# Revisiting timelike geodesics in the Schwarzschild spacetime: 

general expressions in terms of Weierstrass elliptic functions
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## State of the knowledge

- 1916 K. Schwarzschild - the first vacuum solution of Einstein's equations.
- 1917 J. Droste - independently produced the same solution as Schwarzschild. Additionally solved equations of motion of test particles using Weierstrass elliptic functions.
- 1930 Y. Hagihara - gave a full description of the motion of test particles based on Droste's work.
- 1959-62 C. Darwin, J. Plebański, B. Mielnik - description of the geodesic motion in the language of Jacobi elliptical functions.
- 2011 G. Scharf - description of the geodesic motion using the simplified Biermann Weierstrass formula.
- 2014 U. Kostić - elegant description in a modern language.


## Metric

We will work in spherical coordinates $(t, r, \theta, \varphi)$. In its simplest form the Schwarzschild metric is written as

$$
g=-N d \bar{t}^{2}+\frac{d \bar{r}^{2}}{N}+\bar{r}^{2} d \theta^{2}+\bar{r}^{2} \sin ^{2} \theta d \varphi^{2}
$$

where

$$
N=1-\frac{r_{s}}{\bar{r}},
$$

and $r_{s}=2 M$ is the Schwarzschild radius.
In order to avoid irregularities at the horizon, we choose a new time foliation

$$
t=\bar{t}+\int^{\bar{r}}\left[\frac{1}{N(s)}-\eta(s)\right] d s, \quad r=\bar{r},
$$

where $\eta=\eta(\bar{r})$ is a function of radius $\bar{r}$, yields the metric in the form

$$
\begin{equation*}
g=-N d t^{2}+2(1-N \eta) d t d r+\eta(2-N \eta) d r^{2}+r^{2} d \theta^{2}+r^{2} \sin ^{2} \theta d \varphi^{2} \tag{1}
\end{equation*}
$$

## Equations of motion

There are many ways to get the equations of motion, e.g., Hamilton's equations. We can write down the particle equation of motion as

$$
\begin{align*}
\frac{d \xi}{d s} & =\epsilon_{r} \sqrt{\varepsilon^{2}-U_{\lambda}(\xi)}  \tag{2a}\\
\frac{d \psi}{d s} & =\frac{\lambda}{\xi^{2}}  \tag{2b}\\
\frac{d \tau}{d s} & =\frac{\varepsilon}{N(\xi)}+\epsilon_{r} \frac{1-N(\xi) \eta(\xi)}{N(\xi)} \sqrt{\varepsilon^{2}-U_{\lambda}(\xi)} \tag{2c}
\end{align*}
$$

where $N(\xi)=1-2 / \xi$,

$$
\tau=t / M, \xi=r / M, \pi_{\xi}=p_{r} / m, \pi_{\theta}=p_{\theta} / M m, \varepsilon=E / m, \lambda=I / M m
$$

are dimensionless variables and the dimensionless effective potential

$$
U_{\lambda}(\xi)=\left(1-\frac{2}{\xi}\right)\left(1+\frac{\lambda^{2}}{\xi^{2}}\right)=1-\frac{2}{\xi}+\frac{\lambda^{2}}{\xi^{2}}-\frac{2 \lambda^{2}}{\xi^{3}}
$$

and $\epsilon_{r}= \pm 1$, corresponds to the direction of motion.

