



EuroHPC PL

Coincidence classification in the large field-of view J-PET scanners with machine learning methods

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Outline

- EuroHPC PL project
- PET imaging and Jagiellonian-PET
- Classification of PET events using ML



The European High Performance Computing Joint Undertaking (EuroHPC JU)



EuroHPC
Joint Undertaking

https://eurohpc-ju.europa.eu/index_en

joint initiative between the EU, European countries and private partner to develop a World Class Supercomputing Ecosystem in Europe

- Supercomputers
- GPU (Graphical Processor Units) computing
- Quantum computing
- Neuromorphic computing

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<https://www.eurohpc.pl/>

EuroHPC PL – development of the specialized infrastructure for the exascale computations addressing the key challenges for the Polish society, scientific community and the economy.

Consortium of 7 Polish institutions:
ACK Cyfronet AGH, PCSS, CI TASK, WCSS, NCBJ, IITiS PAN and CFT PAN.

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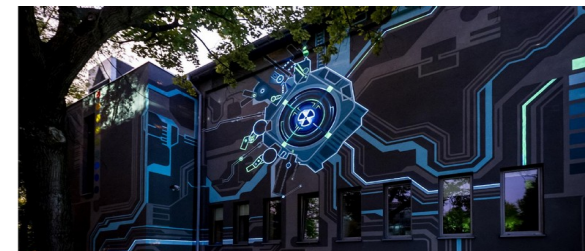
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Software platform for quantum simulations and medical imaging

<https://www.ncbj.gov.pl/en/aktualne/eurohpc-pl-national-supercomputing-infrastructure-eurohpc>



Quantum simulations and medical imaging software platform

Group:

- Wojciech Krzemień
- Konrad Klimaszewski
- Mateusz Bała
- Oleksander Fedoruk
- Lech Raczyński
- Tobiasz Jarosiewicz

Services

Common API

Simulators

PET Image Reconstructor

Phantom generator

Quantum emulators/
Quantum computer

Quantum
simulations

Standard
simulations

Image
reco.

