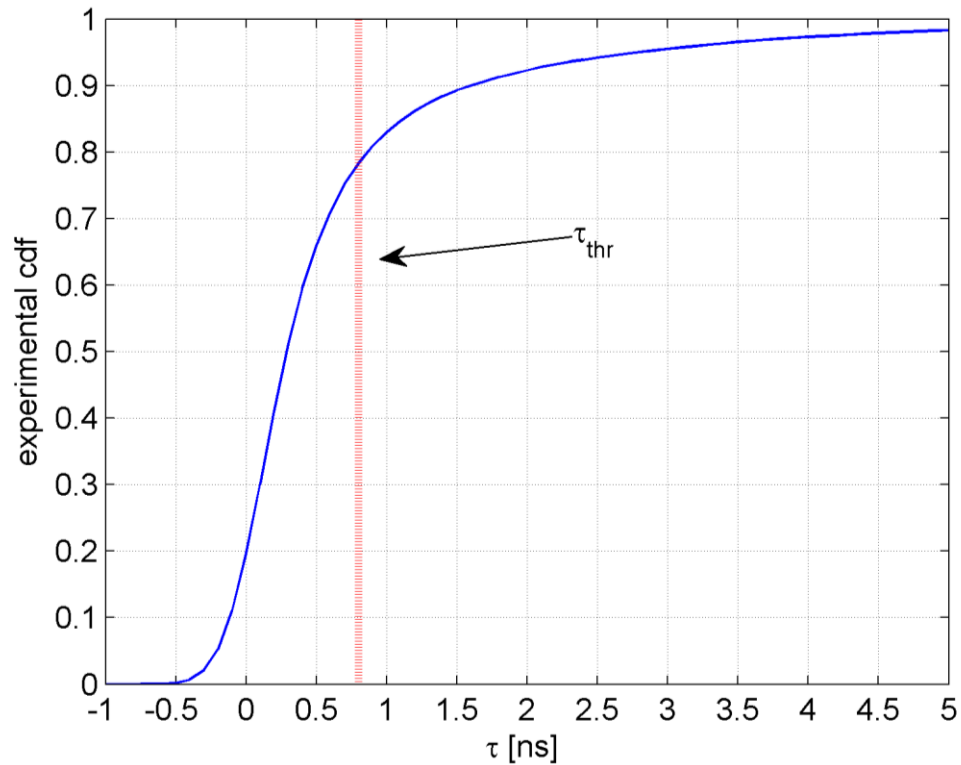
$$\hat{\sigma} = \frac{\sigma_a \sigma_p}{\sqrt{\sigma_a^2 + \sigma_p^2}}$$

- For the smallest  $\sigma_p$  (left figure) we get best possible CRT of about **460 ps** (right figure).



# Simulation results

<b>CONDITION I</b>		
$\tau < \tau_{\text{thr}}$	<b>YES</b>	<b>77%</b>
	<b>NO</b>	<b>23%</b>



# Simulation results

<b>CONDITION I</b>		
$\tau < \tau_{thr}$	<b>YES</b>	<b>77%</b>
	<b>NO</b>	<b>23%</b>

<b>CONDITIONS I and II</b>		$\kappa > \kappa_{thr}$	
		<b>YES</b>	<b>NO</b>
$\tau < \tau_{thr}$	<b>YES</b>	<b>35%</b>	<b>42%</b>
	<b>NO</b>	-	<b>23%</b>