## Solution of equations of motion

Given the form of Eqs. (2), it is natural to treat $\psi$ as a parameter and search for the solution of the form $\xi=\xi(\psi)$. From (2a) and (2b) we get immediately

$$
\begin{equation*}
\frac{d \xi}{d \psi}=\epsilon_{r} \frac{\xi^{2}}{\lambda} \sqrt{\varepsilon^{2}-U_{\lambda}(\xi)}=\epsilon_{r} \sqrt{\frac{\varepsilon^{2}-1}{\lambda^{2}} \xi^{4}+\frac{2}{\lambda^{2}} \xi^{3}-\xi^{2}+2 \xi} . \tag{3}
\end{equation*}
$$

Defining

$$
\begin{equation*}
f(\xi)=a_{0} \xi^{4}+4 a_{1} \xi^{3}+6 a_{2} \xi^{2}+4 a_{3} \xi+a_{4} \tag{4}
\end{equation*}
$$

where

$$
\begin{equation*}
a_{0}=\frac{\varepsilon^{2}-1}{\lambda^{2}}, \quad 4 a_{1}=\frac{2}{\lambda^{2}}, \quad 6 a_{2}=-1, \quad 4 a_{3}=2, \quad a_{4}=0, \tag{5}
\end{equation*}
$$

one can write Eq. (3) as

$$
\begin{equation*}
\frac{d \xi}{d \psi}=\epsilon_{r} \sqrt{f(\xi)} \tag{6}
\end{equation*}
$$

For a segment of the trajectory for which $\epsilon_{r}$ is constant, we get

$$
\begin{equation*}
\psi=\epsilon_{r} \int_{\xi_{0}}^{\xi} \frac{d \xi^{\prime}}{\sqrt{f\left(\xi^{\prime}\right)}} \tag{7}
\end{equation*}
$$

where $\xi_{0}$ is an arbitrarily chosen radius corresponding to the angle $\psi=0$.

## Theorem (Biermann-Weierstrass)

Let

$$
\begin{equation*}
f(x)=a_{0} x^{4}+4 a_{1} x^{3}+6 a_{2} x^{2}+4 a_{3} x+a_{4}, \tag{8}
\end{equation*}
$$

be a quartic polynomial. Denote the invariants of $f$ by $g_{2}$ and $g_{3}$, i.e.,

$$
\begin{align*}
g_{2} & \equiv a_{0} a_{4}-4 a_{1} a_{3}+3 a_{2}^{2},  \tag{9a}\\
g_{3} & \equiv a_{0} a_{2} a_{4}+2 a_{1} a_{2} a_{3}-a_{2}^{3}-a_{0} a_{3}^{2}-a_{1}^{2} a_{4} . \tag{9b}
\end{align*}
$$

Let

$$
\begin{equation*}
z(x)=\int_{x_{0}}^{x} \frac{d x^{\prime}}{\sqrt{f\left(x^{\prime}\right)}} \tag{10}
\end{equation*}
$$

where $x_{0}$ is any constant, not necessarily a zero of $f(x)$.

Then

$$
\begin{equation*}
x=x_{0}+\frac{-\sqrt{f\left(x_{0}\right)} \wp^{\prime}(z)+\frac{1}{2} f^{\prime}\left(x_{0}\right)\left(\wp(z)-\frac{1}{24} f^{\prime \prime}\left(x_{0}\right)\right)+\frac{1}{24} f\left(x_{0}\right) f^{\prime \prime \prime}\left(x_{0}\right)}{2\left(\wp(z)-\frac{1}{24} f^{\prime \prime}\left(x_{0}\right)\right)^{2}-\frac{1}{48} f\left(x_{0}\right) f^{(4)}\left(x_{0}\right)}, \tag{11}
\end{equation*}
$$

and

$$
\begin{gather*}
\wp(z)=\frac{\sqrt{f(x) f\left(x_{0}\right)}+f\left(x_{0}\right)}{2\left(x-x_{0}\right)^{2}}+\frac{f^{\prime}\left(x_{0}\right)}{4\left(x-x_{0}\right)}+\frac{f^{\prime \prime}\left(x_{0}\right)}{24}, \\
\wp^{\prime}(z)=-\left[\frac{f(x)}{\left(x-x_{0}\right)^{3}}-\frac{f^{\prime}(x)}{4\left(x-x_{0}\right)^{2}}\right] \sqrt{f\left(x_{0}\right)}-\left[\frac{f\left(x_{0}\right)}{\left(x-x_{0}\right)^{3}}+\frac{f^{\prime}\left(x_{0}\right)}{4\left(x-x_{0}\right)^{2}}\right] \sqrt{f(x)}, \tag{12b}
\end{gather*}
$$

where $\wp(z)=\wp\left(z ; g_{2}, g_{3}\right)$ is the Weierstrass function corresponding to invariants (9).