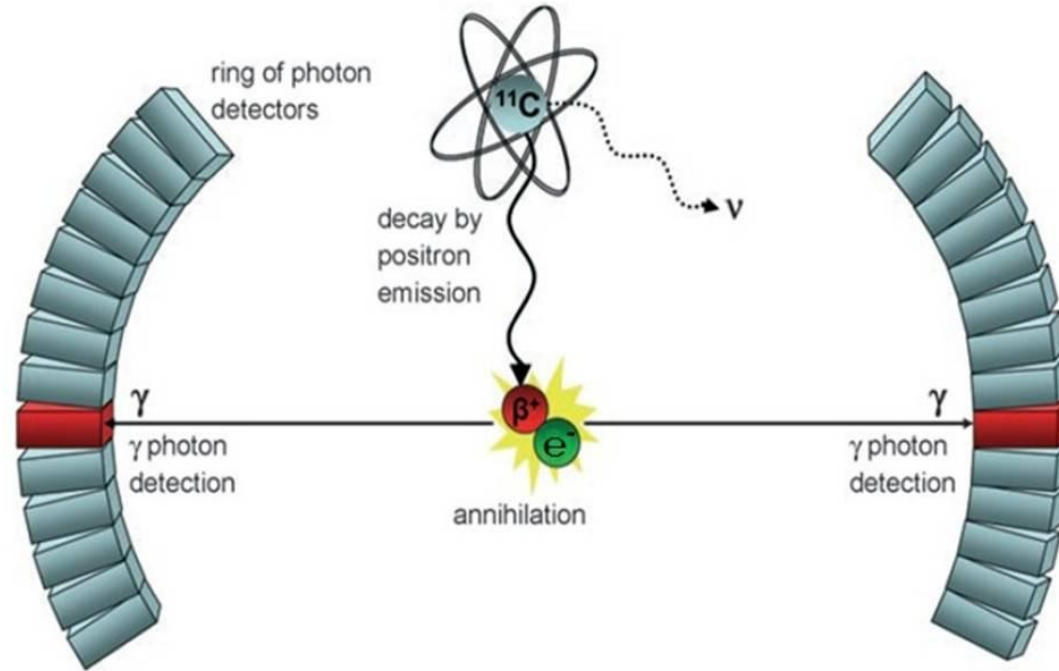
Quantum
Imaging

GAN
networks

Libraries

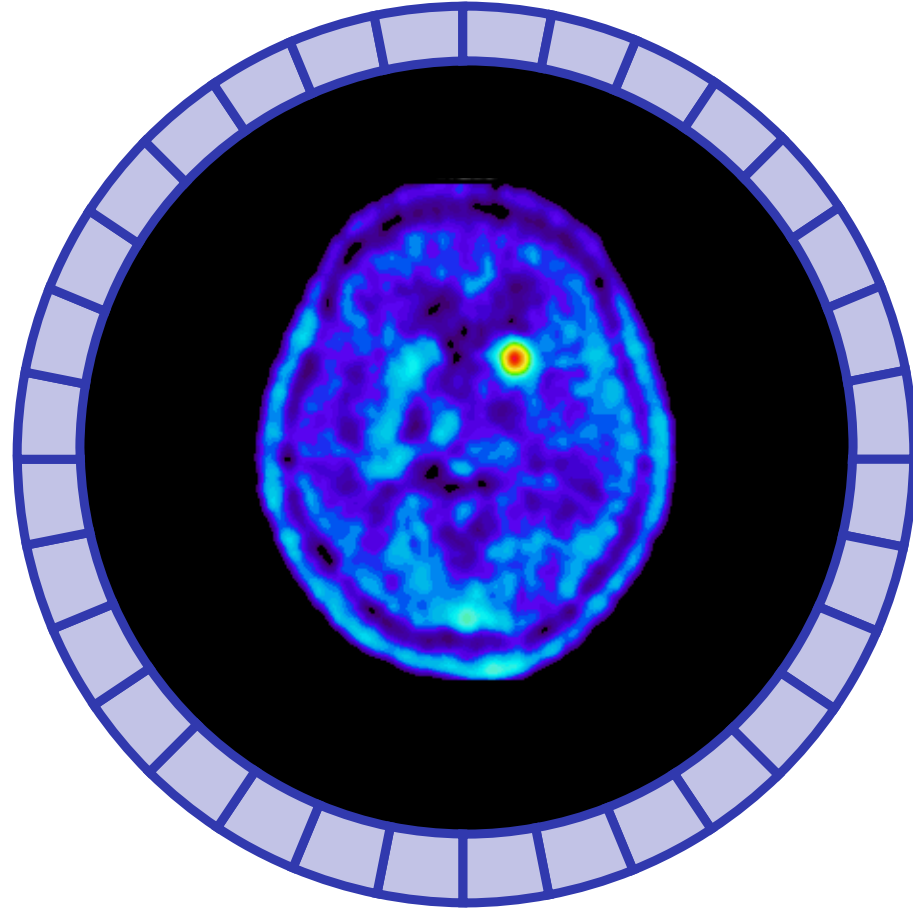


PET



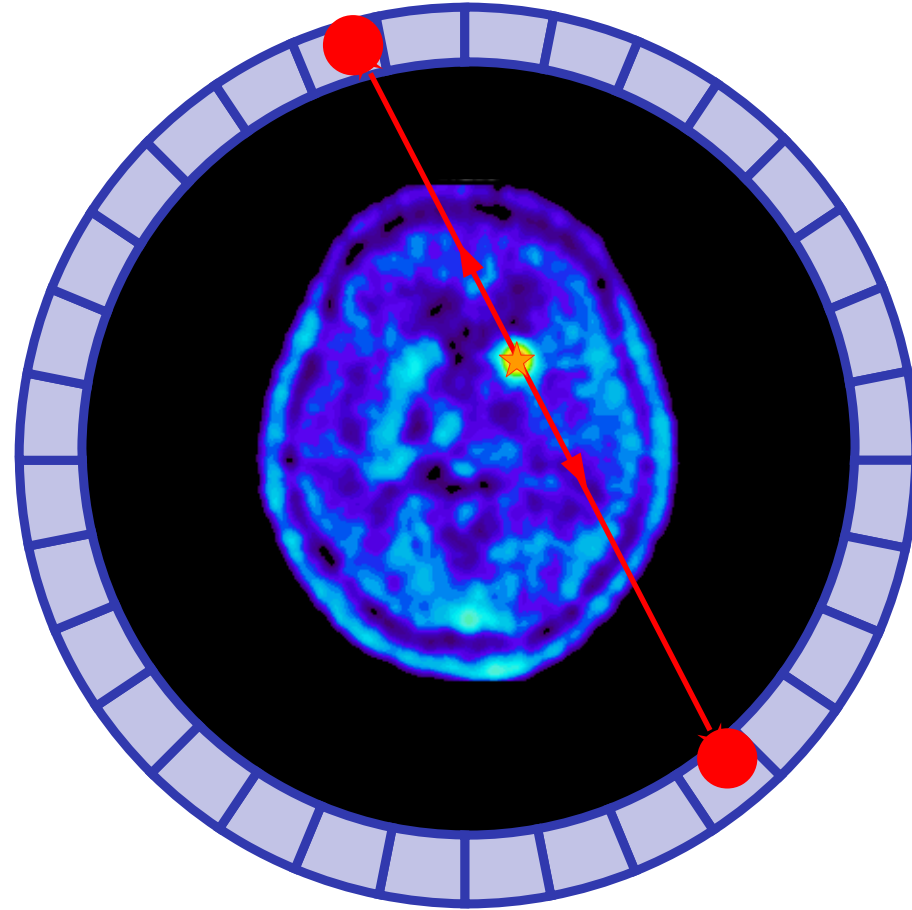


PET



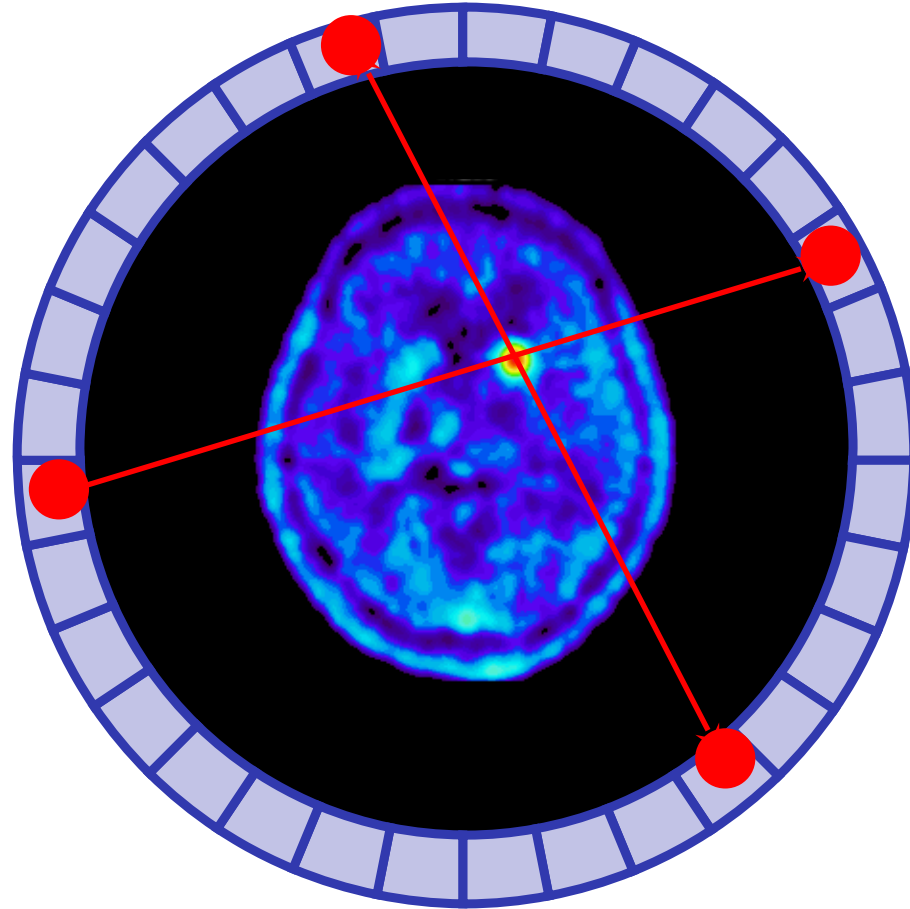


PET



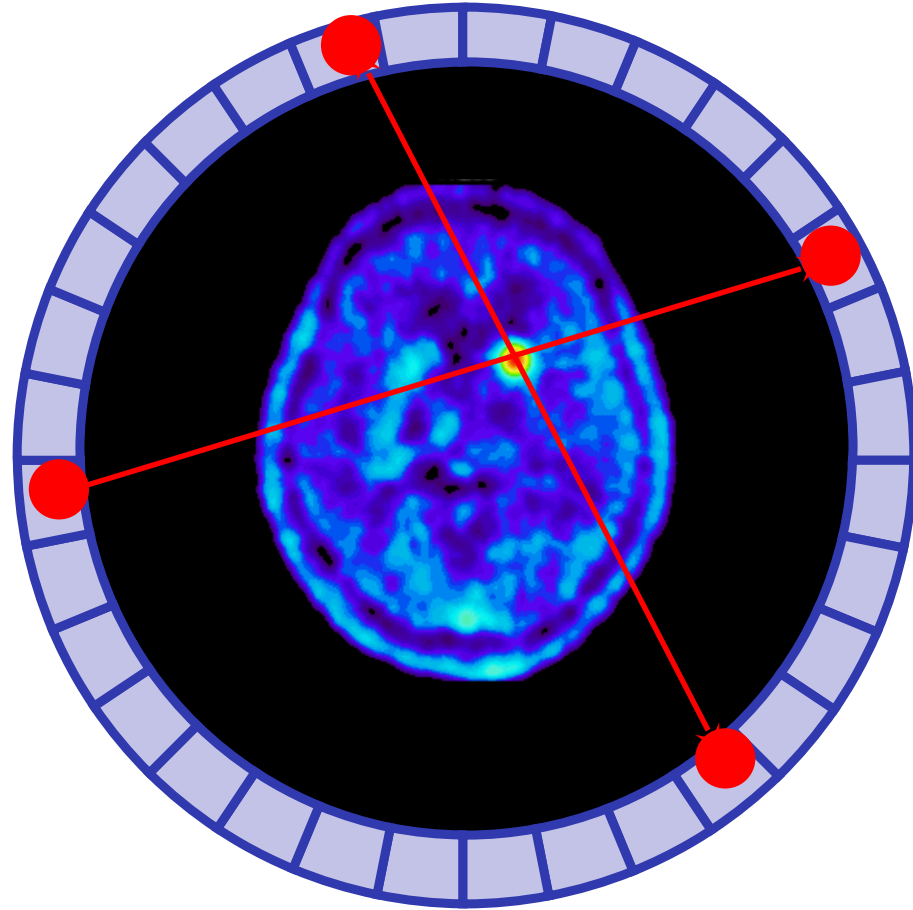


PET



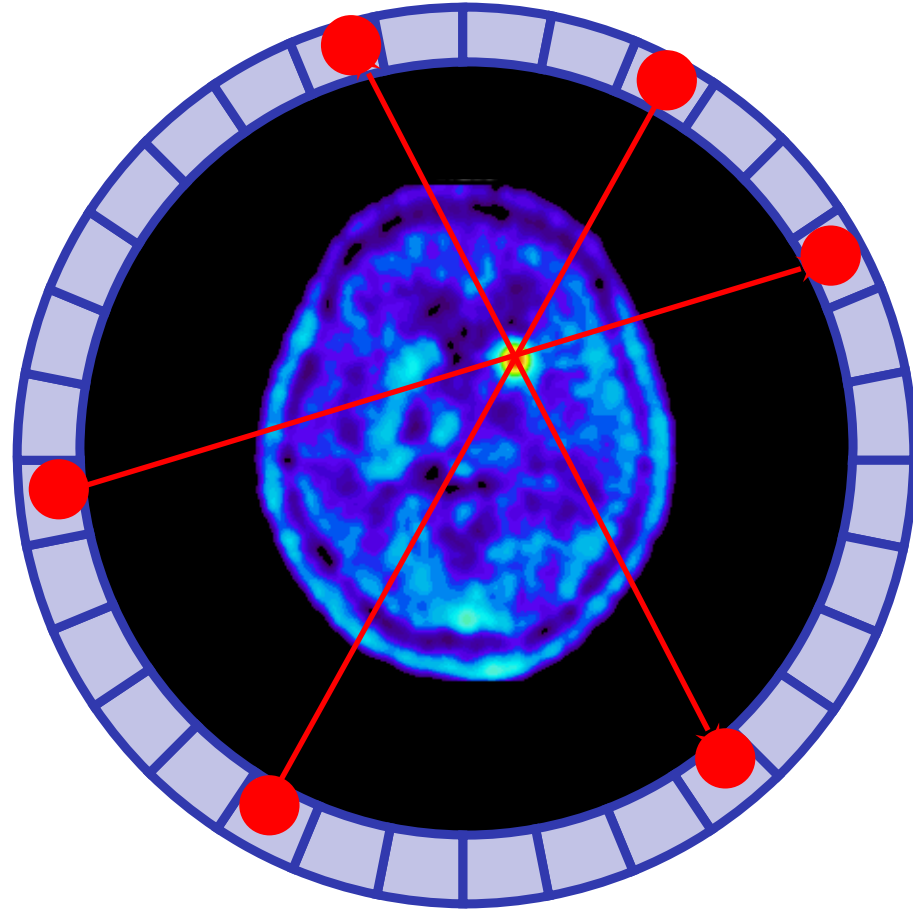


PET



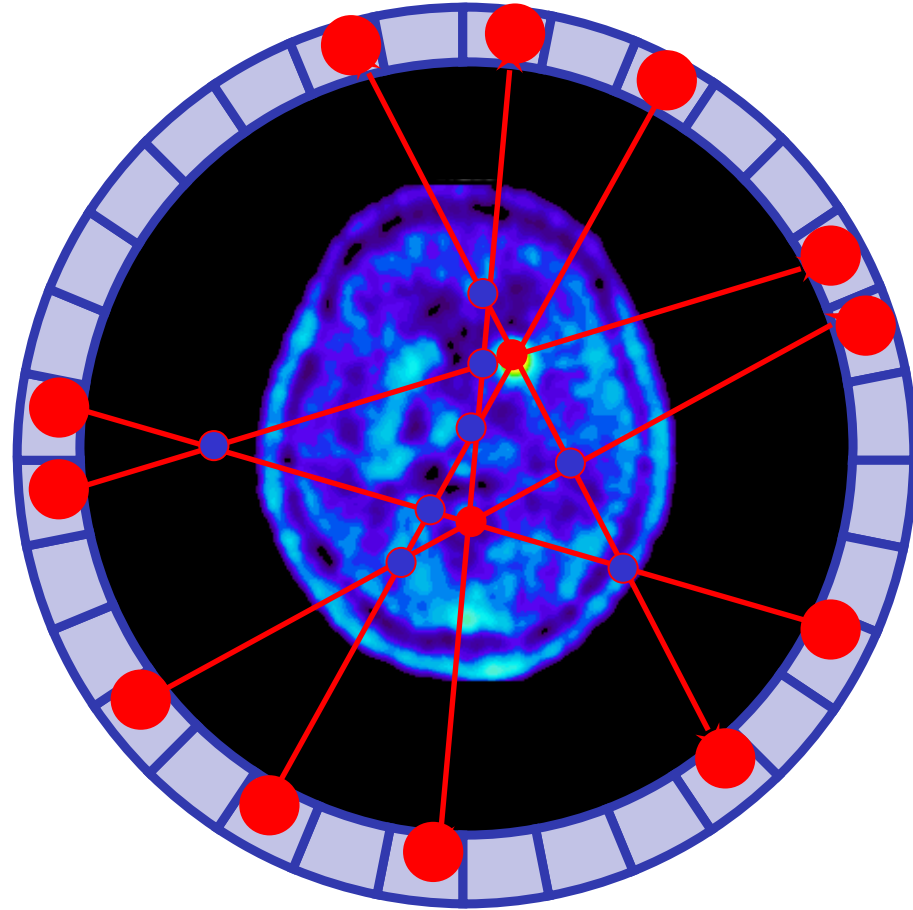


PET

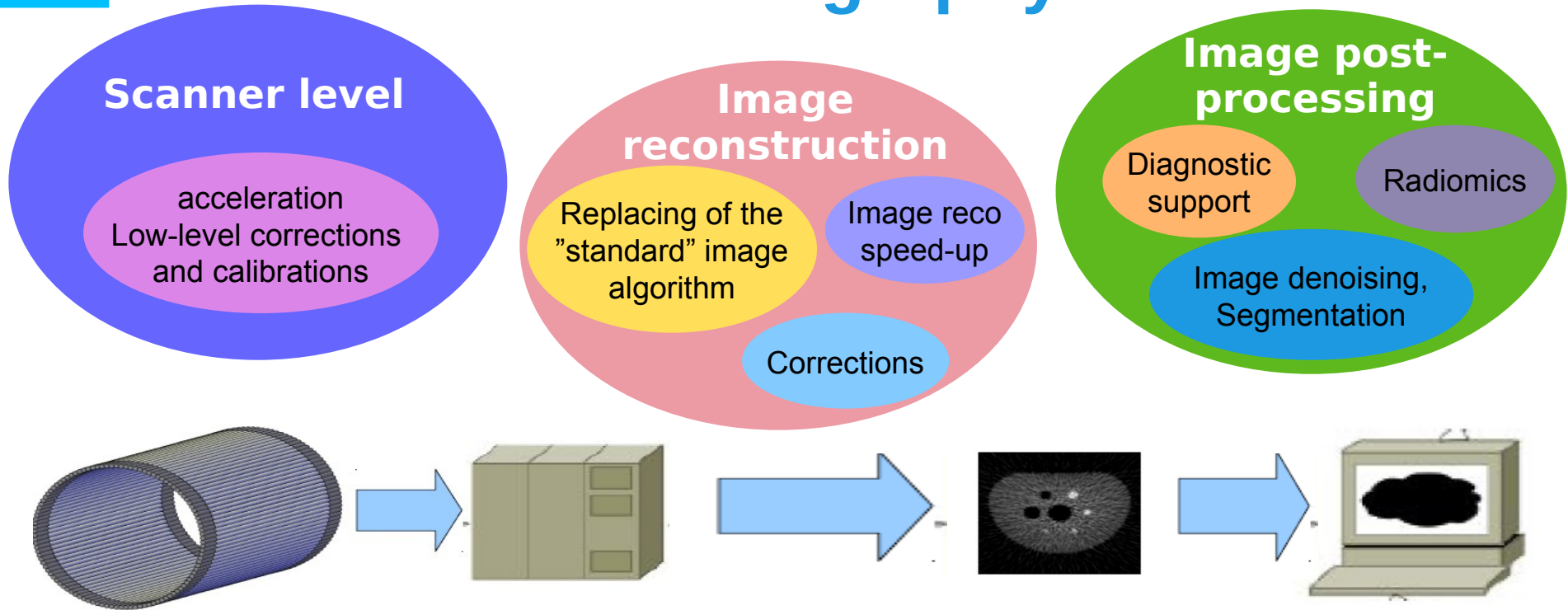




PET



Artificial Intelligence methods in PET tomography



E.g. Using convolutional neural networks to estimate time-of-flight from PET detector waveforms
E. Berg and Simon R. Cherry Phys Med Biol . 2018 Jan 11;63(2):02LT01. doi: 10.1088/1361-6560/aa9dc5.