# Simulation results

- Calculation of CRT for point source in (0,0)
- Take into account that reconstruction with prompt photon may be provided in 35% of cases:

$$\sigma_a^2 = \frac{1}{N_a} \sum_i^{N_a} (x_a^i - \mu)^2$$

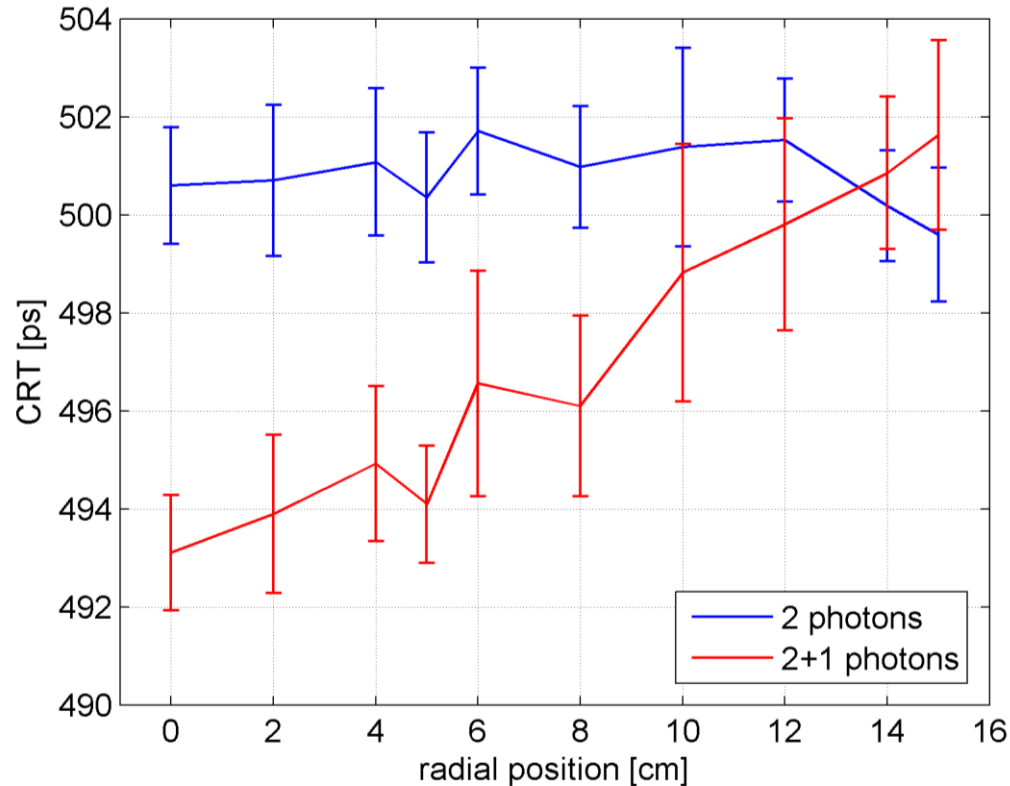
$$\hat{\sigma}^2 = \frac{1}{\hat{N}} \sum_i^{\hat{N}} (\hat{x}^i - \mu)^2$$

$$\sigma_{tot}^2 = \frac{1}{N_{tot}} \left( \sum_i^{N_a} (x_a^i - \mu)^2 + \sum_j^{\hat{N}} (\hat{x}^j - \mu)^2 \right)$$

where:  $N_{tot} = N_a + \hat{N}$  and  $\frac{N_a}{N_{tot}} = 0.65$ ,  $\frac{\hat{N}}{N_{tot}} = 0.35$ .

Therefore:  $\text{CRT}_{tot} \approx \sqrt{0.65 (500)^2 + 0.35 (466)^2} \approx 489 \text{ ps}$