## Application of the theorem

Therefore thanks to the Biermann-Weierstrass theorem, we can write the formula for $\xi=\xi(\psi)$ as
$\xi(\psi)=\xi_{0}+\frac{-\epsilon_{r_{0}} \sqrt{f\left(\xi_{0}\right)} \wp^{\prime}(\psi)+\frac{1}{2} f^{\prime}\left(\xi_{0}\right)\left[\wp(\psi)-\frac{1}{24} f^{\prime \prime}\left(\xi_{0}\right)\right]+\frac{1}{24} f\left(\xi_{0}\right) f^{\prime \prime \prime}\left(\xi_{0}\right)}{2\left[\wp(\psi)-\frac{1}{24} f^{\prime \prime}\left(\xi_{0}\right)\right]^{2}-\frac{1}{48} f\left(\xi_{0}\right) f^{(4)}\left(\xi_{0}\right)}$.

Here $\wp$ is understood to be defined by the invariants $g_{2}$, and $g_{3}$ given by Eq. (9) for $f$ defined in Eq. (6).
The above equation is a general solution to equation Eq. (3), and it is valid for all types of allowed trajectories. Sign of $\epsilon_{r_{0}}$ is selected at the initial position $\xi_{0}$. After selecting it, we do not have to worry about whether the particle is in front of its periapsis or not. It can be checked numerically and demonstrated analytically.

## Properties of the effective potential




IIa



IIIa


## Numerical tests



Figure: Sample inner bound orbits (type Ila) for $\lambda=4.2$. Solid color lines correspond to solutions obtained with Eq. (13). Dotted lines depict corresponding numerical solutions.


Figure: Sample outer bound orbits (type IIb) for $\lambda=4.2$. Solid color lines correspond to solutions obtained with Eq. (13). Dotted lines depict corresponding numerical solutions.


Figure: Sample unbound absorbed orbits (type IIIa) for $\lambda=8$. Solid color lines correspond to solutions obtained with Eq. (13). Dotted lines depict corresponding numerical solutions.


Figure: Sample unobound scattered orbits (type IIIb) for $\lambda=9.68$. Solid color lines correspond to solutions obtained with Eq. (13). Dotted lines depict corresponding numerical solutions.

## Proper time

Given an expression for $\xi=\xi(\psi)$, the corresponding proper time can be computed by integrating Eq. (2b), i.e., as

$$
\begin{equation*}
s(\psi)=\frac{1}{\lambda} \int_{0}^{\psi} \xi^{2}\left(\psi^{\prime}\right) d \psi^{\prime} \tag{14}
\end{equation*}
$$

Integrating the square of expression (13) is, in principle, possible, but it is tedious, and the result seems to be too complicated to be useful in practical applications. Much simpler formulas can be obtained by siplified verosion of using Eq. (13)

$$
\xi(\psi)=\xi_{1}+\frac{f^{\prime}\left(\xi_{1}\right)}{4\left[\wp(\psi)-\frac{1}{24} f^{\prime \prime}\left(\xi_{1}\right)\right]}
$$

i.e., we describe the motion with respect to periapsis.