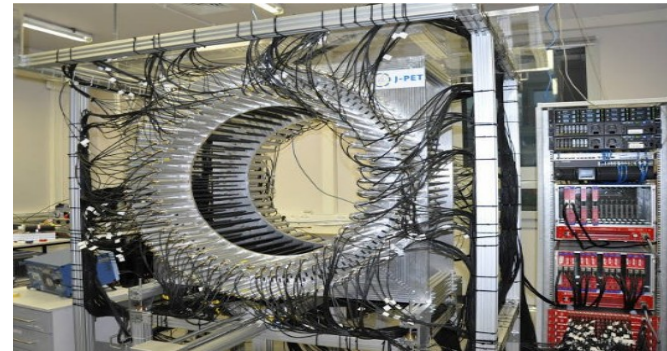
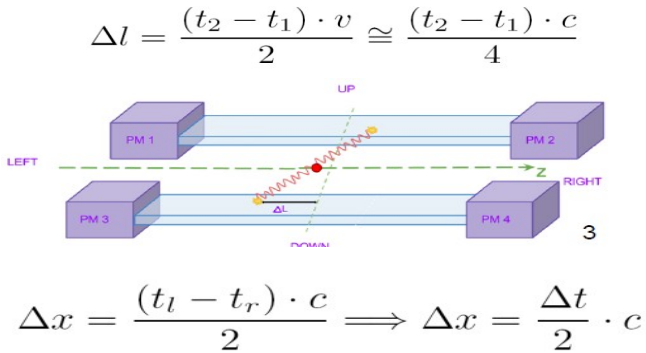
A Review of Deep-Learning-Based Approaches for Attenuation Correction in Positron Emission Tomography
J,S, Lee IEEE Transactions on Radiation and Plasma Medical Sciences 2020

Many papers about DL application for CT-free PET and image reco using DL

Cost-effective total body solution

First prototype

Acta Phys Pol. B 48 (2017) 1567

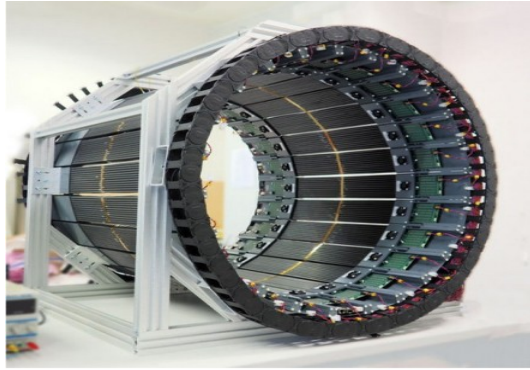


- 50 cm AFOV
- 192 plastic strips
- Readout → vacuum tube photomultipliers



Cost-effective total body solution

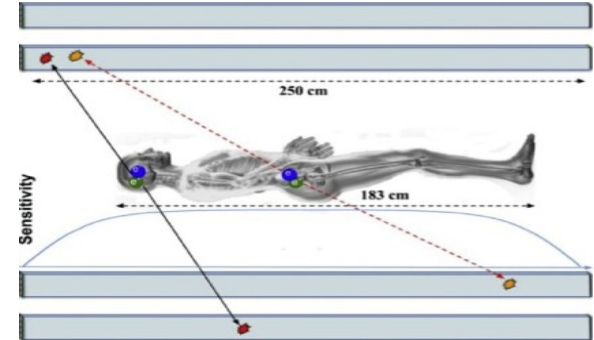
Modular J-PET



- 50 cm AFOV
- 24 modules x 13 strips
- Readout → silicon photomultipliers matrices

Total-body

PET Clinics 15 (2020) 439
 Phys. Med. Biol. 66 (2021) 175015

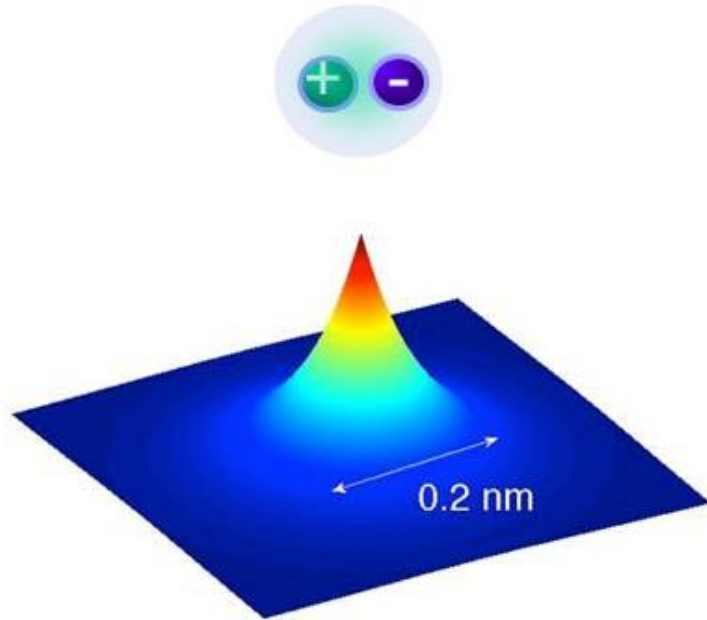


- 250 cm AFOV
- Additional layers of wavelength shifters → better axial resolution

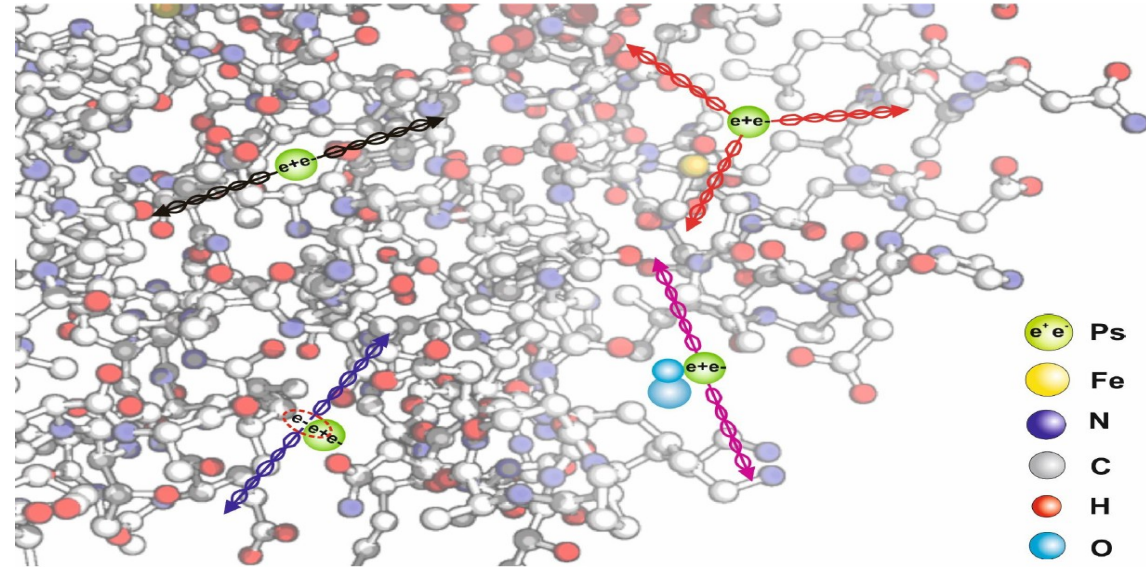


Towards multiphoton/positronium (quantum) tomography

positronium



Model of the hemoglobin molecule



P. Moskal, B. Jasińska, E. Ł. Stępień, S. D. Bass
Nature Reviews Physics 1 (2019) 527-529

P. Moskal et al. Phys. Med. Biol. 64 (2019) 055017

P. Moskal et al. EJNMMI Phys. 7 (2020) 44

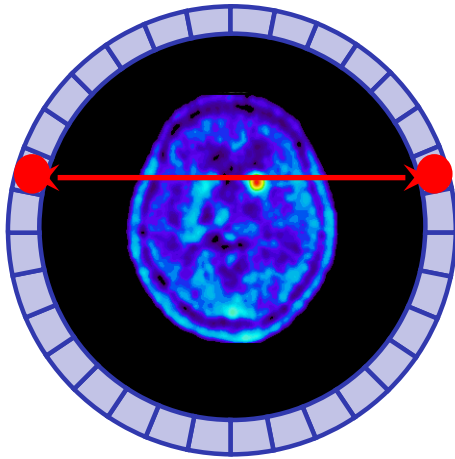
P. Moskal, K. Dulski et al Science Advances 7 (2021) eabh4394

P. Moskal, A. Gajos et al. Nature Communications 12 (2021) 5658

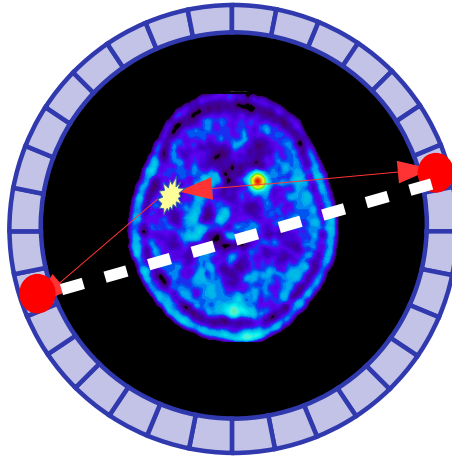


Coincidence classification for total-body J-PET

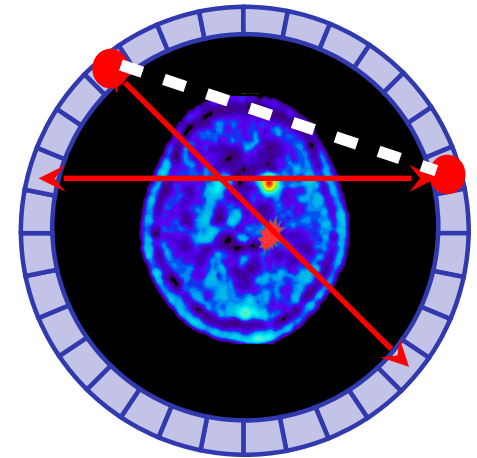
True



Scattered

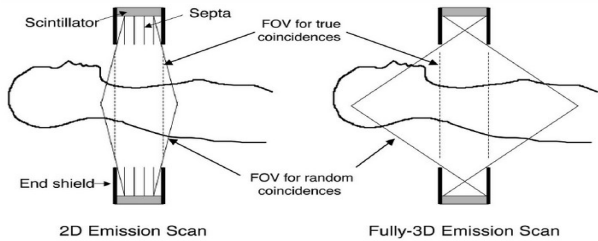


Accidental



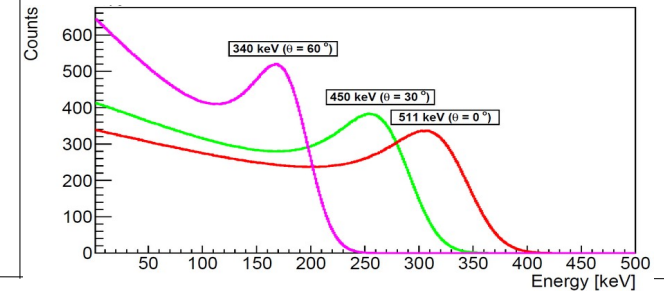
Coincidence classification for total-body J-PET

For total-body J-PET scanner we expect
higher background level from non-genuine coincidences



Multiple scattering in the
phantom is not negligible

In J-PET



D. Brasse et al. J Nucl Med 2005; 46:859–867

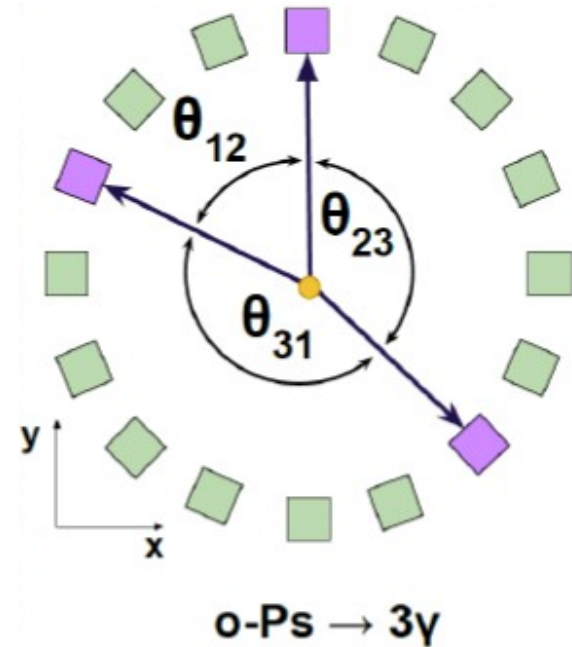


Coincidence classification for total-body J-PET

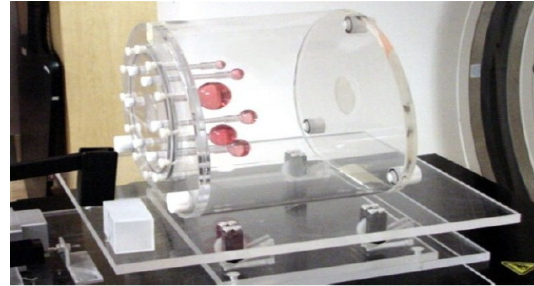
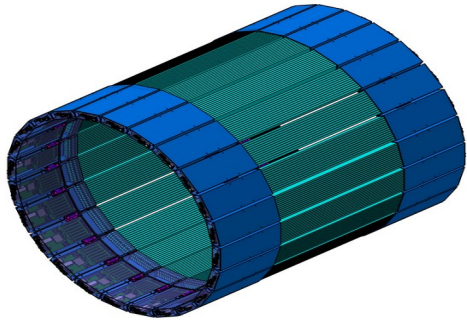
Situation much more complicated for multi-photon coincidences...