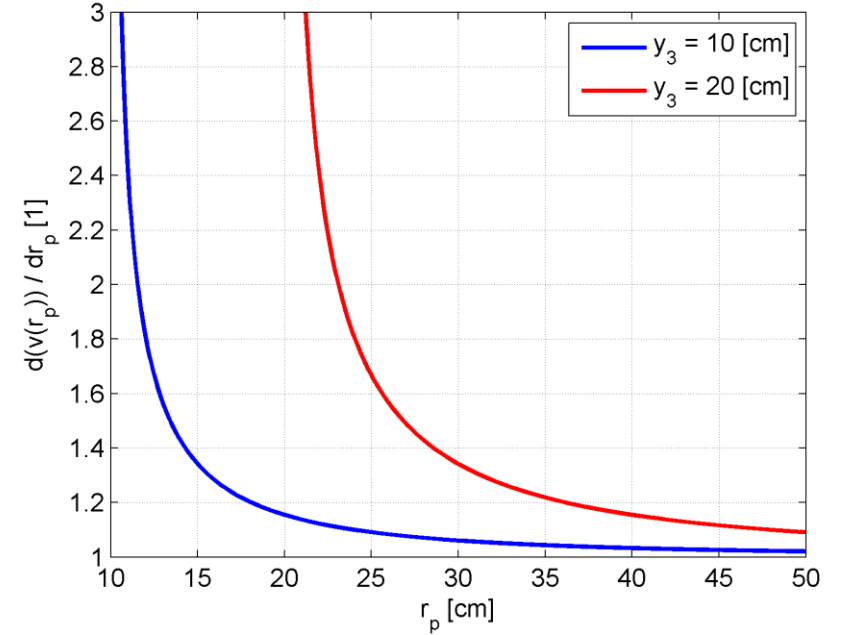
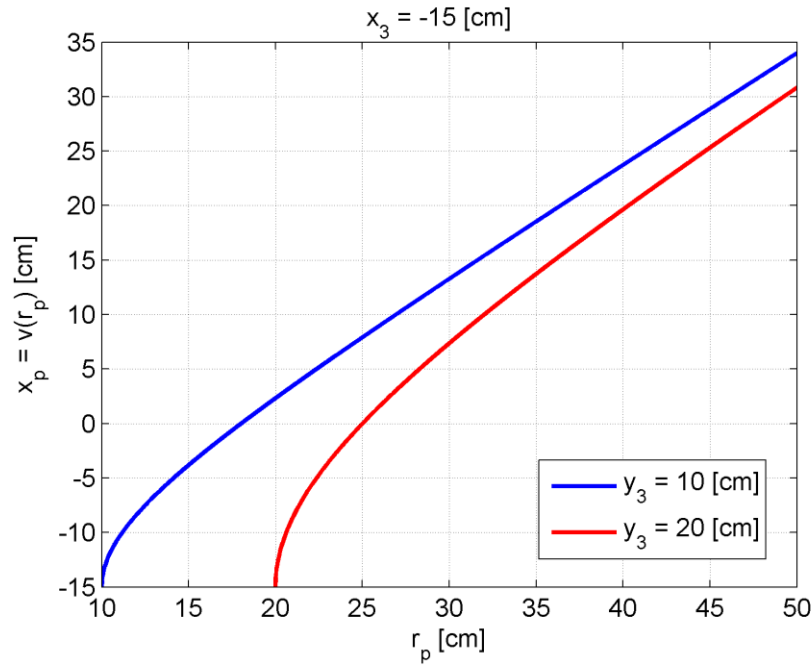
# Simulation results



- Calculation of CRT for point sources in positions from 0 to 15 cm.
- The reference reconstruction with annihilation photons only does not depend on radial position (CRT about 500 ps – see blue curve).
- In the proposed algorithm the worsening of the CRT with increasing radial distance is observed.

# Summary

- The algorithm for position reconstruction using two annihilation photons and prompt photon was proposed.
- There are two reasons why information from additional prompt photon does not improve significantly the CRT resolution:
  1. The proposed reconstruction with prompt photon may be provided in only 1/3 of cases.
  2. The estimate provided by prompt photon alone is smaller than expected (wide distribution of positronium lifetime).
- Future work:
  - Investigation of resolution improvement for CRTs smaller than 500 ps.
  - Consideration of both time and position uncertainties (in presented results positions were exact).



$$x_p = v(r_p) = \begin{cases} x_3 - \sqrt{r_p^2 - y_3^2} & x_3 \geq 0 \\ x_3 + \sqrt{r_p^2 - y_3^2} & x_3 < 0 \end{cases}$$

The linear approximation of a function  $v()$  :

$$x_p \approx x_3 \pm \left( \sqrt{\mu_r^2 - y_3^2} + (r_p - \mu_r) \frac{\partial}{\partial r_p} (v(\mu_r)) \right)$$