The proper time elapsed during the motion from $\psi=0$ o some $\psi=\psi_{2}$ can be written as

$$
\begin{align*}
s_{*}\left(\psi_{2}, \xi_{1}\right)= & \frac{1}{\lambda}\left\{\xi_{1}^{2} \psi_{2}+\frac{1}{2} f^{\prime}\left(\xi_{1}\right) \xi_{1}\left[I_{1}\left(\psi_{2} ; y\right)-I_{1}(0 ; y)\right]\right. \\
& \left.+\frac{1}{16}\left[f^{\prime}\left(\xi_{1}\right)\right]^{2}\left[I_{2}\left(\psi_{2} ; y\right)-I_{2}(0 ; y)\right]\right\} \tag{15}
\end{align*}
$$

where $\wp(y)=\frac{1}{24} f^{\prime \prime}\left(\xi_{1}\right)$ or $y=\wp^{-1}\left(\frac{1}{24} f^{\prime \prime}\left(\xi_{1}\right)\right)$, and,

$$
\begin{align*}
& I_{1}(x ; y)=\frac{1}{\wp^{\prime}(y)}\left(2 \zeta(y) x+\ln \frac{\sigma(x-y)}{\sigma(x+y)}\right)  \tag{16}\\
& I_{2}(x ; y)=-\frac{1}{\wp^{\prime 2}(y)}\left(\zeta(x+y)+\zeta(x-y)+\left(2 \wp(y)+\frac{2 \wp^{\prime \prime}(y) \zeta(y)}{\wp^{\prime}(y)}\right) x\right) \\
&-\frac{\wp^{\prime \prime}(y)}{\wp^{\prime 3}(y)} \ln \frac{\sigma(x-y)}{\sigma(x+y)} \tag{17}
\end{align*}
$$

Consider a motion of a particle starting from an arbitrary location $\xi_{0}$, and moving inwards (in the dorection of the BH ), up to a periapsis with the radius $\xi_{1}$. Next the particle moves outwards, up to a location with a radius $\xi$. Define the angles $\psi_{1}$ and $\psi_{2}$ as

$$
\begin{gathered}
\psi_{1}=-\int_{\xi_{0}}^{\xi_{1}} \frac{d \xi^{\prime}}{\sqrt{f\left(\xi^{\prime}\right)}}=\int_{\xi_{1}}^{\xi_{0}} \frac{d \xi^{\prime}}{\sqrt{f\left(\xi^{\prime}\right)}}, \\
\psi_{2}=\int_{\xi_{1}}^{\xi} \frac{d \xi^{\prime}}{\sqrt{f\left(\xi^{\prime}\right)}} .
\end{gathered}
$$

Both angles satisfy $\psi_{1} \geq 0$ and $\psi_{2} \geq 0$. Let $\psi=\psi_{1}+\psi_{2}$. Because of symmetry, the proper time of the entire motion can be written as

$$
\begin{equation*}
s(\psi)=s_{*}\left(\psi_{1} ; \xi_{1}\right)+s_{*}\left(\psi_{2} ; \xi_{2}\right)=s_{*}\left(\psi_{1} ; \xi_{1}\right)+s_{*}\left(\psi-\psi_{1} ; \xi_{1}\right) . \tag{18}
\end{equation*}
$$

Formula Eq. (18) can be understood as a replacement for integral Eq. (14) with $\xi(\psi)$ given by Eq. (13). Note that, since $s_{*}\left(\psi_{2} ; \xi_{1}\right)$ is an odd function of $\psi_{2}$, we get $s(\psi=0)=0$, as expected. It can also be checked that the same formula holds for $\xi_{1}$ corresponding to an apoapsis.
The coordinate time $\tau$ can be obtained in a way similar to the calculation of the proper time $s$.

## Conclusion

- We have a new description of the motion of test particles, which depends only on the constants of motion $\lambda, \lambda_{z}, \varepsilon$ and the choice of the initial position $\left(\xi_{0}, \psi_{0}\right)$.
- The strengths of our description:
- one function $\xi(\psi)$ for the entire trajectory and every type of trajectory,
- the formula $\xi(\psi)$ does not require the knowledge of turning points,
- the expression for $\xi(\psi)$ is analytic and it is given in terms of well-known Weierstrass elliptic functions.
- The weakness of the description is that functions $\boldsymbol{s}(\psi)$ and $\tau(\psi)$ are not analytical.
- The method was designed to work in simulations of the Vlasov gas on the Schwarzschild background.