- More photons \rightarrow More combinations
- Less strictly defined geometry
- Photon energies have a distribution

Idea: apply ML techniques to reduce background
(ACCIDENTAL, SCATTER)



Training data generation



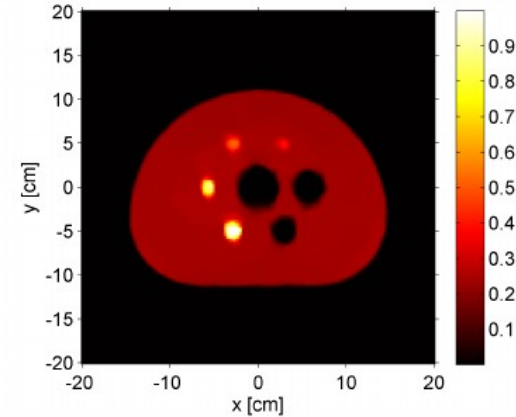
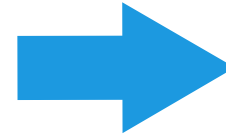
Modular J-PET

- 50 cm AFOV
- 24 modules x 13 strips
- 24 x 6 x 500 mm strips

NEMA IEC Phantom

- 4 hot spheres
- 2 cold spheres
- Activity - 59 Mbq
- acquisition time - 500 seconds
- contrast between hot and cold regions – 4:1

Monte Carlo Simulations



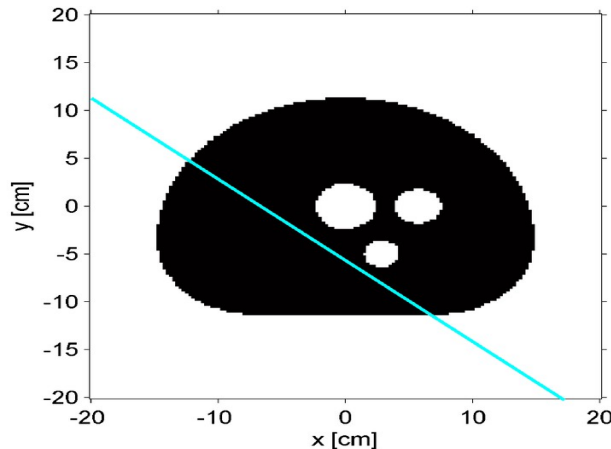
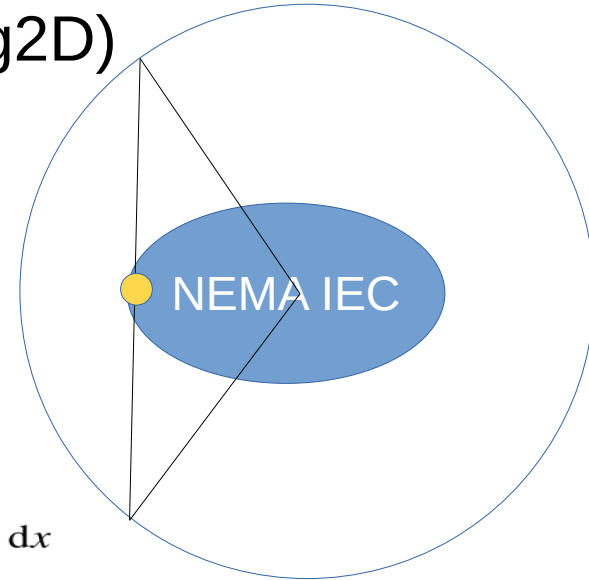
GATE MC Simulation

- 30M coincidences
- Phenomenological time, energy and positional resolution
- Geometry cuts → reduce accidental fraction



Features

- 1) 2D-angle with respect to the geom. center (deg2D)
- 2) time difference (dt)
- 3) LOR length (lorL)
- 4) energy difference $|E_1 - E_2|$ (eDiff)
- 5) energy sum (eSum)
- 6) attenuation coefficients (μ)



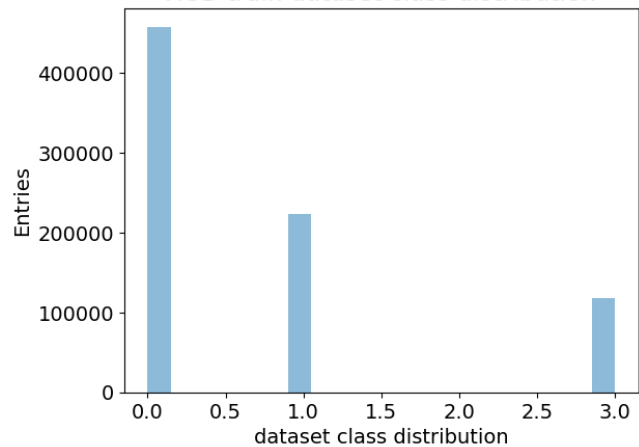
$$a = \int_{-\infty}^{+\infty} \exp(-\mu(x)x) dx$$

$$\begin{aligned} \mu &= 0 \text{ cm}^{-1} && \text{for air} \\ \mu &= 0.096 \text{ cm}^{-1} && \text{for water} \end{aligned}$$

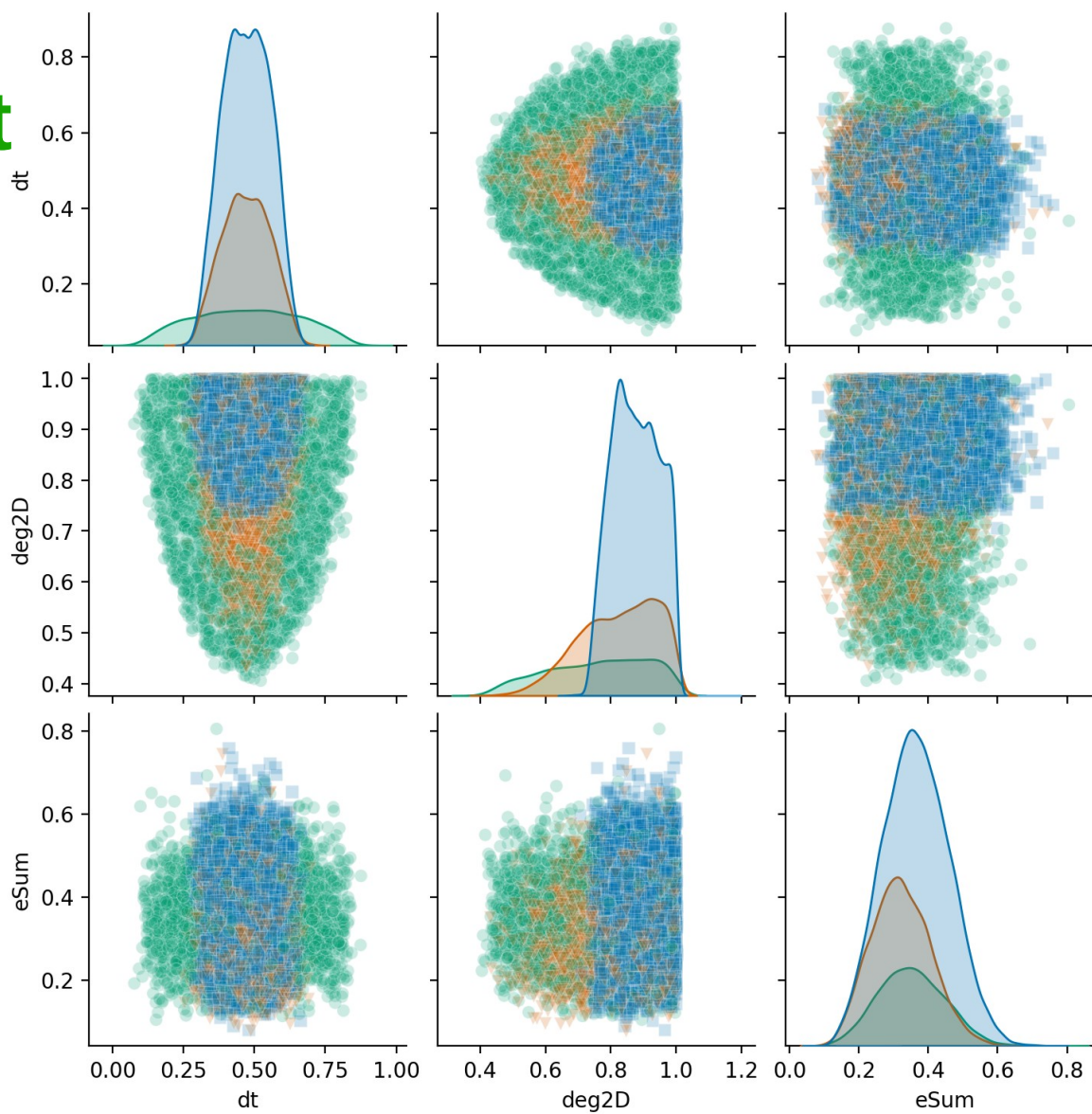


Dataset

XGB-train dataset class distribution





True: 57.3%





Classifiers


- Feedforward Neural Network

 Keras + SciKeras + 

- ADABOOST

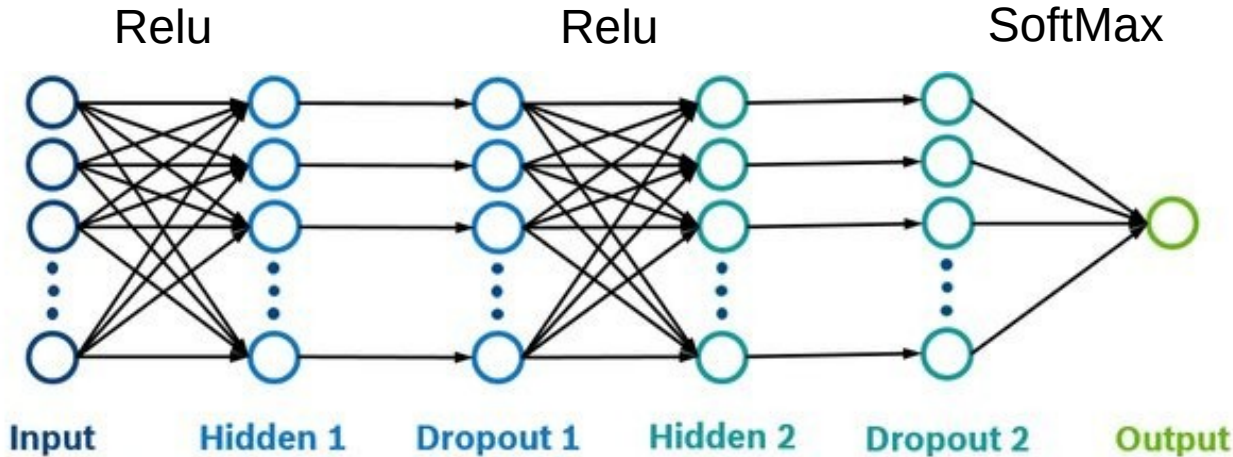


- XGBoost

 + 



Feedforward Neural Network

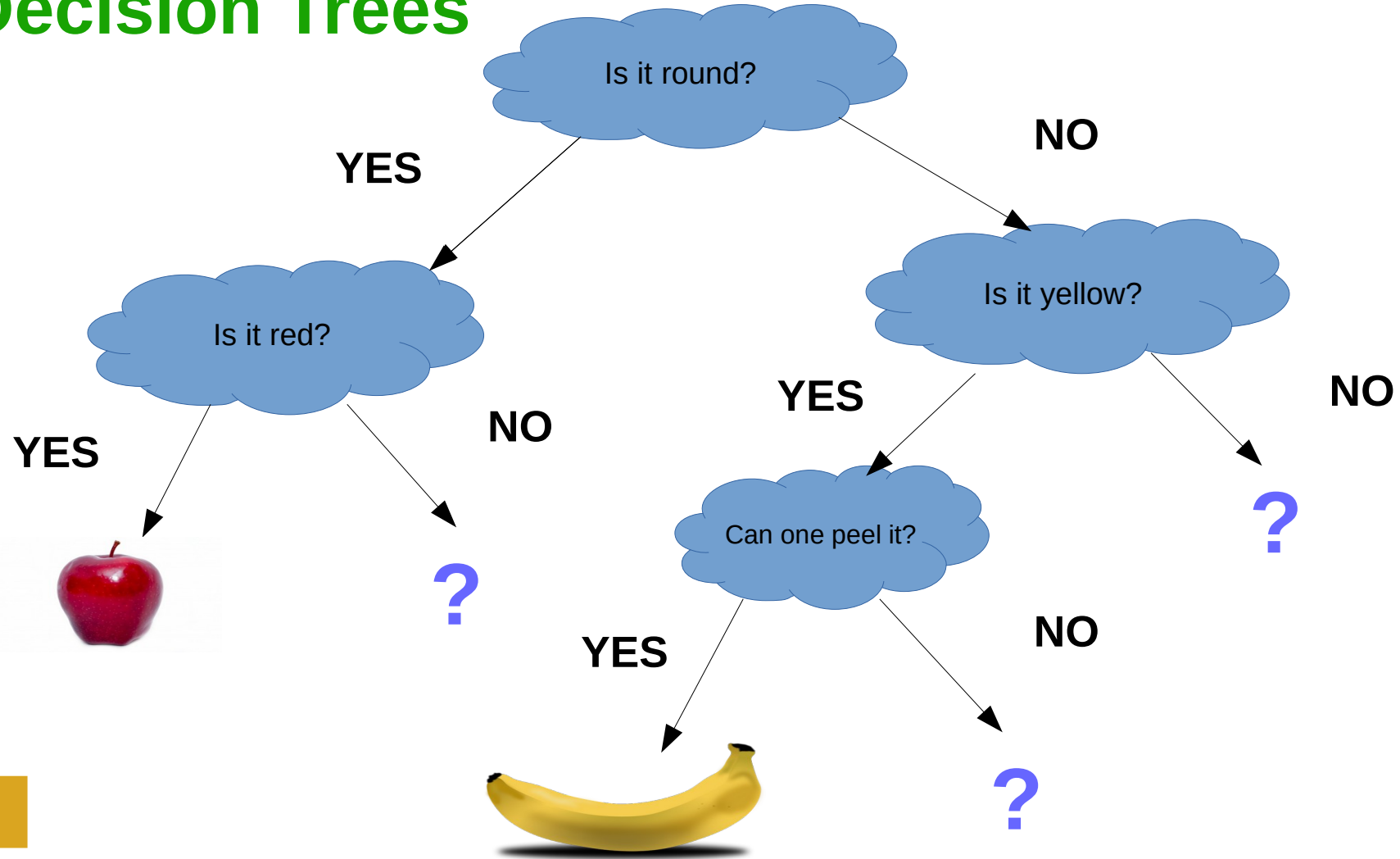


- Optimizer: Adam
- Loss: Categorical Cross Entropy
- Size and number of hidden layers optimized using Cross Validation
- Input data normalized to (0, 1) range

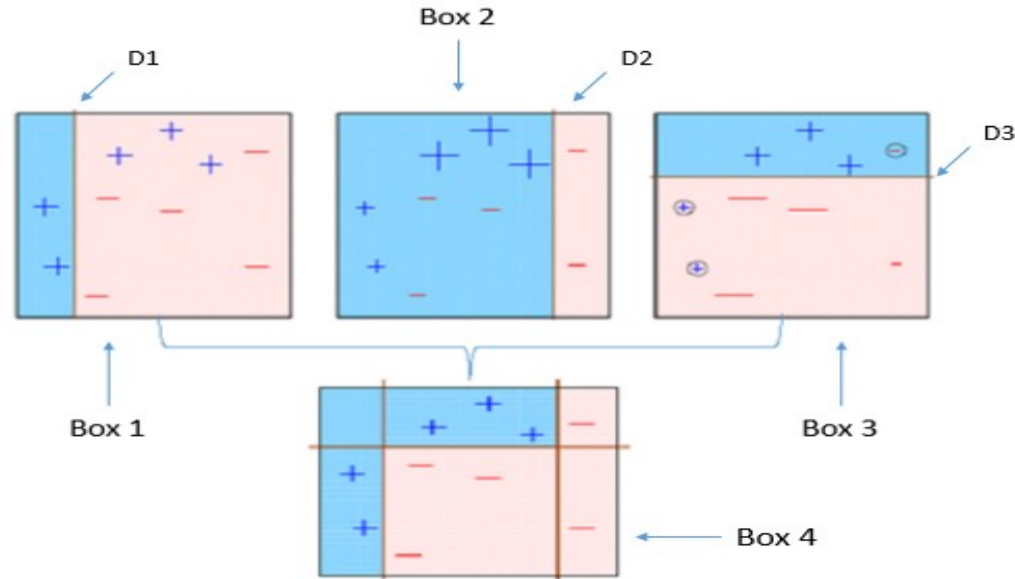


Figure from: Benjamin Volz et.al „A data-driven approach for pedestrian intention estimation”

Decision Trees



Boosting - AdaBoost



$$F_M(\vec{x}) = F_{M-1}(\vec{x}) + \lambda f_M(\vec{x})$$



$$\frac{\partial L[y_i, F(\vec{x}_i)]}{\partial F(\vec{x}_i)} \left\{ \begin{array}{l} F(\vec{x}_i) = F_{M-1}(\vec{x}_i) \end{array} \right.$$

Gradient descent over functional space



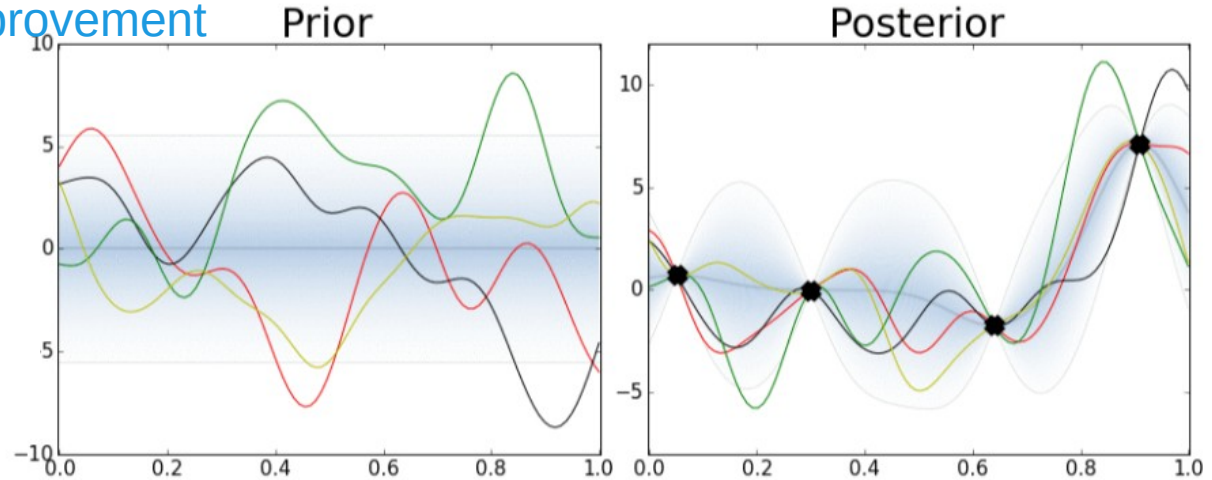
Bayesian optimization + cross validation

f – model accuracy on test sample

- 1) Choose some **prior measure** over the space of possible objectives f
- 2) Combine prior and the likelihood to get a **posterior measure** given some observations
- 3) From posterior decide where to take the next evaluation according to **acquisition function**

- surrogate probability model – **Gaussian process**
- acquisition function – **Expected Improvement**
- f evaluation – best model from **3-fold cross validation**

$$\alpha_{EI}(\mathbf{x}; \theta, \mathcal{D}) = \int_y \max(0, y_{best} - y) p(y|\mathbf{x}; \theta, \mathcal{D}) dy$$



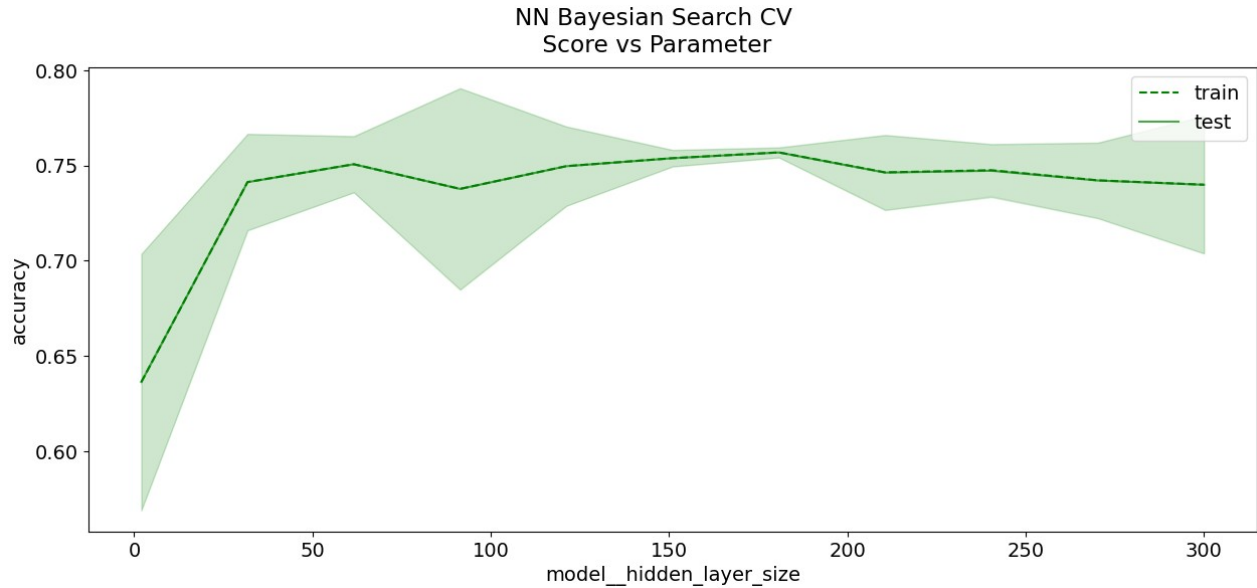
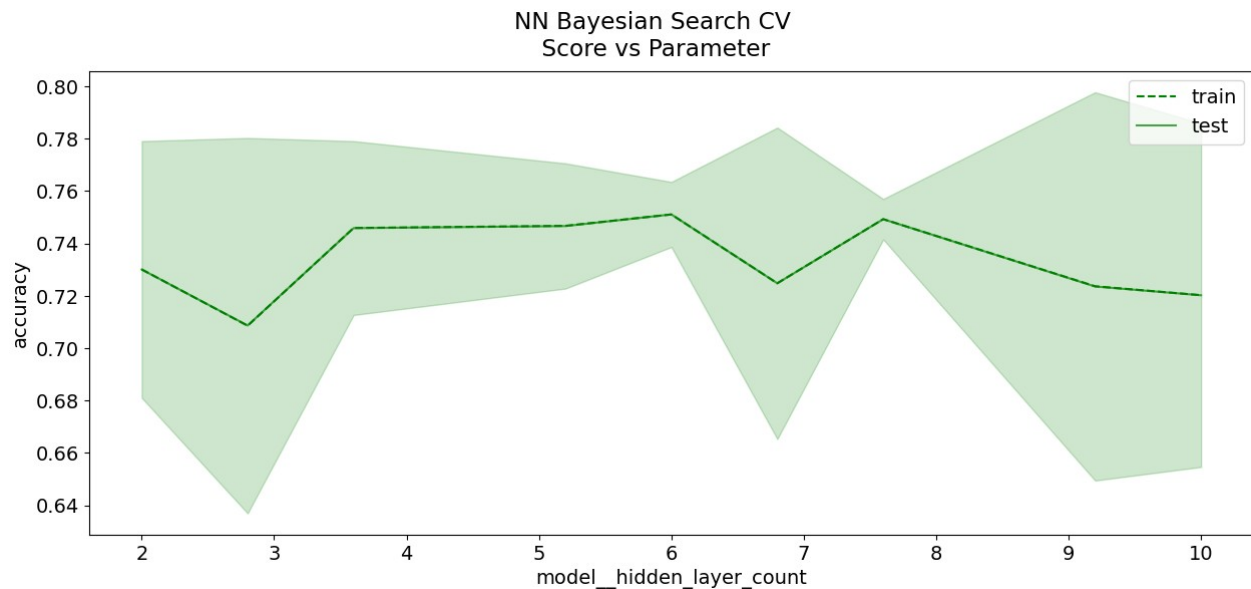
Figures from: Javier Gonzalez, „Introduction to Bayesian Optimization”



NN CV

Best model:

- batch size: 32
- dropout: 0.13
- hidden layers: 2
- layer size: 180
- learning rate: 0.001

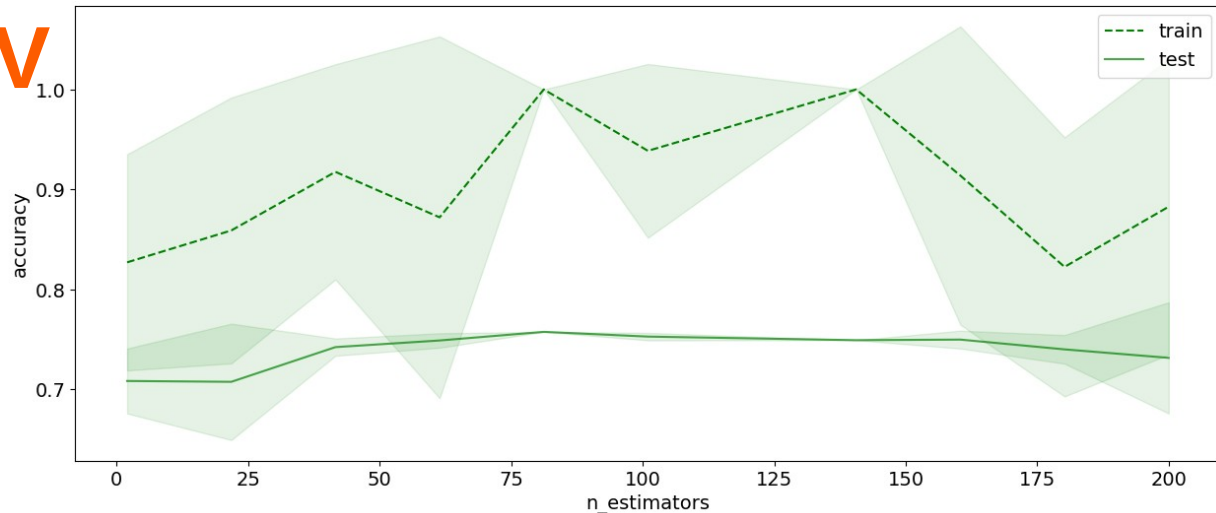


ADABOOST CV

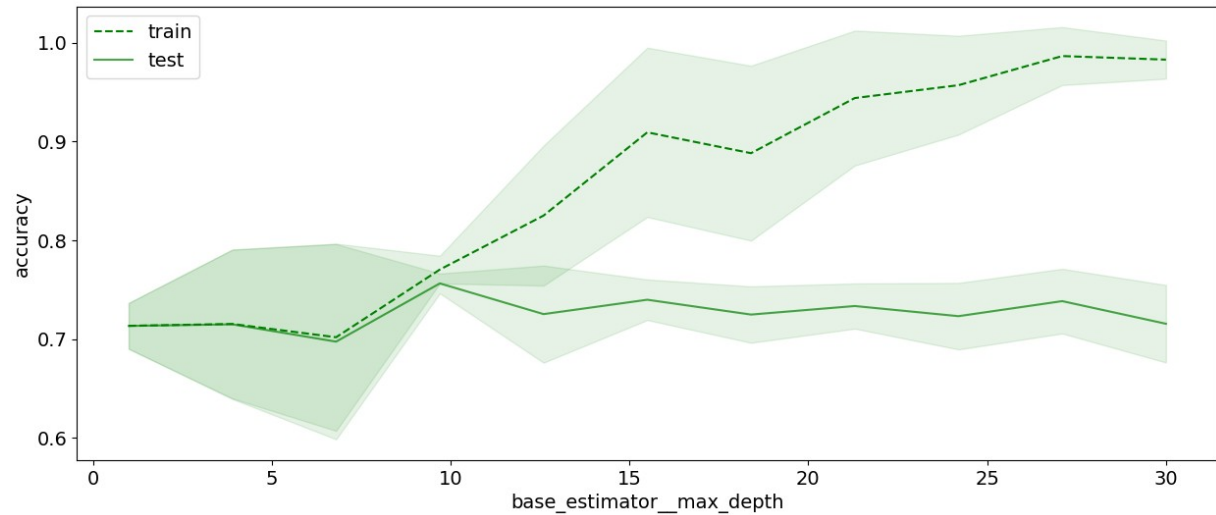
Best model:

- max_depth: 8
- learning_rate: 0.022
- n_estimators: 20

ADA Bayesian Search CV
Score vs Parameter



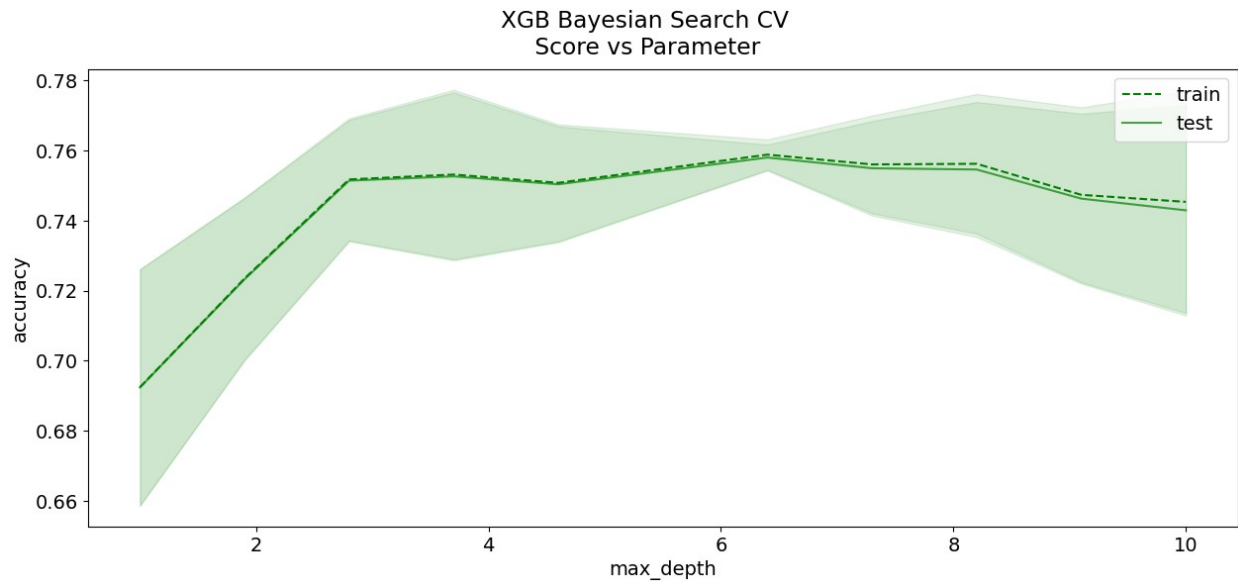
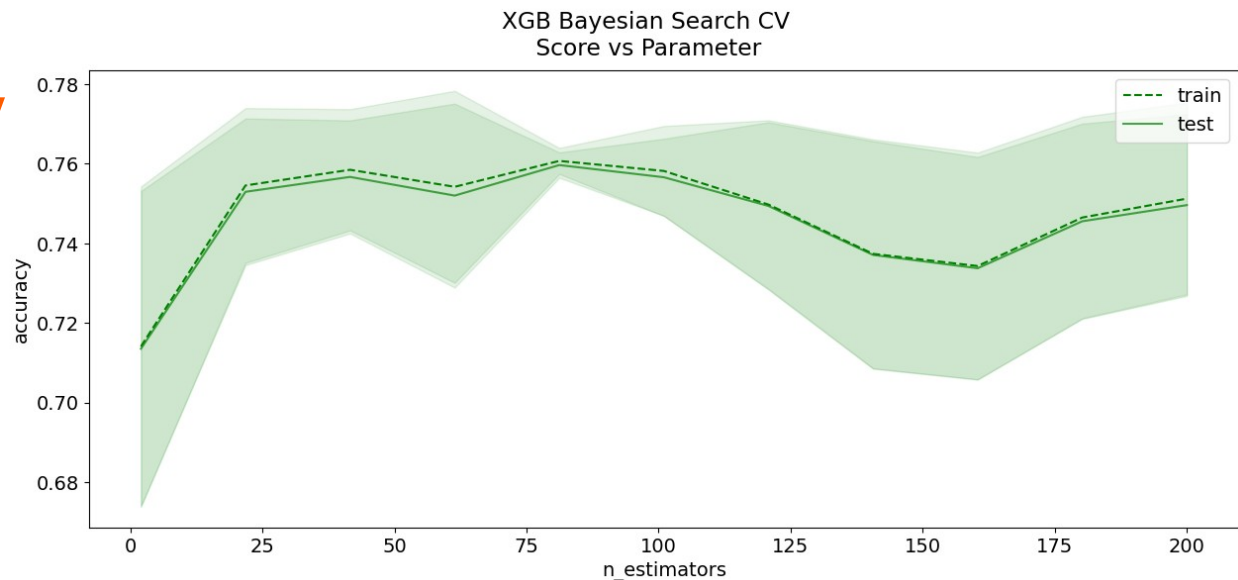
ADA Bayesian Search CV
Score vs Parameter



XGBoost CV

Best model:

- colsample_bytree: 0.96
- gamma: 0.12
- learning_rate: 0.1
- max_depth: 10
- min_child_weight: 5
- estimators: 200
- reg_alpha: 6.23
- reg_lambda: 4.15
- subsample: 0.97

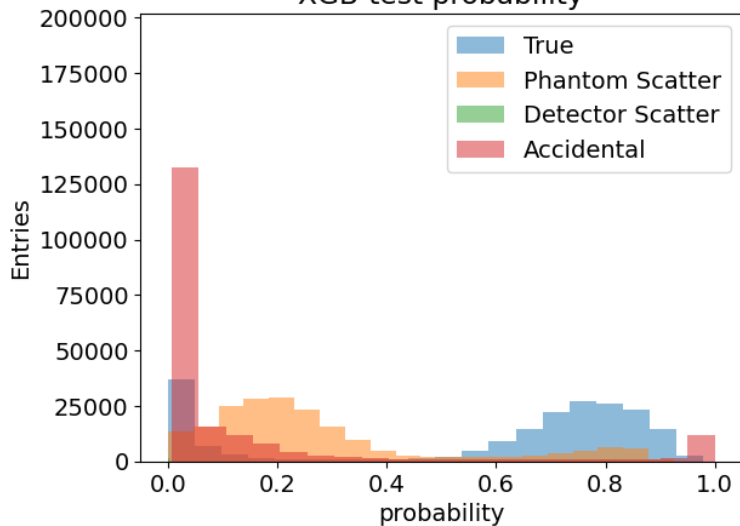




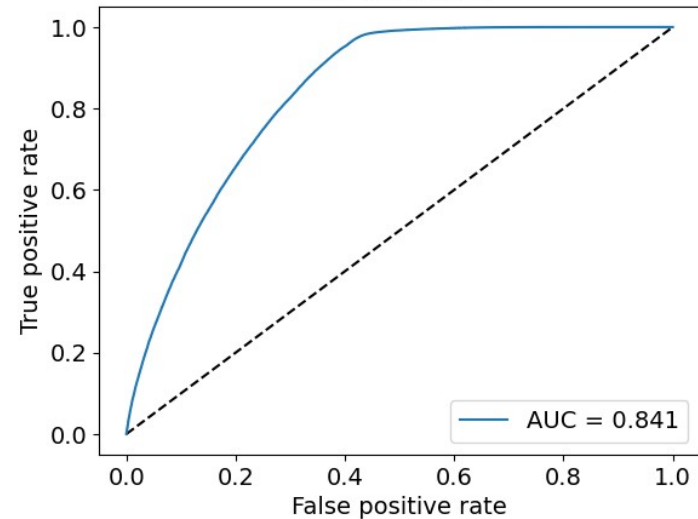
NN



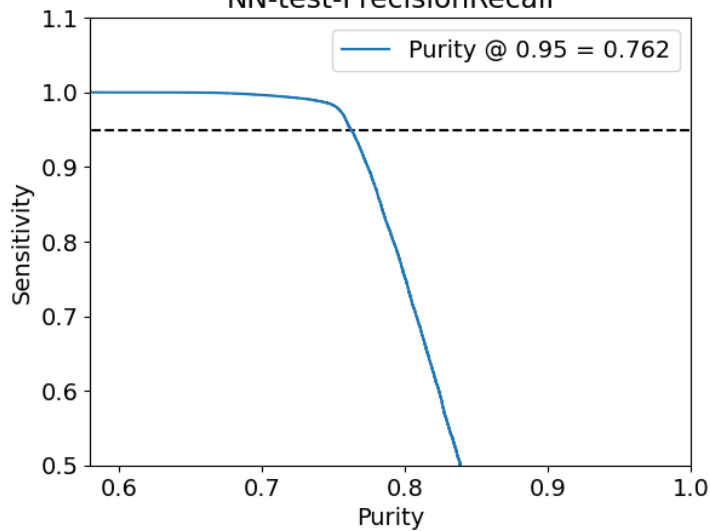
XGB-test probability



NN-test-ROC

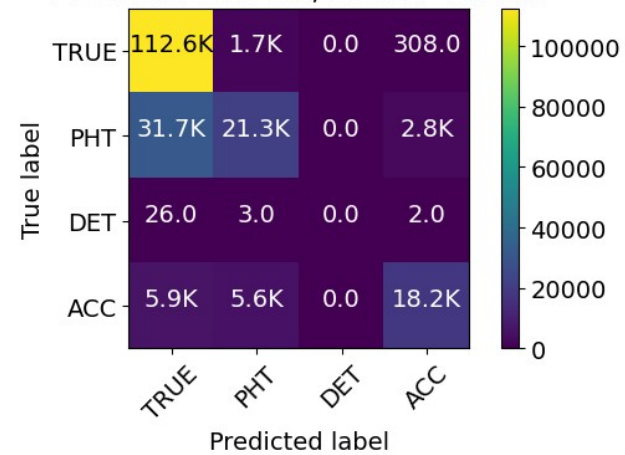


NN-test-PrecisionRecall



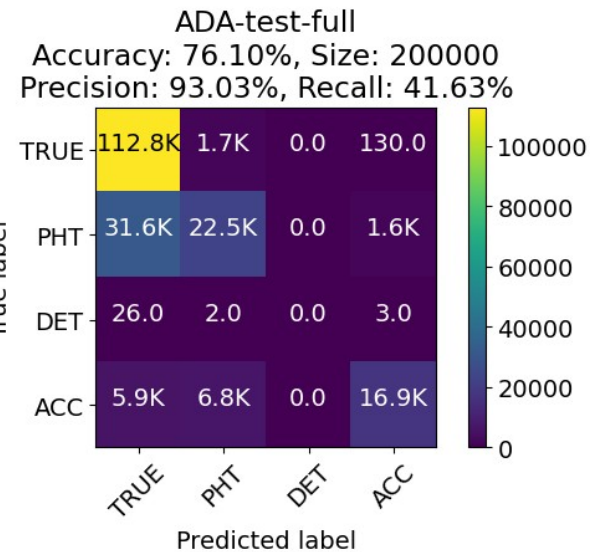
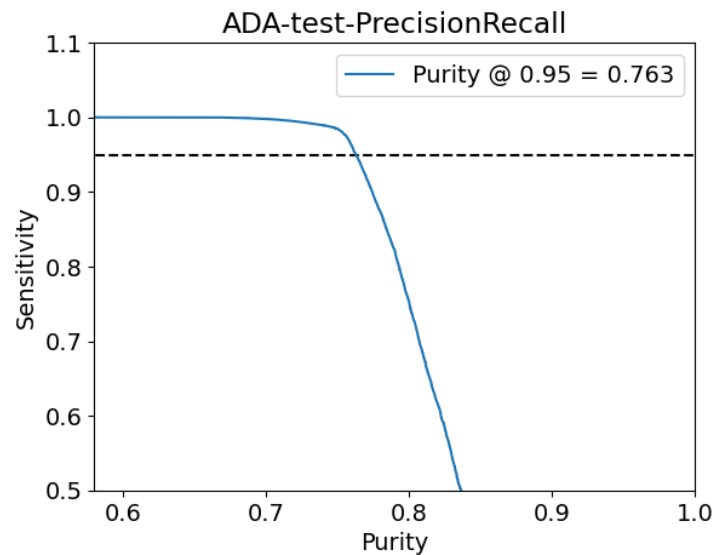
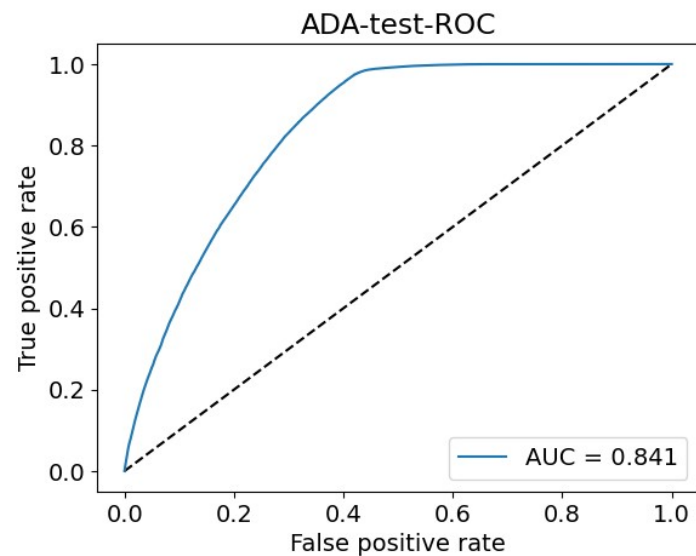
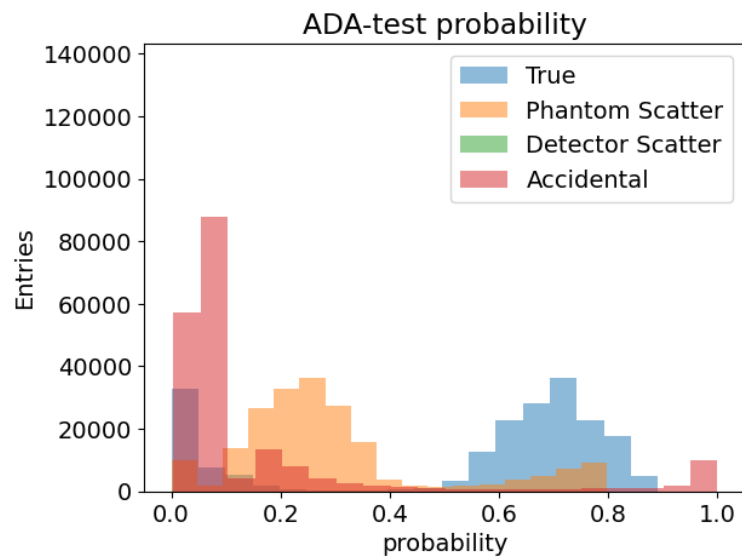
NN-test-full

Accuracy: 76.04%, Size: 200000
Precision: 92.76%, Recall: 40.21%



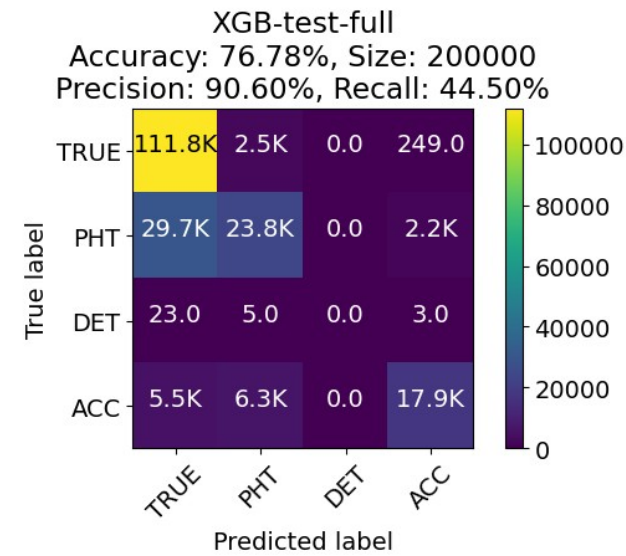
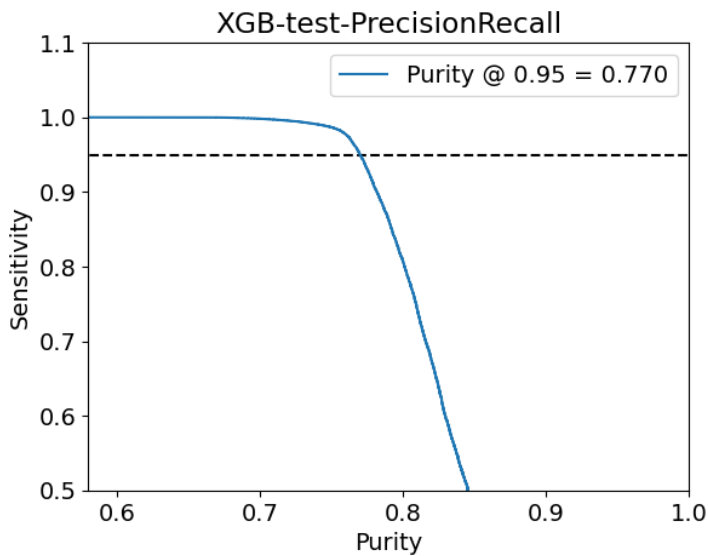
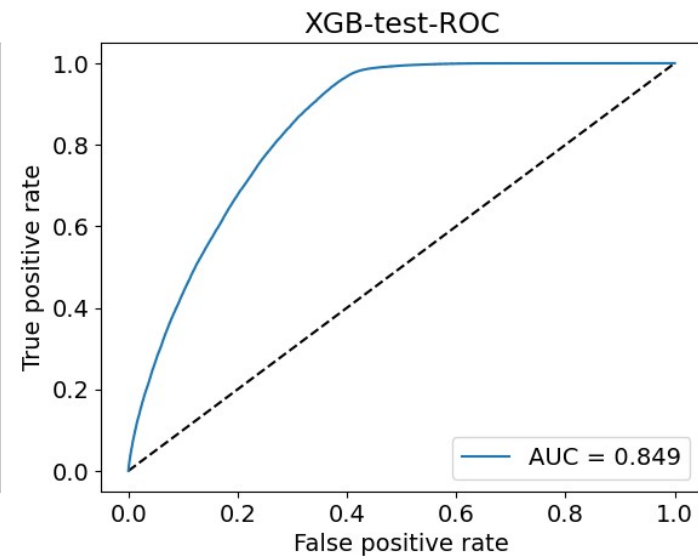
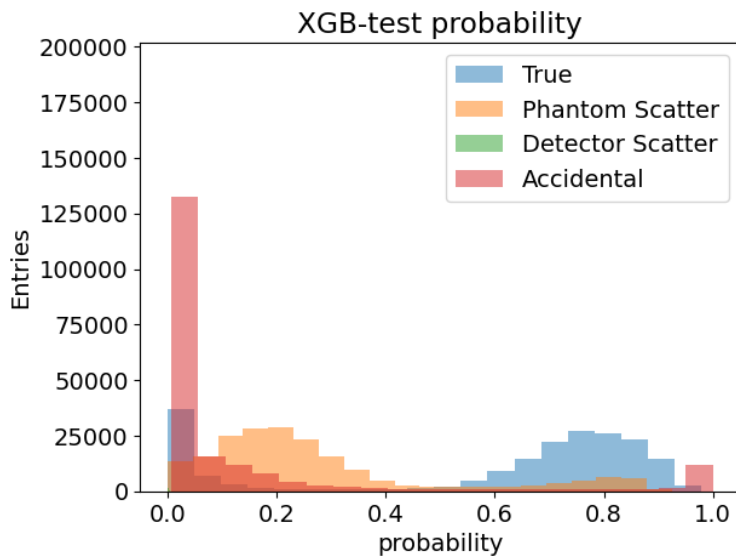


ADABOOST

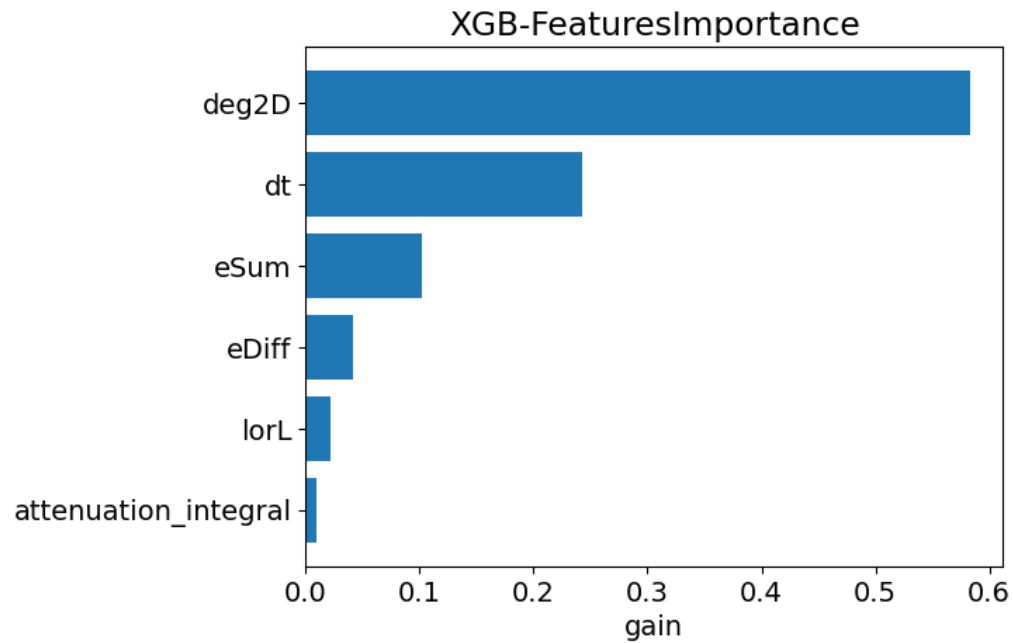
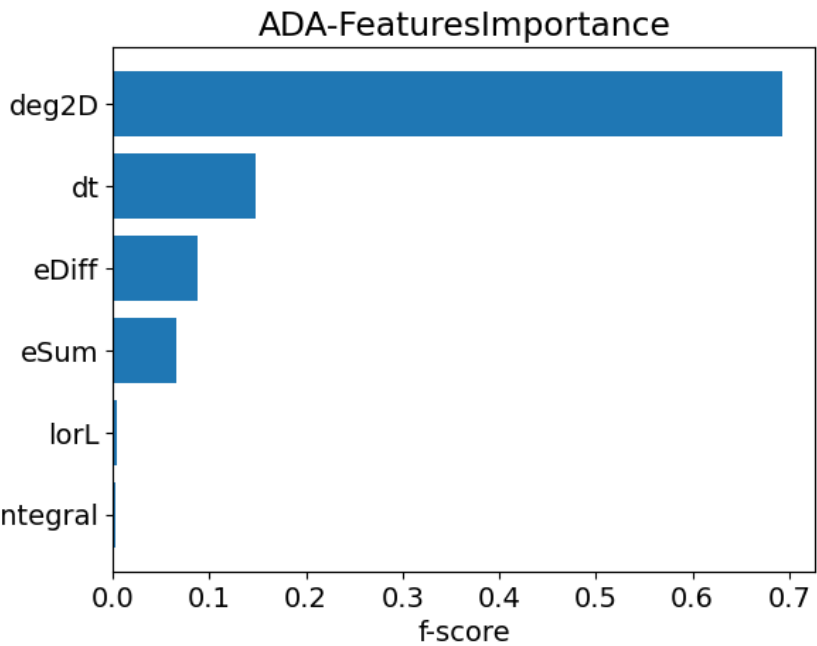


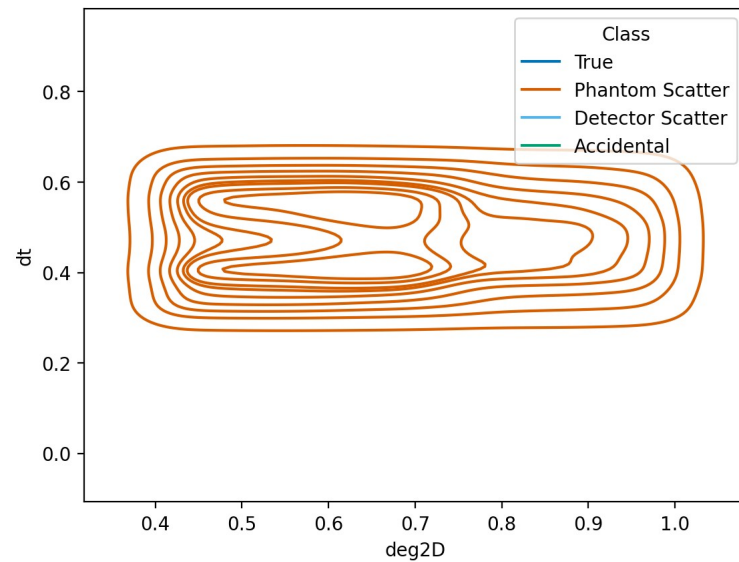
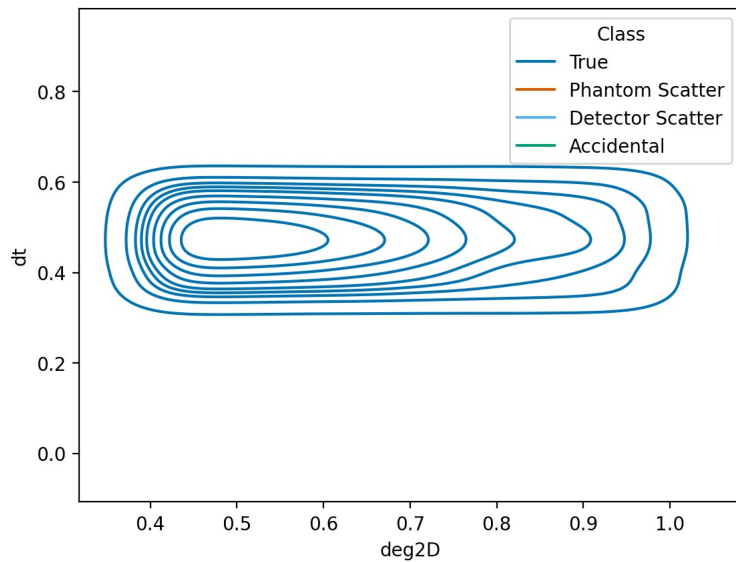


XGBoost



Feature importance





XGBoost

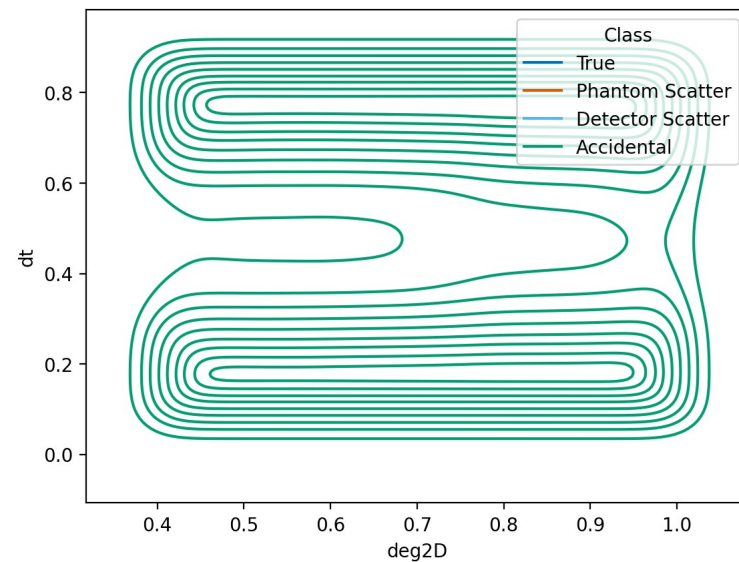
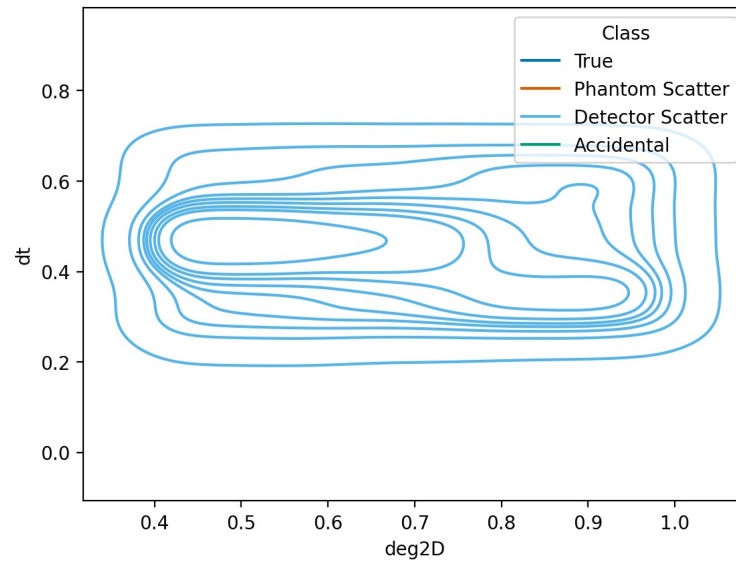
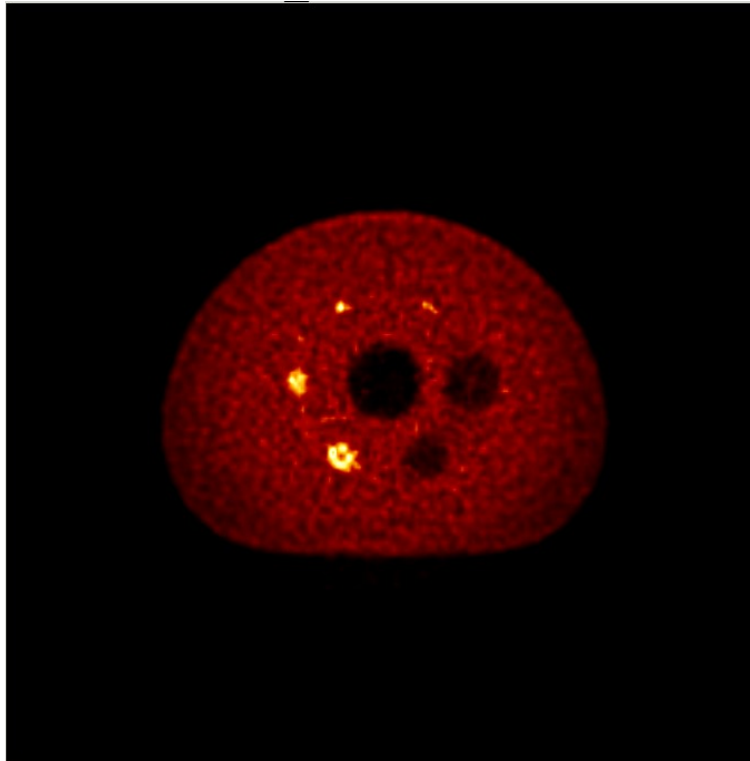
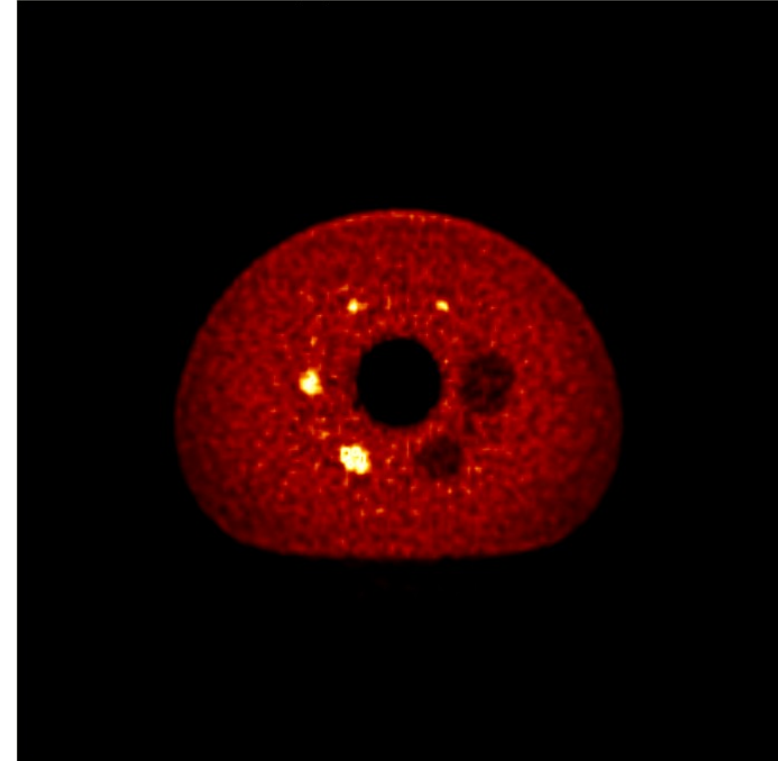


Image reconstruction

Without filtration



XGBoost Filtered



MLEM (CASTOR)

30 iterations





Summary

Method	Precision
Base line	57.3%
NN	76.2%
ADABoost	76.3%
XGBoost	77.0%





Summary

- Verification of ML applicability for PET coincidence classification
- Tested full chain with bayesian optimization
- Comparison of NN, ADABOOST and XGBOOST performance
- Information accessible in the two photon data does not allow for clear class separation.

Further work needed.





Outlook

- Verify the model invariance wrt used phantom
 - test on different phantoms (e.g. X-CAT)
- Apply the method to multiphoton data
 - harder classification problem
 - however larger feature space
- Validation with real data

